

Mathematical Systems and Control Theory – 6th Exercise Sheet.

Discussion of the solutions in the exercise on January 29, 2020.

Problem 1 (Hamiltonian matrices): Let $\mathcal{H} \in \mathbb{R}^{2n \times 2n}$ and $J = \begin{bmatrix} 0 & I_n \\ -I_n & 0 \end{bmatrix}$.

a) Show that the following statements are equivalent:

- i) The matrix \mathcal{H} is Hamiltonian, i. e., $\mathcal{H}^\top J + J\mathcal{H} = 0$.
- ii) The matrix $J\mathcal{H}$ is symmetric.
- iii) There exist $F, G, H \in \mathbb{R}^{n \times n}$ with $G = G^\top$ and $H = H^\top$ such that

$$\mathcal{H} = \begin{bmatrix} F & G \\ H & -F^\top \end{bmatrix}.$$

iv) The matrix \mathcal{H} is skew-adjoint with respect to the J -inner product

$$\langle x, y \rangle_J := y^\top Jx,$$

i. e., for all $x, y \in \mathbb{R}^{2n}$ it holds that $\langle \mathcal{H}x, y \rangle_J = -\langle x, \mathcal{H}y \rangle_J$.

b) Show that

$$\lambda \in \Lambda(\mathcal{H}) \quad \Rightarrow \quad \bar{\lambda}, -\lambda, -\bar{\lambda} \in \Lambda(\mathcal{H}).$$

Problem 2 (Isotropic invariant subspaces): Let $\mathcal{H} \in \mathbb{R}^{2n \times 2n}$ be Hamiltonian and let

$$X = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} \tag{1}$$

with $X_1, X_2 \in \mathbb{R}^{n \times r}$ such that the columns of X span an \mathcal{H} -invariant subspace \mathcal{X} , i. e.,

$$\mathcal{H}X = XZ$$

for some $Z \in \mathbb{R}^{r \times r}$. Show that if $\Lambda(Z) \subset \mathbb{C}^-$, then \mathcal{X} is *isotropic*, meaning that $\langle x, y \rangle_J = 0$ for all $x, y \in \mathcal{X}$.

Problem 3 (Hamiltonian and symplectic matrices): Let \mathbb{H}_{2n} and \mathbb{S}_{2n} denote the sets of Hamiltonian and symplectic matrices in $\mathbb{R}^{2n \times 2n}$, respectively. A matrix $\mathcal{S} \in \mathbb{R}^{2n \times 2n}$ is called *symplectic*, if \mathcal{S} is orthogonal with respect to the J -inner product, i. e., $\langle \mathcal{S}x, \mathcal{S}y \rangle_J = \langle x, y \rangle_J$ for all $x, y \in \mathbb{R}^{2n}$. Show the following statements:

- a) The matrix \mathcal{S} is symplectic, if and only if $\mathcal{S}^\top J\mathcal{S} = J$.
- b) It holds that $\det(\mathcal{S}) \in \{-1, 1\}$.
- c) The set \mathbb{S}_{2n} equipped with the matrix multiplication forms a group.

d) Each $\mathcal{H} \in \mathbb{H}_{2n}$ solves

$$\frac{d}{dt} (\langle (I_{2n} + t\mathcal{H})x, (I_{2n} + t\mathcal{H})y \rangle_J) |_{t=0} = 0 \quad \text{for all } x, y \in \mathbb{R}^{2n}.$$

e) The set \mathbb{H}_{2n} is a Lie algebra with respect to the *Lie bracket* $[\cdot, \cdot] : \mathbb{H}_{2n} \times \mathbb{H}_{2n} \rightarrow \mathbb{R}^{2n \times 2n}$ with

$$[\mathcal{H}_1, \mathcal{H}_2] := \mathcal{H}_1\mathcal{H}_2 - \mathcal{H}_2\mathcal{H}_1,$$

that is, the following properties are satisfied:

- i) $[\mathcal{H}_1, \mathcal{H}_2] \in \mathbb{H}_{2n}$ for all $\mathcal{H}_1, \mathcal{H}_2 \in \mathbb{H}_{2n}$;
 - ii) $[\mathcal{H}, \mathcal{H}] = 0$ for all $\mathcal{H} \in \mathbb{H}_{2n}$;
 - iii) $[\mathcal{H}_1 + \mathcal{H}_2, \mathcal{H}_3] = [\mathcal{H}_1, \mathcal{H}_3] + [\mathcal{H}_2, \mathcal{H}_3]$ for all $\mathcal{H}_1, \mathcal{H}_2, \mathcal{H}_3 \in \mathbb{H}_{2n}$;
 - iv) $[[\mathcal{H}_1, \mathcal{H}_2], \mathcal{H}_3] + [[\mathcal{H}_2, \mathcal{H}_3], \mathcal{H}_1] + [[\mathcal{H}_3, \mathcal{H}_1], \mathcal{H}_2] = 0$ for all $\mathcal{H}_1, \mathcal{H}_2, \mathcal{H}_3 \in \mathbb{H}_{2n}$ (Jacobi identity).
- f) It holds that $\mathcal{S}^{-1}\mathcal{H}\mathcal{S} \in \mathbb{H}_{2n}$ for all $\mathcal{H} \in \mathbb{H}_{2n}$ and $\mathcal{S} \in \mathbb{S}_{2n}$.