

Analysis III for Engineering Students Work sheet 3

Exercise 1: Given a function

$$f : \mathbb{R}^2 \rightarrow \mathbb{R}, \quad f(x, y) := x \cdot y^2 + \cos(x + y) + 2y + 3.$$

- a) Compute the second degree Taylor polynomial T_2 of f at $(x_0, y_0) = (0, 0)$.
- b) Show that for the remainder $R_2(x, y) = f(x, y) - T_2(x, y)$ in the area $|x| \leq 0.2, |y| \leq 0.2$ the following estimate holds:

$$|f(x, y) - T_2(x, y)| \leq \frac{4}{100}.$$

- c) What is the third-degree Taylor polynomial T_3 of f at $(x_0, y_0) = (0, 0)$?
Show that for all $(x, y) \in \mathbb{R}^2, |x| \leq 0.2$ and $|y| \leq 0.2$

$$|f(x, y) - T_3(x, y)| \leq \frac{2}{1000}.$$

holds.

Solution:

a)

$$\begin{array}{ll} f(x, y) = x \cdot y^2 + \cos(x + y) + 2y + 3 & f(0, 0) = 4 \\ f_x(x, y) = y^2 - \sin(x + y) & f_x(0, 0) = 0 \\ f_y(x, y) = 2xy - \sin(x + y) + 2 & f_y(0, 0) = 2 \\ f_{xx}(x, y) = -\cos(x + y) & f_{xx}(0, 0) = -1 \\ f_{xy}(x, y) = 2y - \cos(x + y) & f_{xy}(0, 0) = -1 \\ f_{yy}(x, y) = 2x - \cos(x + y) & f_{yy}(0, 0) = -1 \end{array}$$

$$T_2(x, y) = 4 + 2y - \frac{x^2}{2} - xy - \frac{y^2}{2}.$$

- b) To prove the error estimate, we calculate an upper bound for the magnitudes of all third derivatives for all $|x| \leq 0.2$ and $|y| \leq 0.2$

$$\begin{array}{l} |f_{xxx}(x, y)| = |\sin(x + y)| \leq 1 \\ |f_{xxy}(x, y)| = |\sin(x + y)| \leq 1 \\ |f_{xyy}(x, y)| = |2 + \sin(x + y)| \leq 2 + 1 = 3 \\ |f_{yyy}(x, y)| = |\sin(x + y)| \leq 1. \end{array}$$

The magnitudes of all third derivatives of f are therefore bounded by $C := 3$.

Hence, we have

$$|f(x, y) - T_2(x, y)| \leq \frac{2^3}{3!} \cdot \|(x, y)\|_\infty^3 \cdot C \leq \frac{8}{6} \cdot \frac{2^3}{10^3} \cdot 3 = \frac{8 \cdot 2^2}{1000} = \frac{32}{1000} < \frac{4}{100}.$$

c) Using the third derivatives from part b) we get

$$f_{xxx}(0, 0) = f_{xxy}(0, 0) = f_{yyy}(0, 0) = 0, \quad f_{xyy}(0, 0) = 2.$$

Hence

$$T_3(x, y) = T_2(x, y) + \frac{1}{3!} \cdot 3f_{xyy}(0, 0)xy^2 = 4 + 2y - \frac{x^2}{2} - xy - \frac{y^2}{2} + xy^2.$$

All fourth derivatives are given by $\cos(x + y)$, so that with $\tilde{C} = 1$ it follows:

$$|f(x, y) - T_3(x, y)| \leq \frac{2^4}{4!} \cdot \|(x, y)\|_\infty^4 \cdot \tilde{C} \leq \frac{2}{3} \cdot \frac{2^4}{10^4} = \frac{32}{30000} < \frac{33}{30 \cdot 1000} = \frac{1.1}{1000} < \frac{2}{1000}.$$

Exercise 2:

- a) Describe the following subsets of $\mathbb{R}^2$ and $\mathbb{R}^3$ in words and describe them using polar, cylindrical or spherical coordinates.

$$M_1 := \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 : x^2 + y^2 \leq 4 \right\},$$

$$M_2 := \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 : x^2 + y^2 \leq 4, y \geq 0 \right\},$$

$$M_3 := \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 : x^2 + y^2 \leq 4, x \geq 0 \right\},$$

$$M_4 := \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x^2 + y^2 \leq 4, 0 \leq z \leq 5 \right\},$$

$$M_5 := \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x^2 + y^2 + z^2 \leq 4 \right\},$$

$$M_6 := \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x^2 + y^2 + z^2 \leq 4, y \geq 0 \right\},$$

$$M_7 := \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x^2 + y^2 + z^2 \leq 4, z \geq 0 \right\}.$$

- b) Describe the boundaries of the sets from a) using polar, cylindrical or spherical coordinates.

Solution 2:

- a)

$$M_1 := \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 : x = r \cos(\phi), y = r \sin(\phi); r \in [0, 2], \phi \in [0, 2\pi) \right\},$$

circular disk, radius 2, center 0,

$$M_2 := \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 : x = r \cos(\phi), y = r \sin(\phi); r \in [0, 2], \phi \in [0, \pi) \right\},$$

upper half of the circular disk M_1 ,

$$M_3 := \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 : x = r \cos(\phi), y = r \sin(\phi); r \in [0, 2], \phi \in \left[-\frac{\pi}{2}, \frac{\pi}{2}\right] \right\},$$

right half of the circular disk M_1 ,

$$M_4 := \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x = r \cos(\phi), y = r \sin(\phi); r \in [0, 2], \phi \in [0, 2\pi), z \in [0, 5] \right\},$$

right circular Cylinder with radius 2, axis of rotation = z-axis,

base on the x-y plane and height 5,

$$M_5 := \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x = r \cos(\phi) \cos(\theta), y = r \sin(\phi) \cos(\theta), z = r \sin(\theta), \right.$$

$$\left. r \in [0, 2], \phi \in [0, 2\pi), \theta \in \left[-\frac{\pi}{2}, \frac{\pi}{2}\right] \right\},$$

$$M_6 := \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x = r \cos(\phi) \cos(\theta), y = r \sin(\phi) \cos(\theta), z = r \sin(\theta), \right.$$

sphere with radius 2 around zero,

$$\left. r \in [0, 2], \phi \in [0, \pi), \theta \in \left[-\frac{\pi}{2}, \frac{\pi}{2}\right] \right\},$$

(rear) half of the sphere with radius 2 around zero with $y \geq 0$,

$$M_7 := \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x = r \cos(\phi) \cos(\theta), y = r \sin(\phi) \cos(\theta), z = r \sin(\theta), \right.$$

$$\left. r \in [0, 2], \phi \in [0, 2\pi), \theta \in \left[0, \frac{\pi}{2}\right] \right\},$$

upper half of the sphere with radius 2 around zero

b)

$$\partial M_1 = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 : x = 2 \cos(\phi), y = 2 \sin(\phi); \phi \in [0, 2\pi) \right\},$$

$$\partial M_2 = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 : x = 2 \cos(\phi), y = 2 \sin(\phi); \phi \in [0, \pi) \right\} \cup \left\{ \begin{pmatrix} x \\ 0 \end{pmatrix} \in \mathbb{R}^2 : x \in [-2, 2] \right\}$$

$$\partial M_3 = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 : x = 2 \cos(\phi), y = 2 \sin(\phi); \phi \in [-\frac{\pi}{2}, \frac{\pi}{2}] \right\} \cup \left\{ \begin{pmatrix} 0 \\ y \end{pmatrix} \in \mathbb{R}^2 : y \in [-2, 2] \right\}$$

$$\begin{aligned} \partial M_4 = & \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x = 2 \cos(\phi), y = 2 \sin(\phi); \phi \in [0, 2\pi), z \in [0, 5] \right\} \\ & \cup \left\{ (x, y, 0)^T \in \mathbb{R}^3 : x = r \cos(\phi), y = r \sin(\phi); r \in [0, 2], \phi \in [0, 2\pi) \right\} \\ & \cup \left\{ (x, y, 5)^T \in \mathbb{R}^3 : x = r \cos(\phi), y = r \sin(\phi); r \in [0, 2], \phi \in [0, 2\pi) \right\}. \end{aligned}$$

$$\begin{aligned} \partial M_5 = & \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x = 2 \cos(\phi) \cos(\theta), y = 2 \sin(\phi) \cos(\theta), z = 2 \sin(\theta), \right. \\ & \left. \phi \in [0, 2\pi), \theta \in [-\frac{\pi}{2}, \frac{\pi}{2}] \right\}, \end{aligned}$$

$$\begin{aligned} \partial M_6 = & \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x = 2 \cos(\phi) \cos(\theta), y = 2 \sin(\phi) \cos(\theta), z = 2 \sin(\theta), \phi \in [0, \pi), \theta \in [-\frac{\pi}{2}, \frac{\pi}{2}] \right\} \\ & \cup \left\{ \begin{pmatrix} x \\ 0 \\ z \end{pmatrix} \in \mathbb{R}^3 : x = r \cos(\theta), z = r \sin(\theta), r \in [0, 2], \theta \in [0, 2\pi] \right\}, \end{aligned}$$

$$\begin{aligned} \partial M_7 = & \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x = 2 \cos(\phi) \cos(\theta), y = 2 \sin(\phi) \cos(\theta), z = 2 \sin(\theta), \phi \in [0, 2\pi), \theta \in [0, \frac{\pi}{2}] \right\} \\ & \cup \left\{ \begin{pmatrix} x \\ y \\ 0 \end{pmatrix} \in \mathbb{R}^3 : x = r \cos(\phi), y = r \sin(\phi), r \in [0, 2], \phi \in [0, 2\pi] \right\}. \end{aligned}$$

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