Optimization of Complex Systems – 10th Exercise Sheet.

Discussion of the solutions in the exercise on January 27, 2020.

Problem 1 (primal dual active set strategy): Consider the optimal control problem from HW 9/3 and the discretization from sub-problem a). In the primal dual active set method, in each step a linear system of equations of the form

$$\begin{bmatrix} 0 & A & -R \\ A & -M & 0 \\ ER^{\mathsf{T}} & 0 & I \end{bmatrix} \begin{bmatrix} \widehat{p} \\ \widehat{y} \\ \widehat{u} \end{bmatrix} = \begin{bmatrix} 0 \\ -M \widehat{y}_{\mathrm{d}} \\ X_n^a \widehat{u}_a + X_n^b \widehat{u}_b \end{bmatrix},\tag{1}$$

is solved, where X_n^a and X_n^b are diagonal matrices with

$$X_{n,ii}^{a} = \begin{cases} 1 & \text{if } i \in A_{n}^{a}, \\ 0 & \text{otherwise} \end{cases}, \quad X_{n,ii}^{b} = \begin{cases} 1 & \text{if } i \in A_{n}^{b}, \\ 0 & \text{otherwise} \end{cases}$$

and

$$E := (\lambda N)^{-1} (I - X_n^a - X_n^b).$$

a) Show that the linear system (1) is equivalent to a symmetric linear system

$$\begin{bmatrix} 0 & A & RE_1 \\ A & -M & 0 \\ E_1^{\mathsf{T}} R^{\mathsf{T}} & 0 & -E_2 \end{bmatrix} \begin{bmatrix} \widehat{p} \\ \widehat{y} \\ \widetilde{u} \end{bmatrix} = \begin{bmatrix} 0 \\ -M \widehat{y}_{\mathrm{d}} \\ 0 \end{bmatrix},$$

for some matrices E_1 , E_2 of appropriate dimension and where the length of \tilde{u} corresponds to the number of inactive indices. Specify E_1 and E_2 .

b) Implement the primal dual active set strategy in MATLAB and test it for various levels of discretization on the example from HW 9/3. Visualize your results, i. e., plot the optimal control and corresponding optimal state function.

Problem 2 (saddle point matrices): Consider the matrix

$$M = \begin{bmatrix} A & B \\ B^{\mathsf{T}} & 0 \end{bmatrix}$$

with symmetric and negative definite $A \in \mathbb{R}^{n \times n}$ and $B \in \mathbb{R}^{n \times m}$ with rank B = m. Show that M has exactly m positive and n negative eigenvalues.