

# Differential geometry

## Lecture 4: Tangent spaces (part 2)

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**1** Tangent vectors from local coordinates

**2** Differentials of smooth maps

**3** Immersions, submersions, embeddings, local diffeomorphisms

### Recap of lecture 3:

- defined **vector space of smooth functions**  $C^\infty(M)$
- defined **bump functions** (w.r.t. given data)
- recalled **tangent vectors & tangent space of  $\mathbb{R}^n$**
- defined **tangent vectors for general smooth manifolds**
- showed that tangent vectors are **local objects**
- erratum: **nope!**

How can we write down tangent vectors explicitly? Use **local coordinates!**

### Definition

Let  $\varphi = (x^1, \dots, x^n)$  be local coordinates on a smooth manifold  $M$  defined on  $U \subset M$ . Then  $\frac{\partial}{\partial x^i} \Big|_p \in T_p M$ ,  $p \in U$ , is defined as

$$\frac{\partial}{\partial x^i} \Big|_p (f) := \frac{\partial f}{\partial x^i}(p) := \frac{\partial (f \circ \varphi^{-1})}{\partial u^i}(\varphi(p)) \quad \forall f \in C^\infty(M).$$

- we can think of  $\frac{\partial}{\partial x^i} \Big|_p$  as partial derivative at  $p$  with respect to the chosen local coordinates  $(x^1, \dots, x^n)$
- alternative notations:  $\partial_i \Big|_p$ ,  $\partial_{x^i} \Big|_p$

$\rightsquigarrow$  need to check the following:

### Lemma

$\frac{\partial}{\partial x^i} \Big|_p$  is a well-defined tangent vector.

**Proof:** (next page)

↪ need to check **linearity** and **Leibniz rule**:

- linearity follows from linearity of partial derivatives in  $\mathbb{R}^n$
- Leibniz rule: for  $f, g \in C^\infty(M)$  we calculate

$$\begin{aligned}
 & \frac{\partial(f \cdot g)}{\partial x^i}(p) \\
 &= \frac{\partial((f \cdot g) \circ \varphi^{-1})}{\partial u^i}(\varphi(p)) \\
 &= \frac{\partial((f \circ \varphi^{-1}) \cdot (g \circ \varphi^{-1}))}{\partial u^i}(\varphi(p)) \\
 &= g(p) \frac{\partial(f \circ \varphi^{-1})}{\partial u^i}(\varphi(p)) + f(p) \frac{\partial(g \circ \varphi^{-1})}{\partial u^i}(\varphi(p)) \\
 &= g(p) \frac{\partial f}{\partial x^i}(p) + f(p) \frac{\partial g}{\partial x^i}(p) \quad \square
 \end{aligned}$$

### Example

$$\frac{\partial x^j}{\partial x^i}(p) = \delta_i^j \quad \forall 1 \leq i \leq n, 1 \leq j \leq n,$$

follows from  $(x^j \circ \varphi^{-1})(u^1, \dots, u^n) = u^j$ .

It turns out that **any** tangent vector can be written as a linear combination of the  $\frac{\partial}{\partial x^i} \Big|_p$ 's in a **unique** way:

### Proposition

For all  $p \in M$  and any local chart  $(\varphi = (x^1, \dots, x^n), U)$  with  $p \in U$ , the set of tangent vectors  $\left\{ \frac{\partial}{\partial x^i} \Big|_p, 1 \leq i \leq n \right\}$  is **basis** of  $T_p M$ .

### Proof:

Linear independence of the  $\frac{\partial}{\partial x^i} \Big|_p$ :

- assume  $\exists (c^1, \dots, c^n) \in \mathbb{R}^n \neq 0$ , such that

$$v_0 := \sum_{i=1}^n c^i \frac{\partial}{\partial x^i} \Big|_p = 0$$

as a linear map

- then  $\exists$  at least one  $1 \leq j \leq n$ , such that  $c^j \neq 0$ , and we obtain

$$v_0(x^j) = c^j \neq 0$$

which is a contradiction to  $v_0 = 0$

$$T_p M = \text{span}_{\mathbb{R}} \left\{ \frac{\partial}{\partial x^i} \Big|_p, 1 \leq i \leq n \right\}:$$

- assume wlog  $\varphi(U) = B_r(0)$  [after possibly shrinking  $U$  and translating  $\varphi$  via constant vector  $-\varphi(p) \in \mathbb{R}^n$ ]
- for any  $g \in C^\infty(\varphi(U))$  obtain using the **fundamental theorem of calculus** and

$$g_j(q) := \int_0^1 \frac{\partial g}{\partial u^j}(tq) dt \quad \forall q \in \varphi(U), 1 \leq j \leq n,$$

the identity

$$g = g(0) + \sum_{j=1}^n g_j u^j$$

- $\forall f \in C^\infty(U)$  get via  $g := f \circ \varphi^{-1}$

$$f = g \circ \varphi = f(p) + \sum_{j=1}^n f_j x^j$$

(continuation of proof)

- acting with  $\frac{\partial}{\partial x^i} \Big|_p$  on both sides of above eqn. yields

$$f_i(p) = \frac{\partial f}{\partial x^i}(p) \quad \forall 1 \leq i \leq n$$

- for any  $v \in T_p M$  fixed get by using  $x^i(p) = 0$  for all  $1 \leq i \leq n$  and the Leibniz rule

$$v(f) = \sum_{i=1}^n \frac{\partial f}{\partial x^i}(p) v(x^i)$$

- hence

$$v = \sum_{i=1}^n v(x^i) \frac{\partial}{\partial x^i} \Big|_p,$$

meaning that  $\left\{ \frac{\partial}{\partial x^i} \Big|_p, 1 \leq i \leq n \right\}$  spans  $T_p M$  as claimed

□



Immediate consequence:

### Corollary

The **dimensions** of a smooth manifold  $M$  and its tangent space  $T_p M$  **coincide** for all  $p \in M$ .

**Question:** How do the tangent vectors of the form  $\sum_i c^i \frac{\partial}{\partial x^i} \Big|_p$  behave under a change of coordinates?

$\rightsquigarrow$  to answer this, we need **differentials** of smooth maps

## Definition

Let  $M$  be a smooth manifold of dimension  $m$  and  $N$  be a smooth manifold of dimension  $n$ .

- The **differential at a point**  $p \in M$  of a smooth function  $f \in C^\infty(M)$  is defined as the linear map

$$df_p : T_p M \rightarrow \mathbb{R}, \quad v \mapsto v(f).$$

In a given local coordinate system  $\varphi = (x^1, \dots, x^m)$  on  $M$  that covers  $p$ ,  $df_p$  is of the form

$$df_p : \left. \frac{\partial}{\partial x^i} \right|_p \mapsto \frac{\partial f}{\partial x^i}(p).$$

- (continued on next page)

## Definition (continuation)

- The **differential at a point**  $p \in M$  of a smooth map  $F : M \rightarrow N$  in given local coordinate systems  $\varphi = (x^1, \dots, x^m)$  on  $M$  and  $\psi = (y^1, \dots, y^n)$  on  $N$  covering  $p \in M$  and  $F(p) \in N$ , respectively, is defined as the linear map

$$dF_p : T_p M \rightarrow T_{F(p)} N, \quad \left. \frac{\partial}{\partial x^i} \right|_p \mapsto \sum_{j=1}^n \left. \frac{\partial F^j}{\partial x^i} (p) \right. \left. \frac{\partial}{\partial y^j} \right|_{F(p)},$$

where we have used the notation  $F^j := y^j \circ F$ . The **rank** of  $F$  is the rank of the linear map  $dF_p : T_p M \rightarrow T_{F(p)} N$ , which coincides with the rank of the **Jacobi matrix** of  $F$  at  $p$  in the local coordinate systems  $\varphi, \psi$ ,

$$\left( \frac{\partial F^j}{\partial x^i} (p) \right)_{ji} \in \text{Mat}(n \times m, \mathbb{R}).$$

[  $j = \text{row}, i = \text{column}$  ]

Similar to real analysis, differentials fulfils a **chain rule**:

### Lemma

Let  $M, N, P$  be smooth manifolds and  $F : M \rightarrow N$ ,  $G : N \rightarrow P$ , smooth maps. Then

$$d(G \circ F)_p = dG_{F(p)} \circ dF_p$$

for all  $p \in M$ .

**Proof:** For any  $v \in T_p M$  and  $f \in C^\infty(P)$  we have

$$\begin{aligned} d(G \circ F)_p(v)(f) &= v(f \circ G \circ F) \\ &= dF_p(v)(f \circ G) = dG_{F(p)}(dF_p(v))(f). \end{aligned}$$



### Example

For any local coordinate system  $\varphi = (x^1, \dots, x^n)$  on  $M$  covering  $p \in M$ ,  $d\varphi_p : T_p M \rightarrow T_{\varphi(p)} \mathbb{R}^n \cong \mathbb{R}^n$  is of the form

$$d\varphi_p = (dx^1, \dots, dx^n)_p = (dx_p^1, \dots, dx_p^n),$$

$$dx_p^j \left( \frac{\partial}{\partial x^i} \Big|_p \right) = \delta_i^j.$$

Viewed as  $n \times n$ -matrix [by identifying  $d\varphi_p$  with its Jacobi matrix],  $d\varphi_p = \mathbb{1}_n$ .

## Lemma

For two local coordinate systems  $\varphi = (x^1, \dots, x^n)$  and  $\psi = (y^1, \dots, y^n)$  with overlapping domain on  $M$  we obtain for all  $p$  contained in the overlap the identity

$$\left. \frac{\partial}{\partial x^i} \right|_p = \sum_{j=1}^n \left. \frac{\partial y^j}{\partial x^i} \right|_p \left. \frac{\partial}{\partial y^j} \right|_p.$$

### Proof:

For any  $f \in C^\infty(M)$ ,  $1 \leq i \leq n$ ,  $p$  in the overlap we calculate

$$\begin{aligned} \left. \frac{\partial f}{\partial x^i} \right|_p &= \left. \frac{\partial (f \circ \varphi^{-1})}{\partial u^i} \right|_{\varphi(p)} = \left. \frac{\partial (f \circ \psi^{-1} \circ \psi \circ \varphi^{-1})}{\partial u^i} \right|_{\varphi(p)} \\ &= \sum_{j=1}^n \left. \frac{\partial (f \circ \psi^{-1})}{\partial u^j} \right|_{\psi(p)} \left. \frac{\partial (u^j \circ \psi \circ \varphi^{-1})}{\partial u^i} \right|_{\varphi(p)} \\ &= \sum_{j=1}^n \left. \frac{\partial f}{\partial y^j} \right|_p \left. \frac{\partial y^j}{\partial x^i} \right|_p. \end{aligned}$$

□

Properties of differentials are used to classify smooth maps as follows:

### Definition

- A smooth map between smooth manifolds  $F : M \rightarrow N$  is called an **immersion** if  $dF_p : T_p M \rightarrow T_{F(p)} N$  is injective for all  $p \in M$ .
- $F : M \rightarrow N$  is called a **submersion** if  $dF_p : T_p M \rightarrow T_{F(p)} N$  is surjective for all  $p \in M$ .
- An immersion  $F : M \rightarrow N$  is called an **embedding** if  $F$  is injective and a homeomorphism onto its image  $F(M) \subset N$  equipped with the subspace topology.
- A smooth map  $F : M \rightarrow N$  between smooth manifolds of the same dimension is called a **local diffeomorphism** if for all  $p \in M$  there exists an open neighbourhood of  $p$ ,  $U \subset M$ , such that  $F|_U : U \rightarrow N$  is a diffeomorphism onto its image.

# END OF LECTURE 4

## Next lecture:

- smooth manifold analogue to inverse function theorem
- more examples of smooth maps
- submanifolds of smooth manifolds