

XXI

TWENTY-FIRST LECTURE OF AUTOMATA & FORMAL LANGUAGES

22 NOVEMBER 2022

WHERE ARE WE IN THE OVERALL NARRATIVE OF
AUTOMATA & FORMAL LANGUAGES ?

	Chapter 2 type 3 (regular)	Chapter 3 type 2 (context-free)	Chapter 1 type 1 (context-sensitive)	Chapter 4 type 0
<i>Closure properties.</i>				
Concatenation	✓	✓		✓
Union	✓	✓		✓
Intersection	✓	×		
Complementation	✓	×		
Difference	✓	×		
<i>Decision problems.</i>				
Word problem	✓	✓		✓
Emptiness problem	✓	✓		
Equivalence problem	✓	×		



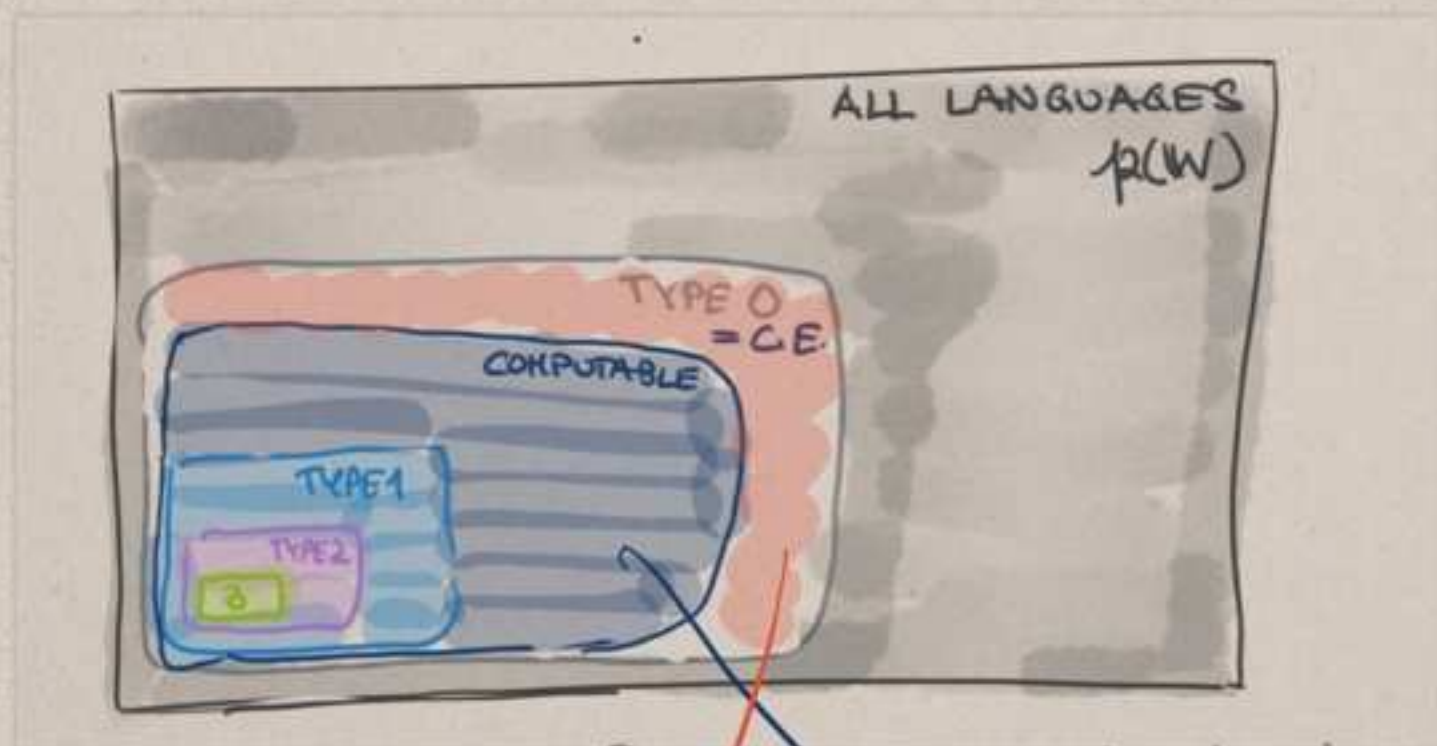
Type 0



COMPUTABLE
COMPUTABLY ENUMERABLE

Also: → The formulation of DECISION PROBLEMS
relies on the notion of
ALGORITHM
which is still not properly defined!

RECAP



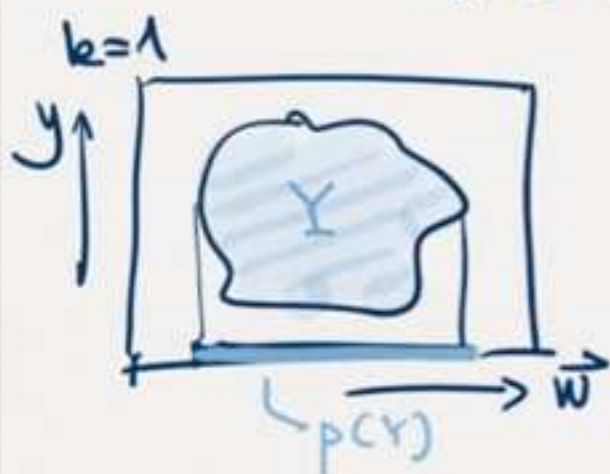
LECTURE XX: We finally proved that
 $c.e. \neq \text{Computable}$

The halting problem H (as H_0) is
computably enumerable, but not computable.

Goal: Understand c.e. sets better
[and argue that $c.e. = \text{type 0}$]

From Lecture XX:

Def. $X \subseteq \mathbb{W}^k$ is called Σ_1 if there is a computable $Y \subseteq \mathbb{W}^{k+1}$ s.t.
 $\vec{w} \in X \iff \exists y (\vec{w}, y) \in Y$.



We say
 $X = p(Y) = \{ \vec{w}; \exists y (\vec{w}, y) \in Y \}$
 is the projection of Y .

We say a set X is Π_1 if it is the complement of a Σ_1 set.

We say X is Δ_1 if it is both Σ_1 & Π_1 .

Motivation for the names

Σ_1

since it is written with
 existential quantifier

Π_1

--- universal (ES#4)

Δ_1

German DURCHSCHNITT
 (intersection)

ANALOGY

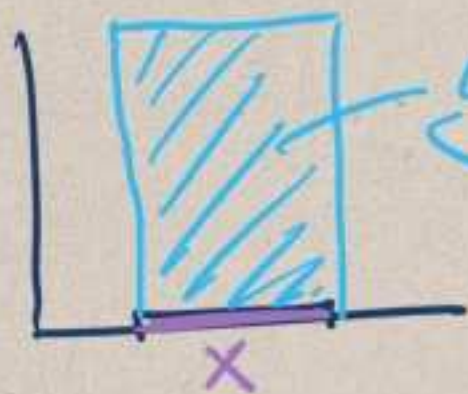
SUMS

PRODUCTS

Prop 4.30 Every computable set is Δ_1 .

Proof. By closure under complement, it's enough to show Σ_1 .

Given X , write
 $Y := \{(\vec{w}, y); \vec{w} \in X\}$



cylinder over $X = Y$

Clearly $p(Y) = X$.

g.e.d.

Theorem 4.31

X is c.e. $\iff X$ is Σ_1 .

Proof. " $\implies$ ".

If X is c.e., then ψ_X is comp.

So there is M s.t.

$$\psi_X = f_{M,k}$$

$$Y := \{(\vec{w}, y); t_{M,k}(\vec{w}, y) = a\}$$

By 4.24, Y is computable.

$$\vec{w} \in X \iff \psi_X(\vec{w}) \downarrow \iff \exists y (\vec{w}, y) \in Y.$$

" $\Leftarrow$ " Let X be Σ_1 . So let Y be computable s.t. $X = p(Y)$.

We know that χ_Y is computable.

Apply minimisation to χ_Y :

$h(\vec{w}) = \text{the minimal } y \text{ s.t. } (\vec{w}, y) \in Y.$

Note $\text{dom}(h) = p(Y) = X$.

So X is the domain of a partial comp. function, thus c.e. q.e.d.

APPLICATION

Suppose

$f: W^2 \rightarrow W$ partial computable

Then $\{w; \exists v f(w, v) \downarrow\}$ is c.e.

Naïve idea

Let $Y := \{(w, v); f(w, v) \downarrow\}$. But that's not in general computable as R_0 shows.

Let M be s.t. $f = f_{M, 2}$.

Let

This is a subset of W^3 , not W^2 !

$$Z := \{(w, v_0, v_1); t_{M,2}(w, v_0, v_1) = a\}$$

Clearly computable by L 4.24.

MERGING & SPLITTING TO THE RESCUE!

Merging & Splitting allows us to view W^2 as W , and treat W^3 as W^2 .

$$Y := \{(w, v); (w, v_{(0)}, v_{(1)}) \in Z\}$$

By the section on splitting,

$v \mapsto v_{(0)}$ are computable

$v \mapsto v_{(1)}$

& thus Y is computable.

$$\begin{aligned} \exists v f(w, v) \downarrow &\iff \exists v_0 \exists v_1 (w, v_0, v_1) \in Z \\ &\iff \exists v (w, v_{(0)}, v_{(1)}) \in Z \\ &\iff (w, v) \in Y \iff w \in p(Y). \end{aligned}$$

So the set

$$\{w; \exists v f(w, v) \downarrow\} \text{ is c.e.}$$

ZIGZAG TECHNIQUE

The previous argument is sometimes known as a zigzag argument.

You can visualise the $\exists v_0 \leftrightarrow \exists v_1$ transformation as searching through $\mathbb{N}^2$ in zigzag fashion.

	ε	0	1	00	10	01	11	000	...
ε	$t_{M,k}(\vec{w}, \varepsilon, \varepsilon) \rightarrow t_{M,k}(\vec{w}, \varepsilon, 0)$	$t_{M,k}(\vec{w}, \varepsilon, 1)$	$t_{M,k}(\vec{w}, \varepsilon, 00)$	$t_{M,k}(\vec{w}, \varepsilon, 10)$	...				
0	$t_{M,k}(\vec{w}, 0, \varepsilon)$	$t_{M,k}(\vec{w}, 0, 0)$	$t_{M,k}(\vec{w}, 0, 1)$	$t_{M,k}(\vec{w}, 0, 00)$	$t_{M,k}(\vec{w}, 0, 10)$	...			
1	$t_{M,k}(\vec{w}, 1, \varepsilon)$	$t_{M,k}(\vec{w}, 1, 0)$	$t_{M,k}(\vec{w}, 1, 1)$	$t_{M,k}(\vec{w}, 1, 00)$	$t_{M,k}(\vec{w}, 1, 10)$	...			
00	$t_{M,k}(\vec{w}, 00, \varepsilon)$	$t_{M,k}(\vec{w}, 00, 0)$	$t_{M,k}(\vec{w}, 00, 1)$	$t_{M,k}(\vec{w}, 00, 00)$	...				
10	$t_{M,k}(\vec{w}, 10, \varepsilon)$	$t_{M,k}(\vec{w}, 10, 0)$	$t_{M,k}(\vec{w}, 10, 1)$	...					
...	...	...	...	...	...	...	...	...	...

This would not work as a SERIAL computation: if you first try to run the first row, it might never halt!

So there may be many rows need to be processed in PARALLEL.

In other words:

we can do ∞ many computations in parallel.

Corollary 4.33

X is computable $\iff$
 X is Δ_1

Proof:

" $\implies$ " Prop. 4.30.

" $\impliedby$ " uses zigzag:

Since X is Δ_1 , we know that there are machines M, M' s.t.

$$\vec{w} \in X \iff \exists v \ t_{M,k}(\vec{w}, v) = a$$

$$\vec{w} \notin X \iff \exists v \ t_{M',k}(\vec{w}, v) = a$$

$$f(\vec{w}, v) := \begin{cases} t_{M,k}(\vec{w}, v_{(1)}) & \text{if } \#v_{(0)} \text{ is even} \\ t_{M',k}(\vec{w}, v_{(1)}) & \text{if } \#v_{(0)} \text{ is odd} \end{cases}$$

Apply minimisation to f , obtain h

$$h(\vec{w}) := \text{the best } v \text{ s.t.}$$

$$f(\vec{w}, v) \neq \varepsilon$$

Output a if $\#h(\vec{w})_{(0)}$ is even

ε if $\#h(\vec{w})_{(0)}$ is odd

q.e.d.

Corollary 4.34

Σ_1 is not closed under complementation.

$[W \setminus K \text{ is } \Pi_1 \text{ and not } \Delta_1, \text{ so not } \Sigma_1]$

!!

CORRECTED

AFTER THE LECTURE

Theorem Every type 0 language is c.e.

Proof. Fix $G = (\Sigma, V, P, S)$

Let $\Sigma' = \Sigma \cup \{\Rightarrow\}$.

Encode derivations as

$$\sigma_0 \Rightarrow \sigma_1 \Rightarrow \dots \Rightarrow \sigma_n$$

this is a Σ' -word.

Say $w \in (\Sigma')^*$ is a derivation code if

$$w = \sigma_0 \Rightarrow \dots \Rightarrow \sigma_n$$

with $(\sigma_0, \dots, \sigma_n)$ a G -derivation.

In this case, we call σ_0 the initial string
 σ_n the final string.

$Y := \{ (w, v); \text{ } v \text{ is a derivation code} \\ \text{with initial string } S \\ \text{\& final string } w \}$

Clearly, Y is computable.

But

$$w \in L(G) \iff \underbrace{\exists v (w, v) \in Y}_{\Sigma_1, \text{ i.e. c.e.}}$$

q.e.d.

Converse also holds:

Every c.e. set $X \subseteq \mathbb{N}$ is a type 0 language.

Proof in Salomaa,
Formal Languages
Theorem 4.4
(p. 37)



Arto Salomaa
(born 1934)

Proof sketch in § 4.10.

[Salomaa proves this via Turing machines,
so we'll see a sketch after having
introduced them.]

§ 4.9 Closure properties

Prop. 4.38 The computable sets are closed
under all five operations.

Proof. Let A, B be computable, so
therefore χ_A, χ_B are
computable functions.

get

$$\chi_{A \cap B}(\vec{w}) = \begin{cases} a & \text{if } \chi_A(\vec{w}) = a = \chi_B(\vec{w}) \\ \varepsilon & \text{o/w} \end{cases}$$

$$\chi_{A \cup B}(\vec{w}) = \begin{cases} \varepsilon & \text{if } \chi_A(\vec{w}) = \varepsilon = \chi_B(\vec{w}) \\ a & \text{o/w} \end{cases}$$

$$\chi_{W \setminus A}(\vec{w}) = \begin{cases} a & \text{if } \chi_A(\vec{w}) = \varepsilon \\ \varepsilon & \text{o/w} \end{cases}$$

All obviously computable.

[This is essentially the idea of a product machine.]

Homework Try to make this idea of a "product machine"

precise: what properties does a product operation need to have to allow the conclusion that the class is closed under all Boolean operations?

Concatenation AB is computable.

$[A, B \subseteq W]$

Given w , check all possible $w = vu$ for v initial segment of w .

How many? $|w|$ many initial segments.

For each such, check $\chi_A(v) = a = \chi_B(u)$.

If so, output a ;

If none of them work, output ε .

q.e.d.