

Optimization of Complex Systems – 6th Exercise Sheet.

Discussion of the solutions in the exercise on December 9, 2019.

Problem 1 (projection formula): Let $u_a, u_b, p \in \mathbb{R}$ and $\lambda > 0$. Solve the optimization problem

$$\min_{v \in [u_a, u_b]} \left(pv + \frac{\lambda}{2} v^2 \right)$$

by deriving a projection formula.

Problem 2 (discontinuous trace operator): Assume that $\Omega \subset \mathbb{R}^N$ is a bounded Lipschitz domain with boundary Γ . Show that there exists no constant $c > 0$ that only depends on Ω such that

$$\|u\|_{L^2(\Gamma)} \leq c \|u\|_{L^2(\Omega)}$$

for each $u \in C(\overline{\Omega})$.

Problem 3 (adjoint equation and necessary optimality conditions): Let $\Omega \subset \mathbb{R}^N$ be a bounded Lipschitz domain with boundary Γ . Let functions $a_\Omega, u \in L^2(\Omega), a_\Gamma \in L^2(\Gamma), \beta \in L^\infty(\Omega), \alpha \in L^\infty(\Gamma)$ with $\alpha \geq 0$ almost everywhere be given. Let y and p be the weak solutions of the elliptic boundary value problems

$$\begin{aligned} -\Delta y &= \beta u & \text{in } \Omega, \\ \frac{\partial y}{\partial n} + \alpha y &= 0 & \text{on } \Gamma, \end{aligned}$$

and

$$\begin{aligned} -\Delta p &= a_\Omega & \text{in } \Omega, \\ \frac{\partial p}{\partial n} + \alpha p &= a_\Gamma & \text{on } \Gamma, \end{aligned}$$

respectively.

a) Show that

$$\int_{\Omega} a_\Omega y dx + \int_{\Gamma} a_\Gamma y ds = \int_{\Omega} \beta p u dx.$$

b) Assume now further that $\lambda, \lambda_\Omega, \lambda_\Gamma \geq 0$ and $y_\Omega \in L^2(\Omega), y_\Gamma \in L^2(\Gamma)$. Consider the optimal control problem

$$\min J(y, u) := \frac{\lambda_\Omega}{2} \|y - y_\Omega\|_{L^2(\Omega)}^2 + \frac{\lambda_\Gamma}{2} \|y - y_\Gamma\|_{L^2(\Gamma)}^2 + \frac{\lambda}{2} \|u\|_{L^2(\Omega)}^2$$

subject to

$$\begin{aligned} -\Delta y &= \beta u & \text{in } \Omega, \\ \frac{\partial y}{\partial n} + \alpha y &= 0 & \text{on } \Gamma, \\ u_a(x) &\leq u(x) \leq u_b(x) & \text{a. e. in } \Omega. \end{aligned}$$

Show that with $U_{\text{ad}} := \{u \in L^2(\Omega) : u_a(x) \leq u(x) \leq u_b(x) \text{ a. e. in } \Omega\}$ and for an optimal triple (\bar{u}, \bar{y}, p) , the optimality conditions are given by

$$\int_{\Omega} (\beta p + \lambda \bar{u})(u - \bar{u}) dx \geq 0 \quad \forall u \in U_{\text{ad}},$$

where the adjoint state p is given by the weak solution of

$$\begin{aligned} -\Delta p &= \lambda_{\Omega}(\bar{y} - y_{\Omega}) \quad \text{in } \Omega, \\ \frac{\partial p}{\partial n} + \alpha p &= \lambda_{\Gamma}(\bar{y} - y_{\Gamma}) \quad \text{on } \Gamma. \end{aligned}$$