

RECURSION THEORY

LECTURE II

22 October 2021

COPIED FROM
LECTURE I

Def. A MODEL OF COMPUTATION is a triple

$$M = (\Sigma, \Phi, h)$$

where

Σ is an alphabet

Φ is a transition function

h is an output function.

$$\Phi : \Sigma^* \times \Sigma^* \rightarrow \Sigma^*$$

where $l_h(\Phi(v, w)) \leq l_h(w) + 1$

PROGRAM INPUT STORAGE

This already incorporates the halting principle.

h is a partial function

$$h : \Sigma^* \dashrightarrow \Sigma^*$$

$H := \text{dom}(h)$; its elements are called the halting markers

and $h(w)$ is a subword of w .

Recursive definition:

$$w_0 \sim C_M(P, w, 0) := w$$

$$w_{n+1} \sim C_M(P, w, n+1) := \overline{\Phi}(P, C_M(P, w, n))$$

Called the M-computation with program P and input w.

$$\Phi : \Sigma^* \times \Sigma^* \rightarrow \Sigma^*$$

$$\text{where } l_h(\Phi(v, w)) \leq l_h(w) + 1$$

PROGRAM

INPUT

STORAGE

This already incorporates the halting principle.

Def. The M-computation with program P and input w halts if there is some $i \in N$ s.t.

$$C_M(P, w, i) \in H.$$

In this case, we say that the M-computation with P/w outputs

v if for the least i s.t.

$$C_M(P, w, i) \in H$$

we have

$$v = h(C_M(P, w, i)).$$

Let's write $\underline{o}_M(P, w)$ for this.

The computation gives us a partial function for each program $\forall P$:

$$f_P : \Sigma^* \dashrightarrow \Sigma^*$$

$$f_P(w) := \begin{cases} g_M(P, w) & \text{if the computation} \\ & \uparrow \\ & \text{is complete} \end{cases}$$

MODEL OF COMPUTATION

$$M := (\Phi, \Sigma, h)$$

transition
function alphabet output function

$$\Phi : \Sigma^* \times \Sigma^* \longrightarrow \Sigma^* \times \{0,1\}$$

PROGRAM INPUT NEXT STEP WHETHER HALTS OR NOT

$$h : \Sigma^* \longrightarrow \Sigma^*$$

s.t. $h(w_0)$ is a subword of w

$$C_M(P, w, 0) := w$$

$$C_M(P, w, u+1) := v \quad \text{where}$$

$$\Phi(P, C_M(P, w, u)) = (v, b)$$

If $b = 1$, we say program P halts at input w at time $u+1$.

We say that P halts at input w if there is some i s.t. P halts at w at time i .

If P halts at input w and i is the least such halting time, then

$$o_M(P, w) := h(C_M(P, w, i)).$$

If $P \in \Sigma^*$, we define

$$f_P : \Sigma^* \dashrightarrow \Sigma^*$$

by

$$f_P(w) := \begin{cases} o_M(P, w) & \text{if } P \text{ halts at } w \\ \uparrow & \text{o/w.} \end{cases}$$

REMARKS on the character of the notion of "model of computation".

- Our notion of "model of computation" is certainly not sufficient for being a reasonable model of computation.

Reason: You can make everything M-computable with the right choice of M.

Why? Let $A \subseteq \Sigma^*$ arbitrary.

Define transition function Φ by

$$\Phi(P, w) := \begin{cases} (\sigma, 1) & \text{if } w \in A \\ (\varepsilon, 1) & \text{if } w \notin A \end{cases}$$

This is a (strange) model of computation s.t. X_A is M-computable. → CONTINUED ON P.S.

Def. A partial function $f: \Sigma^* \rightarrow \Sigma^*$ is called D_M-computable if there $P \in \Sigma^*$ s.t. $f = f_P$.

Def. If $A \subseteq \Sigma^*$; fix some $\sigma \in \Sigma$. Then

$X_A : \Sigma^* \rightarrow \Sigma^*$
is called the characteristic function of A if $X_A(w) = \begin{cases} \epsilon & \text{if } w \notin A \\ \sigma & \text{if } w \in A \end{cases}$

Then A is called M-computable if X_A is M-computable.

2. So, our conditions for models of computation are minimal requirements for something to be a model of computation.

3. Even ~~that~~ is questionable:

Suppose $M = (\Phi, \Sigma, \Delta)$ is a (we) model of computation. Define

$$\bar{\Phi}(P, w) := (v, c)$$

Check $\bar{\Phi}(P, w) = : (v, b)$.

If $b = 1$, let $v := u$ and $c := 1$.

If $b = 0$, check $\bar{\Phi}(P, u) = (v', b')$ and let $v := v'$ and $c := b'$.

Define $\bar{M} := (\bar{\Phi}, \bar{\Sigma}, \bar{\Delta})$.

By construction, any partial function

$$f: \sum^* \dashrightarrow \sum^*$$

is M -computable iff it is \bar{M} -computable.

So \bar{M} is intuitively as good a "model of computation" as M , and yet it may fail the "length increased by at most 1" criterion.

Proposition 1 There are at most countably many computable partial functions.

Proof. \sum^* is a finite alphabet, so \sum^* is countably infinite.

Hence by definition

$$P \xrightarrow{f} P$$

is a surjection from \sum^* onto the set of M-computable partial fns.

q.e.d.

Proposition 2 There are uncountably many partial functions from \sum^* to \sum^* and hence there are non-computable partial functions.

Proof. By Cantor's Theorem, already the set of total functions from \sum^* to \sum^* is uncountable.

q.e.d.

THE HALTING PROBLEM

In Computer Science, subsets $A \subseteq \Sigma^*$ are called problems:

think of A as a task where you are given $w \in \Sigma^*$ and need to determine whether $w \in A$ or not.

Def. The halting problem is denoted by K and is defined as follows:

$w \in K : \iff f_w(w) \downarrow$.

Goal Show that K is not M-computable.

This will need a few additional properties of M:

COMPOSITIONALITY

If P and Q are programs then there is an $R \in \Sigma^*$ s.t.

$$f_R = f_P \circ f_Q$$

Remark: Composability does not follow from the other properties of being a "model of computation". But it is very reasonable in the sense that "programmable in Ctt" will have this property.

We define the following partial functions

$$d_{xy} : \sum^* \dashrightarrow \sum^*$$

where $x, y \in \sum^* \cup \{\uparrow\}$ as follows

$$d_{xy}(w) := \begin{cases} x & \text{if } w = \epsilon \\ y & \text{if } w \neq \epsilon \end{cases}$$

CASE DISTINCTION FUNCTIONS

CASE DISTINCTION

Every case distinction function d_{xy} is M-computable.

Remark: Again, it doesn't follow from the other properties, but is reasonable since we know how to do it in Ctt.

Theorem If M is a model of computation satisfying Case Distinctness & Composability, then K is not M -computable.

Proof. Assume towards a contradiction that it is:

K is M -computable, i.e., X_K is M -computable

$$X_K(w) := \begin{cases} \in & \text{if } w \notin K \Leftrightarrow f_w(w) \uparrow \\ \sigma & \text{if } w \in K \Leftrightarrow f_w(w) \downarrow \end{cases}$$

Let P be a program s.t.

$$X_K = \#P$$

Consider

$$\Delta g = d_{\Sigma^\uparrow} \circ f_P$$

(*) By our two extra assumptions, Δg is M -computable.

$$\Delta g(w) = \begin{cases} P \uparrow & \text{if } w \in K \\ \varepsilon & \text{if } w \notin K \end{cases}$$

If $w \in K \rightarrow f_P(w) = X_K(w) = \sigma$, so $\Delta g(w) \uparrow$.

If $w \notin K \rightarrow f_P(w) = X_K(w) = \varepsilon$, so $\Delta g(w) \downarrow = \varepsilon$.

By (*) Δg is M -computable, so ex. $G \in \Sigma^*$, s.t.

$$\Delta g = f_G$$

Now calculate $f_G(G)$:

$$\left\{ \begin{array}{l} G \in K \\ G \notin K \end{array} \right\} = f_G(G) = g(G) = \left\{ \begin{array}{ll} \uparrow & \text{if } G \in K \\ \downarrow & \text{if } G \notin K \end{array} \right.$$

Thus, we obtained a contradiction.

q.e.d.

REDUCTION FUNCTIONS

A function $f: \sum^* \rightarrow \sum^*$ is called a reduction function if it is total and computable.

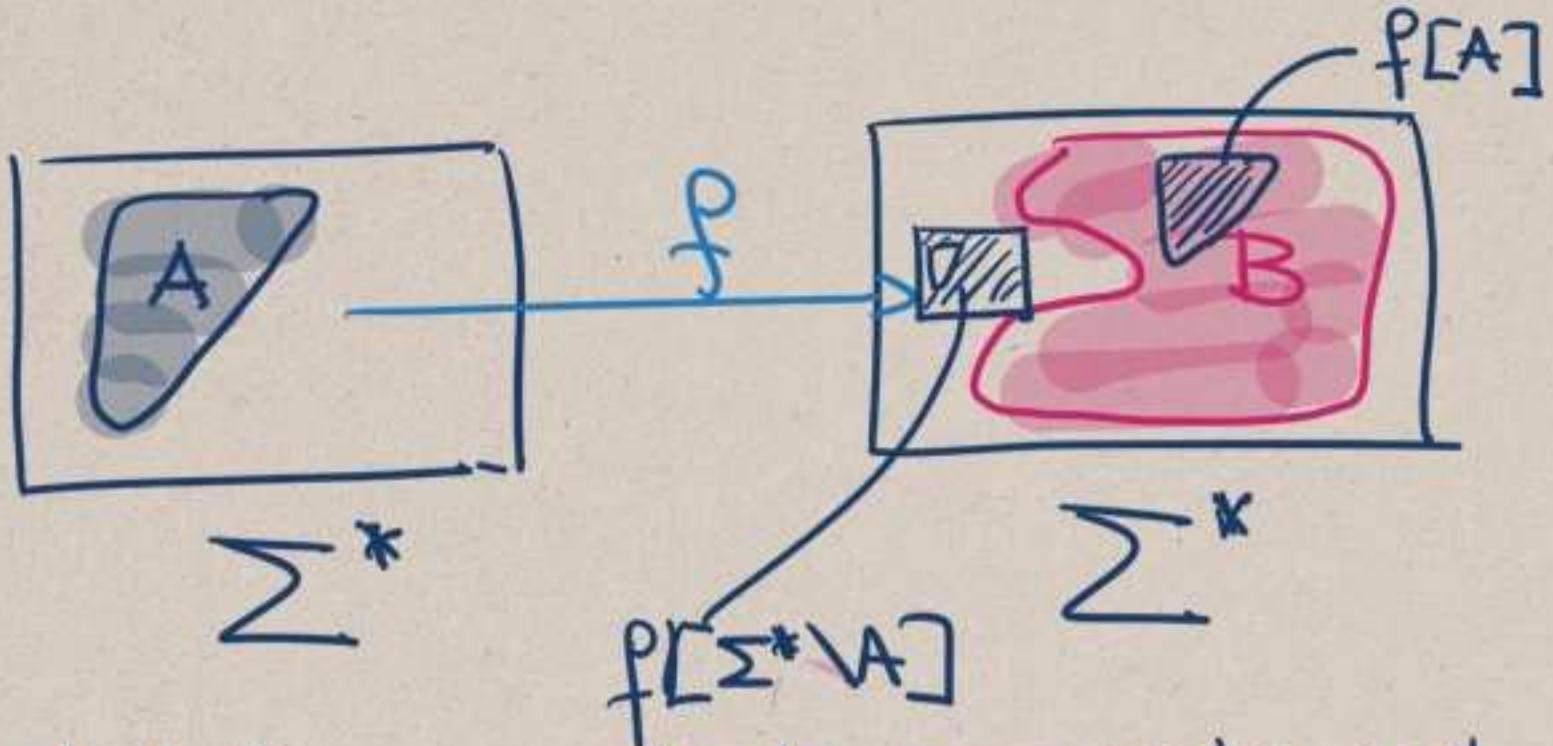
If $A, B \subseteq \sum^*$, we write

$A \leq_m B$

A is many-one-reducible to B

if there is a reduction function f s.t.

f.a. $w \in A \iff f(w) \in B$.



Remark 1 "many-one" because we're not demanding that f is an 'injective'; there is also a notion called "one-one reducibility" with injectives: \leq_1

Remark 2 This general definition occurs in many parts of mathematics, e.g., if you replace "computable" with "continuous", you get the notion of Wadge reduction; if you use "polynomial time computable", you get polynomial reductions, etc.

↑
William W. Wadge

Lemma If M is compositional and $A, B \subseteq \Sigma^*$ and

$f: \Sigma^* \rightarrow \Sigma^*$
 $w \in A \Leftrightarrow f(w) \in B$

$A \leq_m B$ and B

is M -computable,

then A is M -computable.

Proof. If B is computable, that means X_B is computable. But then

$$X_A = \frac{X_B \circ f}{\text{comp. comp.}}$$

so by compositionality, X_A is computable. q.e.d.

Corollary Under the same assumptions, if $A \leq_m B$ and A is not M -computable, then B is not M -computable.

This means: if we wish to show that a set B is not computable, it is enough to show [compositionality + case dist.] $K \leq_m B$.

Properties of \leq_m :

① Clearly reflexive. Under the assumption that the identity function $\text{id} : \sum^* \rightarrow \sum^*$
 $w \mapsto w$

is M-computable.

② Transitivity follows from
composability of M.

③ In general, not anti-symmetric.

Def. A relation R on a set X is
called a partial preorder if R is
reflexive and transitive.

If we define

$$A =_m B : \iff A \leq_m B \text{ and } B \leq_m A$$

many-one equivalent

This gives an equivalence relation.

[In general, if R is a partial preorder and
 $x =_{\equiv} x' : \iff xRx' \text{ and } x'Rx$, then
 $(X/\equiv, R)$ is a partial order.]

The \equiv_m -equivalence classes, called many-one degrees are clusters of sets that are computationally the same.

More about the structure of \leq_m :

④ If $A \neq \Sigma^*$, then $\emptyset \leq_m A$.

PROVIDED THAT CONSTANT FUNCTIONS ARE COMPUTABLE

If $w \in \Sigma^*$ $c_w(v) := w$ for all $v \in \Sigma^*$.

[Proof.] If $A \neq \Sigma^*$, there is some $w \notin A$.

Consider c_w

$$v \in \emptyset \iff c_w(v) \in A$$

False for all v

False for all v .

Thus c_w is a reduction function

from \emptyset to A .

$$\emptyset \not\leq_m \Sigma^*$$

$$\Sigma^* \not\leq_m \emptyset$$

⑤

⑥

⑦ If $A \neq \emptyset$, then $\Sigma^* \leq_m A$.

Provided that constant functions are computable.

[If $A \neq \emptyset$, let $w \in A$.

Then c_w reduces Σ^* to A :

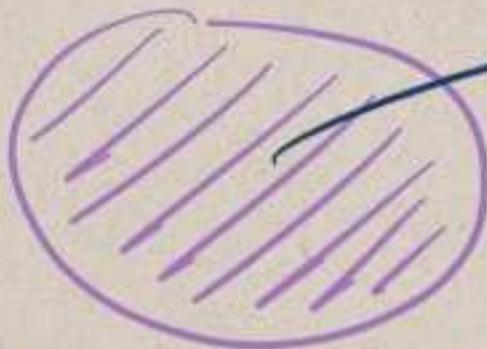
$$v \in \Sigma^* \iff c_w(v) \in A$$

↑ always true ↑ always true

Picture



The M-computable set
that are neither
 \emptyset nor Σ^*



\emptyset

Σ^*

We'll prove concretely in lecture III that
this picture is correct.