

## Differential Equations I for Students of Engineering Sciences

### Sheet 7, Exercise class

To shorten the notation we employ the Doetsch symbol:

$$F(s) := \mathcal{L}f(s) := \int_0^\infty e^{-st} f(t) dt \iff f(t) \circ\bullet F(s)$$

The following correspondences or relations for  $\operatorname{Re}(s) > \gamma$ , which were either proved in the lecture or could be proved completely analogously to the lectures procedure, may be used. We always have  $f(t) = 0, \forall t < 0$ .

$f(t), t \geq 0$	$F$	$\gamma$
1 i.e. $h_0(t)$	$\frac{1}{s}$	0
$h_a(t)$	$e^{-as} \frac{1}{s}$	0
$t^n, n \in \mathbb{N}$	$\frac{n!}{s^{n+1}}$	0
$e^{at}, a \in \mathbb{C}$	$\frac{1}{s-a}$	$\operatorname{Re}(a)$
$e^{at} \sin(\omega t), \omega \in \mathbb{R}$	$\frac{\omega}{(s-a)^2 + \omega^2}$	0
$e^{at} \cos(\omega t), \omega \in \mathbb{R}$	$\frac{s-a}{(s-a)^2 + \omega^2}$	0

$h_a(t)$  for  $a \geq 0$  is defined as follows:  $h_a(t) := \begin{cases} 1 & t \geq a \geq 0, \\ 0 & t < a. \end{cases}$

If  $f(t) \circ\bullet F(s)$ , then the following shifting theorems hold.

- |     |  |  |
|-----|--|--|
| I)  | $h_a(t)f(t-a) \circ\bullet e^{-sa}F(s)$                | Shifting in the original space<br>Multiplication with exponential function in the image space        |
| II) | $e^{at}f(t) \circ\bullet F(s-a)$<br>$a \in \mathbb{C}$ | Shifting in<br>the image space/<br>Multiplication with<br>exponential function in the original space |

**Exercise 1:**

- a) Which is the algebraic equation resulting from Laplace transformation of the initial value problem

$$u'' - 2u' + u = \sin(4t) + 2te^{-t}, \text{ for } t > 0, \quad u(0) = 1, u'(0) = 0?$$

Please justify your answer by intermediate computations.

Compute the solution of the algebraic equation.

- b) Let  $F(s) = \frac{1}{s(s+1)^2}$  be the Laplace transform of the function

$$f: \mathbb{R}_0^+ \rightarrow \mathbb{R}, \quad f: t \mapsto f(t).$$

Determine  $f(t)$ .

**Exercise 2:**

- a) For the following matrices  $\mathbf{A}$  analyse the stability of the stationary point  $(0,0)^T$  of the linear system  $\mathbf{u}'(t) = \mathbf{A} \mathbf{u}(t)$ .

i)  $A = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$ ,      ii)  $A = \begin{pmatrix} -1 & 0 \\ -1 & -1 \end{pmatrix}$ ,      iii)  $A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$ .

- b) Consider the following linear system

$$\dot{\mathbf{u}}(t) = \begin{pmatrix} -3 & 0 & 3 \\ -1 & -\gamma & 1 \\ 3 & 0 & -3 \end{pmatrix} \mathbf{u}(t).$$

Determine the stability behaviour of the stationary point  $(0,0,0)^T$  depending on the parameter  $\gamma \in \mathbb{R}$ .

**Dates of classes:** 22.01.-26.01.2024