Analysis III: Auditorium Exercise-04 For Engineering Students

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The goal is to find the extremal values of a C^1 function

 $f: D \subset \mathbb{R}^n \to \mathbb{R}$

on the following subset of the domain:

$$G := \{ \mathbf{x} \in D \mid \boldsymbol{g}(\mathbf{x}) = \mathbf{0} \} \subset D,$$

with a C^1 function

$$\boldsymbol{g}: D \to \mathbb{R}^m$$

and m < n, i.e., the extremal values must additionally satisfy the m equations

$$\boldsymbol{g}(\mathbf{x}) = (g_1(\mathbf{x}), \dots, g_m(\mathbf{x}))^T = \mathbf{0}$$



<u>Theorem: (Lag</u>range Multiplier Rule)

Let $\mathbf{x}^0 \in D$ be a local extremum of the function f under the constraint $g(\mathbf{x}^0) = \mathbf{0}$, satisfying the regularity condition

Rank
$$\mathbf{J}\boldsymbol{g}(\mathbf{x}^0) = m$$

Then there exist **Lagrange multipliers** $\lambda_1, \ldots, \lambda_m$, such that the **Lagrange function**

$$F(\mathbf{x}) := f(\mathbf{x}) + \sum_{i=1}^{m} \lambda_i g_i(\mathbf{x})$$

satisfies the necessary first-order condition:

grad
$$F(\mathbf{x}^0) = \text{grad } f(\mathbf{x}^0) + \sum_{i=1}^m \lambda_i \text{grad } g_i(\mathbf{x}^0) = \mathbf{0}.$$



A) Compact Admissible Set and Continuous fIf the admissible set is compact and f is continuous then Min/Max are attained.

Candidate with the highest function value = global maximum. Candidate with the smallest function value = global minimum. B) Second-Order Conditions (in the case of two constraints) Let x_0 be admissible (i.e., $g(x_0) = h(x_0) = 0$), the regularity condition is satisfied at x_0 , and assume:

$$\exists \lambda, \mu \text{ with } \nabla F(x_0) = 0.$$

Define the Tangent Space:

$$T_G(x_0) = \{ w : \langle w, \nabla g(x_0) \rangle = 0 \text{ and } \langle w, \nabla h(x_0) \rangle = 0 \}.$$



Necessary for a Local Minimum:

$$w^T H_F(x_0) w \ge 0, \quad \forall w \in T_G(x_0) \setminus \{0\}.$$

Sufficient for a Local Minimum:

$$w^T H_F(x_0) w > 0, \quad \forall w \in T_G(x_0) \setminus \{0\}.$$

Necessary for a Local Maximum:

$$w^T H_F(x_0) w \le 0, \quad \forall w \in T_G(x_0) \setminus \{0\}.$$

Sufficient for a Local Maximum:

$$w^T H_F(x_0) w < 0, \quad \forall w \in T_G(x_0) \setminus \{0\}.$$



This means, in particular, that the necessary conditions for minima (maxima) in the unconstrained case (i.e., positive (negative) semi-definite Hessian matrix) are no longer strictly necessary here. For example:

The Hessian matrix $H_F(x_0)$ can have negative eigenvalues at a minimum, as long as the corresponding eigenvectors do not represent admissible directions (i.e., directions that lead out of the admissible set).





Compute the extremal values of the function

$$f:\mathbb{R}^2\to\mathbb{R}\,,\quad f(x,y)=x+y$$

on the circle $x^2 + y^2 = 1$.

a) Under the constraint

$$g(x, y) := x^2 + y^2 - 1 = 0$$

determine the extremal points of the function

$$f(x,y) = x + y$$

using the Lagrange multiplier rule.





Regularity condition:

grad
$$g(x, y) = (2x, 2y) = (0, 0) \Rightarrow (x, y) = (0, 0),$$

i.e., only (0,0) violates the regularity condition.

Since g(0,0) = -1, (0,0) is not on the circle.

All feasible points, i.e., those with g(x, y) = 0, satisfy the regularity condition

 $\operatorname{Rank}(\mathbf{J}g(x,y))=1.$





Lagrangian:
$$F(x, y) = x + y + \lambda(x^2 + y^2 - 1)$$

Lagrange Multiplier Rule:

$$\begin{pmatrix} \nabla F(x,y) \\ g(x,y) \end{pmatrix} = \begin{pmatrix} 1+2\lambda x \\ 1+2\lambda y \\ x^2+y^2-1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Multiplying the first equation by y and the second by x and subtracting both, we get

$$x - y = 0 \quad \Rightarrow \quad x = y.$$





From the third equation, we then obtain $x^2 + x^2 = 1$

$$\Rightarrow \quad x_{1,2} = \pm \frac{1}{\sqrt{2}}, \quad y_{1,2} = \pm \frac{1}{\sqrt{2}}.$$

Extremal candidates:

$$P_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1\\1 \end{pmatrix}$$
, $P_2 = -\frac{1}{\sqrt{2}} \begin{pmatrix} 1\\1 \end{pmatrix}$.





Example: 01.(a)

Since the set g(x, y) = 0 describes a circle, it is compact.

Thus, the continuous function f attains a maximum and minimum on g(x, y) = 0.

We have $f(P_1) = \sqrt{2}$ and $f(P_2) = -\sqrt{2}$.

So, P_1 is a maximum and P_2 is a minimum.







Image: Constraint $g(x, y) = x^2 + y^2 - 1 = 0$ with level curves of the function f(x, y) = x + y





b) Parametrization of the circle

$$g(x,y) := x^2 + y^2 - 1 = 0$$

by c and then solving the extremal problem for h(t) := f(c(t)).





The circle is parametrized by polar coordinates

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \cos t \\ \sin t \end{pmatrix} =: c(t) , \quad 0 \le t < 2\pi,$$

i.e., $g(\cos t, \sin t) = 0$.

Now, we just need to find the extrema of the function

$$h(t) := f(c(t)) = \cos t + \sin t$$

$$h'(t) = -\sin t + \cos t = 0 \quad \Rightarrow \quad \tan t = 1$$

 $\Rightarrow \quad t_1 = \frac{\pi}{4} , \quad t_2 = \frac{5\pi}{4}$





$$h''(t) = -\cos t - \sin t$$

$$\Rightarrow h''(t_1) = -\sqrt{2} < 0, h''(t_2) = \sqrt{2}$$

Thus,

 $t_1 = \pi/4$ is a maximum with $h(t_1) = \sqrt{2}$ and $t_1 = 5 - (4 \text{ is a maximum with } h(t_1))$

 $t_2 = 5\pi/4$ is a minimum with $h(t_2) = -\sqrt{2}$.







Figure: c(t) and $f(c(t)) = \cos t + \sin t$





For the function

$$f(x, y, z) = z^2$$

compute and classify the extrema on the intersection of the cylinder $x^2 + y^2 = 9$ with the plane y = z using the Lagrange multipliers rule.

Regularization condition:

$$Jg(x,y,z) = \begin{pmatrix} 2x & 2y & 0\\ 0 & 1 & -1 \end{pmatrix}$$

has rank < 2, when the first row is equal to the zero vector,



i.e., for the points (0,0,z).

However, these are not feasible due to

$$g_1(0,0,z) = -9$$

So, all feasible points satisfy the regularization condition, The Lagrange multiplier rule can be applied:

Lagrange function:

$$F(x, y, z) = z^{2} + \lambda_{1}(x^{2} + y^{2} - 9) + \lambda_{2}(y - z)$$





Lagrange multiplier rule:

$$\begin{pmatrix} \nabla F(x,y,z) \\ g(x,y,z) \end{pmatrix} = \begin{pmatrix} 2\lambda_1 x \\ 2\lambda_1 y + \lambda_2 \\ 2z - \lambda_2 \\ x^2 + y^2 - 9 \\ y - z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

- 1. Equation: 1. Case: x = 0 $\Rightarrow 0 = g_1(0, y, z) = y^2 - 9$
- $\Rightarrow \quad y = 3 = z \quad \lor \quad y = -3 = z$





Extreme candidates:
$$P_1 = \begin{pmatrix} 0\\ 3\\ 3 \end{pmatrix}, P_2 = \begin{pmatrix} 0\\ -3\\ -3 \end{pmatrix}$$

2. Case:
$$\lambda_1 = 0$$

 $\Rightarrow \quad \lambda_2 = 0 \quad \Rightarrow \quad z = 0 = y \quad \Rightarrow \quad x = 3 \lor x = -3$
Extreme candidates: $P_3 = \begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix}, P_4 = \begin{pmatrix} -3 \\ 0 \\ 0 \end{pmatrix}$



The intersection of the cylinder $x^2 + y^2 = 9$ with the plane y = z is an ellipse and therefore compact.

The continuous function f attains its absolute maximum and minimum there.

Among the extreme candidates are the absolute maximum and minimum.

The function values of the extreme candidates are

$$f(P_{1,2}) = 9$$
, $f(P_{3,4}) = 0$.

So, $P_{1,2}$ are absolute maxima, and $P_{3,4}$ are absolute minima.



Example: 02



Figure: f on the intersection of the cylinder $x^2 + y^2 = 9$ with the plane y = z





Determine the global extrema of the function:

$$f(x, y, z) = x - 8y + z$$

on the intersection of the two spherical surfaces:

$$g(x, y, z) = x^{2} + (y+4)^{2} + z^{2} - 25 = 0$$

and

$$h(x, y, z) = x^{2} + y^{2} + z^{2} - 9 = 0.$$



Regularity Condition (RC):

$$J(g,h)(x,y,z) = \begin{pmatrix} g_x & g_y & g_z \\ h_x & h_y & h_z \end{pmatrix} = \begin{pmatrix} 2x & 2(y+4) & 2z \\ 2x & 2y & 2z \end{pmatrix}$$

RC violated if:

$$\alpha \begin{pmatrix} 2x \\ 2(y+4) \\ 2z \end{pmatrix} = \begin{pmatrix} 2x \\ 2y \\ 2z \end{pmatrix} \Rightarrow \begin{cases} \alpha = 1 \lor x = 0 \\ \text{not satisfiable for } \alpha = 1 \\ \alpha = 1 \lor z = 0 \end{cases}$$

Thus, RC can only be violated for x = z = 0.

$$g(0, y, 0) = 0 + (y+4)^2 + 0 - 25 = 0 \Rightarrow y = -4 \pm 5,$$

$$h(0, y, 0) = 0 + y^2 + 0 - 9 = 0 \Rightarrow y = \pm 3.$$

Mathematics



Conclusion: The regularity condition is satisfied at all admissible points.

With f(x, y, z) = x - 8y + z and the Lagrange function:

$$F = f + \lambda g + \mu h,$$

we obtain the necessary conditions for extrema.

1)
$$F_x = 0$$
:
2) $F_y = 0$:
3) $F_z = 0$:
4) $g = 0$:
 $x^2 + (y+4)^2 + z^2 - 25 = 0$,
5) $h = 0$:
 $x^2 + y^2 + z^2 - 9 = 0$.





From the last two equations, it follows:

$$(y+4)^2 - y^2 = 16 \iff 8y + 16 = 16 \iff y = 0.$$

Substituting y = 0 into the second equation yields $\lambda = 1$, and therefore:

I)
$$1 + 2x + 2\mu x = 0$$
,
II) $1 + 2z + 2\mu z = 0$,
III) $x^2 + z^2 - 9 = 0$,
 $\lambda = 1, y = 0$.



I - II:

$$(1+\mu)(x-z) = 0 \iff \mu = -1 \text{ or } x = z.$$

For $\mu = -1$: (I) For x = z: (III) Candidates and Function Values For f(x, y, z) = x - 8y + z:

$$P_{1} = \begin{pmatrix} \frac{3}{\sqrt{2}} \\ 0 \\ \frac{3}{\sqrt{2}} \end{pmatrix}, \quad f(P_{1}) = 3\sqrt{2},$$
$$P_{2} = \begin{pmatrix} -\frac{3}{\sqrt{2}} \\ 0 \\ -\frac{3}{\sqrt{2}} \end{pmatrix}, \quad f(P_{2}) = -3\sqrt{2}.$$



Since the intersection of the two spherical surfaces (empty, a point, or a circular boundary) is a compact set, the minimum and maximum of the continuous function f are achieved. A comparison of the function values shows that:

- ▶ P_1 : Global maximum.
- ▶ P_2 : Global minimum.



Given the optimization problem:

$$f(x,y) = x^2 + y^2$$
 to minimize,

subject to the constraint:

$$g(x,y) = e^{x-1} - \arctan(y+1) - 1 = 0.$$

(a) Verify the regularity condition and demonstrate $x_0 = (1, -1)^T$, along with an appropriate multiplier λ , satisfies the requirements to be an admissible and stationary point of the Lagrange function F. (b) Investigate the Type of the Stationary Point Investigate the stationary point $(1, -1)^T$ for its type. For this purpose, set up the Hessian matrix $H_x F(x_0)$ and check its definiteness on the tangent space:

$$\ker Dg(x_0) = T_{G_a}(x_0).$$



Regularity Condition: The Jacobian of g(x, y) is the gradient:

$$Jg(x,y) = \nabla g(x,y) = \left(e^{x-1}, -\frac{1}{1+(1+y)^2}\right).$$

For all $(x, y) \in \mathbb{R}^2$, the gradient:

$$\nabla g(x,y) \neq (0,0).$$

This means the rank of $\nabla g(x, y)$ is 1, satisfying the Regularity Condition.

Admissibility:

The constraint is satisfied at the point $x_0 = (1, -1)^T$:

$$g(1,-1) = e^{1-1} - \arctan(-1+1) - 1 = 1 - 0 - 1 = 0.$$





Lagrange Function:

$$F(x, y, \lambda) = f(x, y) + \lambda g(x, y),$$

where:

$$F(x, y, \lambda) = x^2 + y^2 + \lambda \left(e^{x-1} - \arctan(y+1) - 1 \right).$$

Stationary Point:

To find a stationary point of $F(x, y, \lambda)$, we compute:

$$\nabla F(1, -1, \lambda) = 0.$$

Compute the gradient:

$$\nabla F(x,y) = \left(2x + \lambda e^{x-1}, \ 2y - \lambda \frac{1}{1 + (1+y)^2}\right)_{\text{Department of Mathematics}}$$

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Example: 04

At
$$x_0 = (1, -1)$$
:
 $\nabla F(1, -1) = \left(2(1) + \lambda e^{1-1}, \ 2(-1) - \lambda \frac{1}{1 + (1-1)^2}\right) = (2 + \lambda, \ -2 - \lambda).$

Setting $\nabla F(1, -1) = 0$, we find:

$$2 + \lambda = 0 \quad \Rightarrow \quad \lambda = -2.$$

Thus, $x_0 = (1, -1)$ is a stationary point. Hessian Matrix: The Hessian matrix of F(x, y) is:

$$H_{x,y}F = \begin{pmatrix} F_{xx} & F_{xy} \\ F_{yx} & F_{yy} \end{pmatrix}$$

Compute the second derivatives:

$$F_{xx} = \frac{\partial}{\partial x}(2x + \lambda e^{x-1}) = 2 + \lambda e^{x-1},$$





$$F_{xy} = F_{yx} = 0,$$

$$F_{yy} = \frac{\partial}{\partial y} \left(2y - \lambda \frac{1}{1 + (1+y)^2} \right) = 2 + \lambda \cdot \frac{2(1+y)}{(1 + (1+y)^2)^2}.$$
At (1,-1):

$$F_{xx}(1,-1) = 2 + \lambda e^{1-1} = 2 + \lambda = 0,$$

$$F_{yy}(1,-1) = 2 + \lambda \cdot \frac{2(1-1)}{(1 + (1-1)^2)^2} = 2.$$

Thus:

$$H_{x,y}F(1,-1) = \begin{pmatrix} 0 & 0 \\ 0 & 2 \end{pmatrix}.$$



Definiteness on the Tangent Space:

The tangent space is:

$$\ker Dg(x_0) = T_G(x_0) = \left\{ w \in \mathbb{R}^2 : \nabla g(x_0) \cdot w = 0 \right\}.$$

Let $w = \binom{w_1}{w_2}$. The condition:
 $\nabla g(1, -1) \cdot w = e^{1-1}w_1 - \frac{1}{1 + (1-1)^2}w_2 = w_1 - w_2 = 0,$

implies:

$$w_1 = w_2.$$

On the tangent space, let:

$$w = \alpha \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad \alpha \neq 0.$$





Quadratic Form: Compute:

$$w^T H_{x,y} F(1,-1)w = \alpha \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

Simplify:

$$w^{T}H_{x,y}F(1,-1)w = \alpha^{2} \cdot \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 2 \end{pmatrix} = \alpha^{2} \cdot 2 = 2\alpha^{2} > 0.$$

Since $w^T H_{x,y} F(1,-1) w > 0$ for all $w \neq 0$ in the tangent space, $H_{x,y} F(1,-1)$ is positive definite on the tangent space. The Hessian is positive definite on the tangent space, confirming that (1,-1) is a strict local minimum of f(x,y) under the constraint g(x,y) = 0.



Goal: Find the solution of the system:

$$f(x) = 0, \quad x \in D \subset \mathbb{R}^n, \quad f: D \to \mathbb{R}^n$$

Linearization:

Instead, solve the linear approximation at the point $x^{[k]}$:

$$T_1(x; x^{[k]}) = f(x^{[k]}) + J_f(x^{[k]})(x - x^{[k]}) = 0$$
$$\Rightarrow J_f(x^{[k]})(x - x^{[k]}) = -f(x^{[k]})$$

Use this x as the new approximation and iterate. The initial guess $x^{[0]}$ must be provided.



Iteration:

- 1. Compute $f(x^{[k]})$.
- 2. Compute the Jacobian matrix $J_f(x^{[k]})$.
- 3. Solve the linear system:

$$J_f(x^{[k]}) \cdot \Delta^{[k]} = -f(x^{[k]})$$

4. Update the solution:

$$x^{[k+1]} = x^{[k]} + \Delta^{[k]}$$

Initial Guess: Start with $x^{[0]}$ and iterate until convergence.





To determine the minimum of the function:

$$z = F(x, y) := x^{2} + 2y^{2} - 0.1\cos(x + y) - 3x + 2y,$$

Newton's Method should be applied to the function $f(x,y) := \nabla F(x,y)^T$.

- (a) Compute f(x, y) and the Jacobian matrix $J_f(x, y)$.
- (b) Formulate Newton's Method and perform the first iteration step by hand, using the starting vector:

$$(x_0, y_0) = (0, 0).$$

(c) Perform the iteration numerically and compute the solution to at least ten decimal places of accuracy.





$$f(x,y) = \begin{pmatrix} 2x+0.1\sin(x+y)-3\\4y+0.1\sin(x+y)+2 \end{pmatrix}$$
$$f(0,0) = \begin{pmatrix} -3\\2 \end{pmatrix}$$
$$J_f(x,y) = \begin{pmatrix} 2+0.1 * \cos(x+y) & 0.1 * \cos(x+y)\\0.1 * \cos(x+y) & 4+0.1 * \cos(x+y) \end{pmatrix}$$
$$J_f(0,0) = \begin{pmatrix} 2.1 & 0.1\\0.1 & 4.1 \end{pmatrix}$$
$$J_f(0,0) \cdot \Delta^{[0]} = -f(0,0) \iff \begin{pmatrix} 2.1 & 0.1\\0.1 & 4.1 \end{pmatrix} \cdot \begin{pmatrix} \Delta_1\\\Delta_2 \end{pmatrix} = -\begin{pmatrix} -3\\2 \end{pmatrix}$$
$$x^{[1]} = x^{[0]} + \Delta^{[0]}$$



MATLAB Implementation

```
format long
2 k = 0;
3 \mathbf{x} = 0; % Initial value
4 \mathbf{y} = \mathbf{0}; \% Initial value
5 for j = 1:5 % Number of Newton iterations
       c = 0.1 * cos(x + y);
       s = 0.1 * sin(x + y);
 7
       A = [2 + c c; c 4 + c]; \% Jacobian matrix
8
       b = [-2 * x - s + 3; -4 * y - s - 2]; % Function whose
9
           root is sought
      % Newton iteration
       dx = A \setminus b; % Solve the linear system
11
     k = k + 1;
12
       x = x + dx(1, 1);
13
       y = y + dx(2, 1);
14
15 end
16 % Gradient of the original function
17 g = b;
                                                           Department o
```

Iteration (k)	x	y
0	0.0000000000000000000000000000000000000	0.000000000000000
1	1.45348837209302	-0.52325581395349
2	1.45963647269063	-0.52018176365468
3	1.45963810885761	-0.52018094557119
4	1.45963810885773	-0.52018094557114
5	1.45963810885773	-0.52018094557114

Gradient of F at point $x^{[5]}$:

 $g = 10^{-15} \cdot (-0.444089209850063, -0.222044604925031)$

Since the Hessian matrix of F (i.e., the Jacobian matrix of f) is positive definite, this is indeed an approximation of a minimum.



THANK YOU

