

## Exercise sheet # 04

### Topics in representation theory WS 2017

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#### Exercise 13

Let  $G$  be a connected matrix Lie group (or just a connected topological group), and let  $V \subset G$  be any open neighbourhood of the unit  $e \in G$ . Show that

$$G = \{g_1 \cdots g_n \mid n > 0, g_i \in V\} .$$

#### Exercise 14

Let  $G$  be a matrix Lie group and  $\mathfrak{g}$  its Lie algebra. Let  $W$  be a finite-dimensional  $\mathbb{C}$ -vector space and  $(W, \rho)$  a smooth representation of  $G$ . Show that for all  $X \in \mathfrak{g}$  we have

$$\rho(\exp(X)) = \exp(D\rho(X)) .$$

*Hint:* For  $t \in \mathbb{R}$  write  $f(t) = \rho(\exp(tX))$  and  $g(t) = \exp(tD\rho(X))$ . Then  $f, g$  are smooth functions  $\mathbb{R} \rightarrow \text{End}(W)$ . Try to find a first order differential equation they both satisfy.

*If you are bored:* A special case of the above result is that for all  $X \in \text{Mat}(N, \mathbb{C})$  we have  $\det(\exp(X)) = \exp(\text{tr}(X))$ . Do you see how?

#### Exercise 15

Let  $\mathcal{H}$  be a Hilbert space. Remind yourself of the definition of a semidirect product of groups and see if you can write  $UA(\mathcal{H})$  as a semidirect product of  $U(\mathcal{H})$  with something.

#### Exercise 16

In the lecture we defined  $\gamma : UA(\mathcal{H}) \rightarrow \text{Aut}(\mathbb{P}(\mathcal{H}))$  as follows. For  $X \in UA(\mathcal{H})$  abbreviate  $T = \gamma(X)$ . Then for  $[\varphi] \in \mathbb{P}(\mathcal{H})$  the class of  $\varphi \in \mathcal{H}$  we declare  $T([\varphi]) = [X\varphi]$ .

Show that  $T$  is independent of the choice of representative and does indeed lie in  $\text{Aut}(\mathbb{P}(\mathcal{H}))$ . Show that  $\gamma$  is a group homomorphism.

**Please turn over.**

**Exercise 17**

Let  $L$  be the Lorentz group of four-dimensional (or  $n$ -dimensional, if you like) Minkowski space. Set

$$L_+^\uparrow := \{M \in L \mid \det(M) > 0 \text{ and } M_{00} > 0\} .$$

1. Show that  $L_+^\uparrow$  is connected.

*Hint:* You could show that every element can be written as (rotation)  $\times$  (boost)  $\times$  (rotation). (You may assume that  $SO(3)$  is connected.)

2. How many connected components does  $L$  have? Can you write it as a semidirect product of  $L_+^\uparrow$  with something?