

# Differential geometry

## Lecture 15: Connections in vector bundles

David Lindemann

University of Hamburg  
Department of Mathematics  
Analysis and Differential Geometry & RTG 1670

15. June 2020



## 1 Motivation

## 2 Connections in vector bundles

## Recap of lecture 14:

- introduces **(local) frames** of vector bundles
- described **subbundles** using local frames of ambient vector bundles, discussed **examples**
- defined **Killing vector fields**

**Question 1:** What is a good choice for a **derivative** of sections in vector bundles, in particular tensor powers of the tangent bundle?

**Hint 1:** Not the Lie derivative.

**Question 2:** What is a, in a sense preferred, way to **transport** vectors or, more generally, tensors in a given fibre to some other fibre in  $TM \rightarrow M$ , respectively  $T^{r,s}M \rightarrow M$ , along a piecewise smooth curve? What extra data do we need on  $M$  to make **our choice** the preferred choice?

**Hint 2:** Do not attempt to use a **coordinate-based** approach...

**Question 3:** Can we somehow **connect** fibres in a vector bundle in the sense that we can **identify** them via a preferred linear isomorphism for each pair of fibres?

**Hint 3:** If we can solve Q1 & Q2 and, frankly, work **a lot** more.

## Definition

Let  $E \rightarrow M$  be a vector bundle. A **connection in  $E \rightarrow M$**  is a bilinear map

$$\nabla : \mathfrak{X}(M) \times \Gamma(E) \rightarrow \Gamma(E), \quad (X, s) \mapsto \nabla_X s,$$

that is  $C^\infty(M)$ -**linear in the first entry**, i.e.

$$\nabla_{fX} s = f \nabla_X s \quad \forall f \in C^\infty(M), X \in \mathfrak{X}(M), s \in \Gamma(E),$$

and fulfils the **Leibniz rule**

$$\nabla_X(fs) = X(f)s + f \nabla_X s \quad \forall f \in C^\infty(M), X \in \mathfrak{X}(M), s \in \Gamma(E).$$

The last condition can be written as  $\nabla(fs) = s \otimes df + f \nabla s$ .

**Note:** A connection can be canonically extended to be defined on **local sections**.

## Remark

Recall that for  $E = T^{r,s}M$ , the Lie derivative is **not**  $C^\infty(M)$ -linear in the first entry of  $(X, A) \mapsto \mathcal{L}_X A$ ,  $X \in \mathfrak{X}(M)$ ,  $A \in \mathcal{T}^{r,s}(M)$ . Hence,  $\mathcal{L}$  is **not a connection** in  $T^{r,s}M \rightarrow M$  for any  $r, s$ .

**Question:** How do we actually calculate with a given connection in a vector bundle  $E \rightarrow M$ ?

**Answer:** Use **local frames** of  $E$  and **local coordinates** on  $M$ .

## Definition

Let  $\nabla$  be a connection in  $E \rightarrow M$  of rank  $\ell$  and  $\{s_1, \dots, s_\ell\}$  be a local frame over  $U \subset M$  open, such that there exist local coordinates  $(x^1, \dots, x^n)$  on  $U \subset M$ . This can always be achieved after possibly shrinking  $U$ . Let further  $\dim(M) = n$ . Define

$$\nabla s_i := \omega_i, \quad \omega_i(X) = \nabla_X s_i \quad \forall X \in \mathfrak{X}(M),$$

for  $1 \leq i \leq \ell$ . Then each  $\omega_i$  is an  $E$ -valued **1-form**, that is  $\omega_i \in \Gamma(E|_U \otimes T^*M|_U)$  for all  $1 \leq i \leq \ell$ . (continued on next page)

## Definition (continuation)

Thus we have

$$\omega_i = \sum_{j=1}^n \omega_{ij} \otimes dx^j$$

for all  $1 \leq i \leq \ell$ , where  $\omega_{ij} \in \Gamma(E|_U)$  for all  $1 \leq i \leq \ell$ ,  $1 \leq j \leq n$ . We can further write

$$\omega_{ij} = \sum_{k=1}^{\ell} \omega_{ij}^k s_k,$$

with  $\omega_{ij}^k \in C^\infty(U)$  for all  $1 \leq i \leq \ell$ ,  $1 \leq j \leq n$ ,  $1 \leq k \leq \ell$ .

Recall that for any **local section**  $s \in \Gamma(E|_U)$  we can write

$s = \sum_{i=1}^k f^i s_i$  with  $f^i$ ,  $1 \leq i \leq k$ , **uniquely determined** for  $s$ . We

obtain the general formula

$$\nabla s = \sum_{i=1}^{\ell} s_i \otimes df^i + \sum_{j=1}^n \sum_{i,k=1}^{\ell} f^i \omega_{ij}^k s_k \otimes dx^j. \quad (1)$$

(continued on next page)

## Definition (continuation)

On the other hand we might write

$$\nabla s_i = \omega_i = \sum_{k=1}^{\ell} s_k \otimes \omega_i^k$$

for all  $1 \leq i \leq \ell$ , where  $\omega_i^k \in \Omega^1(U)$  for all  $1 \leq i, k \leq \ell$ . The  $\omega_i^k$  are called **connection 1-forms** and determine the connection  $\nabla$  in  $E|_U$  completely. We can view  $(\omega_i^k)$  as an  $(\ell \times \ell)$ -**matrix valued map** where each entry is a **local 1-form** on  $M$ .

**Warning:** Even though connection 1-forms have “**1-form**” in their name, they **do not** transform like  $E$ -valued 1-forms when changing the **local frame** in  $E$ , e.g. via a change of coordinates on  $M$  when  $E = T^{r,s}M$ . (details on next page)

**Question:** Does every manifold **admit** a connection in its tangent bundle?

**Answer:** Yes! [Exercise! Alternatively, wait until we define the so-called Levi-Civita connection.]



## Lemma

Let  $\nabla$  be a **connection** in a vector bundle  $E \rightarrow M$  of rank  $\ell$ . Let  $\{s_1, \dots, s_\ell\}$  and  $\{\tilde{s}_1, \dots, \tilde{s}_\ell\}$  be **local frames** of  $E$  over a **chart neighbourhood**  $U \subset M$ , equipped with local coordinates  $(x^1, \dots, x^n)$ , that are related by the  $(\ell \times \ell)$ -**matrix valued smooth map**

$$A : U \rightarrow \text{GL}(\ell), \quad (s_1, \dots, s_\ell) \cdot A = (\tilde{s}_1, \dots, \tilde{s}_\ell).$$

Let  $(\omega_i^k)$  denote the **matrix of connection 1-forms with respect to the local frame**  $\{s_1, \dots, s_\ell\}$  and  $(\tilde{\omega}_i^k)$  the **matrix of connection 1-forms with respect to the local frame**  $\{\tilde{s}_1, \dots, \tilde{s}_\ell\}$ . Then

$$(\tilde{\omega}_i^k) = A^{-1} dA + A^{-1} (\omega_i^k) A.$$

In the above equation,  $dA$  denotes the differential of the map  $A : U \rightarrow \text{GL}(\ell)$ , where we identify  $T\text{GL}(\ell) \cong \text{GL}(\ell) \times \text{End}(\mathbb{R}^\ell)$ .

Connections, like tangent vectors, are **local objects**:

### Lemma A

Let  $\nabla$  be a connection in a vector bundle  $E \rightarrow M$  of rank  $\ell$ .  
Let  $U \subset M$  be open and suppose that for two vector fields  $X, Y \in \mathfrak{X}(M)$  and two sections in  $E \rightarrow M$ ,  $s, \tilde{s}$ , we have

$$X|_U = Y|_U, \quad s|_U = \tilde{s}|_U.$$

Then  $\nabla_X s$  and  $\nabla_Y \tilde{s}$  **coincide** on  $U$ .

### Proof:

- $\nabla_X s|_U = \nabla_Y s|_U$  follows from the **tensoriality property** in the first argument of any connection
- $\rightsquigarrow$  suffices to show  $\nabla_X s|_U = \nabla_X \tilde{s}|_U$
- by the linearity in the second argument,  $\nabla_X s$  and  $\nabla_X \tilde{s}$  coincide in  $U$  **if and only if**  $\nabla_X(s - \tilde{s})|_U \equiv 0$
- $\rightsquigarrow$  suffices to prove  $\nabla_X s|_U = 0$  if  $s|_U = 0$

(continued on next page)

- fix  $p \in U$ , choose a **bump function**  $b \in C^\infty(M)$  and an open nbh. of  $p$ ,  $V \subset U$ , that is **precompact** in  $U$ , such that  $b|_V \equiv 1$  and  $\text{supp}(b) \subset U$
- the **Leibniz rule** implies

$$0 = \nabla_X 0|_p = \nabla_X (bs)|_p = X(b)s|_p + b(p)\nabla_X s|_p = \nabla_X s|_p$$

- since  $p \in U$  was **arbitrary**, above completes the proof  $\square$

**Note:** Lemma A means that  $(\nabla_X s)(p)$  for any  $p \in M$  depends only on  $X_p \in T_p M$  and the restriction of  $s$  to an **arbitrary small** open neighbourhood of  $p$  in  $M$

## Example A

Consider  $\mathbb{R}^n$  with **canonical coordinates**  $(u^1, \dots, u^n)$  and **induced global frame**  $\left\{ \frac{\partial}{\partial u^1}, \dots, \frac{\partial}{\partial u^n} \right\}$  of  $T\mathbb{R}^n \rightarrow \mathbb{R}^n$ . Vector fields on  $\mathbb{R}^n$  can be viewed as **smooth vector valued functions**. So a reasonable approach for a connection, **defined in our choice of coordinates**, is

$$\nabla_X Y := \sum_i X(Y^i) \frac{\partial}{\partial u^i} \in \mathfrak{X}(\mathbb{R}^n)$$

for all vector fields  $X = \sum_i X^i \frac{\partial}{\partial u^i}$  and  $Y = \sum_i Y^i \frac{\partial}{\partial u^i}$ . This means that, in canonical coordinates, we **differentiate  $Y$  entrywise in  $X$ -direction**. One verifies that the so-defined  $\nabla$  **in fact is a connection** in  $T\mathbb{R}^n \rightarrow \mathbb{R}^n$ . This **construction** is, however, **not coordinate-independent**, meaning that in **different coordinates**,  $\nabla_X Y$  will **not be the entrywise differentiation** of  $Y$  in  $X$ -direction. Note that all connection 1-forms of the above connection **identically vanish**.

**Question:** How does the connection in Example A look like in **different coordinates**, e.g. in polar coordinates?

**Answer:** To formalise this **type** of question, first define the following:

### Definition

Let  $\nabla$  be a connection in  $TM \rightarrow M$  and  $(x^1, \dots, x^n)$  be local coordinates on  $U \subset M$ . Then in the induced local frame of  $TM$ ,

$$\nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j} = \sum_{k=1}^n \Gamma_{ij}^k \frac{\partial}{\partial x^k},$$

where  $\Gamma_{ij}^k \in C^\infty(M)$ ,  $1 \leq i, j, k \leq n$ . The terms  $\Gamma_{ij}^k$  are called **Christoffel symbols** of the connection  $\nabla$  with respect to the chosen local coordinates  $(x^1, \dots, x^n)$ .

**Note:** The Christoffel symbols specify the connection  $\nabla$  in  $TM|_U \rightarrow U$  completely, meaning in particular that two connections in  $TM \rightarrow M$  coincide if they have the same Christoffel symbols for all local coordinates on  $M$ .

In comparison with the most general case, the Christoffel symbols are for the **special case** of the tangent bundle with induced local frame precisely the terms  $\omega_{ij}^k$  on page 7.

**Question:** How do Christoffel symbols behave under a **change of coordinates**?

**Answer:**

### Lemma

Let  $M$  be an  $n$ -dimensional smooth manifold,  $\nabla$  a connection in  $TM \rightarrow M$ . Let further  $\varphi = (x^1, \dots, x^n)$  and  $\psi = (y^1, \dots, y^n)$  local coordinate systems on an open set  $U \subset M$ . Let  $\Gamma_{ij}^k$  denote the **Christoffel symbols** of  $\nabla$  **with respect to**  $\varphi$  and  $\tilde{\Gamma}_{ij}^k$  denote the **Christoffel symbols** of  $\nabla$  **with respect to**  $\psi$ . Then the following **identity** holds:

$$\Gamma_{ij}^k = \sum_{\rho} \frac{\partial^2 y^{\rho}}{\partial x^i \partial x^j} \frac{\partial x^k}{\partial y^{\rho}} + \sum_{\mu, \nu, \rho} \frac{\partial y^{\mu}}{\partial x^i} \frac{\partial y^{\nu}}{\partial x^j} \frac{\partial x^k}{\partial y^{\rho}} \tilde{\Gamma}_{\mu\nu}^{\rho}.$$

**Proof:** (on the right)

## Example

In **polar coordinates**  $(r, \varphi)$ , the connection  $\nabla$  in  $T(\mathbb{R}^2 \setminus \{(x, 0), x \leq 0\}) \rightarrow \mathbb{R}^2 \setminus \{(x, 0), x \leq 0\}$  as in Example A has the following Christoffel symbols:

$$\Gamma_{\varphi\varphi}^r = -r, \quad \Gamma_{r\varphi}^\varphi = \Gamma_{\varphi r}^\varphi = \frac{1}{r}, \quad 0 \text{ else.}$$

Recall that knowing the Lie derivative on vector fields and functions allowed us to make sense of  $\mathcal{L}_X A$  for  $X \in \mathfrak{X}(M)$  and any type of tensor field  $A \in \mathcal{T}^{r,s}(M)$ , turning it into a **tensor derivative** for  $X$  fixed.

**Question:** Can we similarly define a **connection in**  $T^{r,s}M \rightarrow M$  if we have a connection in the tangent bundle? Do we get a similar **Leibniz rule** for the tensor product?

**Answer:** Yes! (see next page)

## Lemma

Let  $\nabla$  be a connection in  $TM \rightarrow M$ . Then  $\nabla$  induces a **connection**  $\nabla$  in each tensor bundle  $T^{r,s}M \rightarrow M$ ,  $r \geq 0$ ,  $s \geq 0$ , such that

- the induced connection in  $T^{1,0}M \cong TM \rightarrow M$  **coincides with**  $\nabla$ ,
- $\nabla f = df$  for all  $f \in \mathcal{T}^{0,0}(M) = C^\infty(M)$ ,
- the induced connection is a **tensor derivation** in the second argument, meaning that

$$\nabla(A \otimes B) = (\nabla A) \otimes B + A \otimes (\nabla B)$$

whenever the tensor field  $A \otimes B$  is defined,

- the induced connections **commute with all possible contraction**, meaning that for any contraction  $C : \mathcal{T}^{r,s}(M) \rightarrow \mathcal{T}^{r-1,s-1}(M)$  we have

$$\nabla(C(A)) = C(\nabla(A))$$

for all tensor fields  $A \in \mathcal{T}^{r,s}(M)$ .



### Lemma (continuation)

The so-defined connections in each tensor bundle  $T^{r,s}M \rightarrow M$  are **uniquely determined** by the above properties.

#### Proof:

- first define **candidates** for each connection, then we show that it **fulfils all requirements**, then prove **uniqueness**
- **note:** to define **any** connection in  $T^{r,s}M \rightarrow M$  it suffices to specify what it does on sections that can be, locally, written as **pure tensor products** of  $r$  local vector fields and  $s$  local 1-forms
- for  $T^{1,0}M \rightarrow M$ , we simply take  $\nabla$  to be our **initial connection**, which thereby automatically fulfils the **first point**
- for  $f \in \mathcal{T}^{0,0}(M) = C^\infty(M)$  we set  $\nabla f = df$ , thereby fulfilling the **second point**

(continued on next page)

(continuation of proof)

- $\rightsquigarrow$  define  $\nabla$  in  $T^{0,1}M \rightarrow M$  in such a way, that **the last two points** will be satisfied
- define for any local 1-form  $\omega \in \Omega^1(U)$ ,  $U \subset M$  open,

$$(\nabla_X \omega)(Y) := X(\omega(Y)) - \omega(\nabla_X Y) \quad \forall X, Y \in \mathfrak{X}(U)$$

- this in fact **defines a connection** in  $T^{0,1}M \rightarrow M$
- $\rightsquigarrow$  obtain a connection in  $T^{r,s}M \rightarrow M$  for all  $r \geq 0$ ,  $s \geq 0$  by requiring the third point, i.e. the tensor **Leibniz rule**, to hold on **pure** and, hence by **linear extension, on all tensor fields**
- again, this in fact defines a connection in each  $T^{r,s}M \rightarrow M$
- $\rightsquigarrow$  remains to check that then the fourth point, that is the **contraction property**, holds

(continued on next page)

(continuation of proof)

- This can be done **inductively using** the third point, the **Leibniz rule**, after checking that it holds for the **only possible contraction in**  $T^{1,1}M \rightarrow M$ , which on pure tensor fields is of the form

$$C(X \otimes \omega) = \omega(X) \quad \forall X \in \mathfrak{X}(M), \omega \in \Omega^1(M)$$

- find for all  $X, Y \in \mathfrak{X}(M)$  and all  $\omega \in \Omega^1(M)$

$$\nabla_Y(C(X \otimes \omega)) = \nabla_Y(\omega(X)) = Y(\omega(X))$$

- **by definition** of  $\nabla$  in  $T^{0,1}M \rightarrow M$  and the **imposed** third point (Leibniz), the above coincides with

$$\begin{aligned} Y(\omega(X)) &= (\nabla_Y \omega)(X) + \omega(\nabla_Y X) \\ &= C(X \otimes (\nabla_Y \omega)) + (\nabla_Y X) \otimes \omega = C(\nabla_Y(X \otimes \omega)) \end{aligned}$$

(continued on next page)

(continuation of proof)

- remains to show **uniqueness** of so-defined connections
- suppose there is **an other connection**  $\tilde{\nabla}$  **fulfilling all requirements** of this lemma
- linearity in the second argument  $\rightsquigarrow$  suffices to show that  $\nabla$  and  $\tilde{\nabla}$  coincide on **local pure tensor fields**
- **Leibniz rule** and  $\nabla = \tilde{\nabla}$  in  $TM \rightarrow M \rightsquigarrow$  suffices to show that  $\nabla$  and  $\tilde{\nabla}$  **coincide in**  $T^{0,1}M = T^*M \rightarrow M$
- this follows from **first** ( $\nabla = \tilde{\nabla}$  in  $TM \rightarrow M$ ), **second** ( $\tilde{\nabla}f = df$ ), and **forth** (contraction property) point by direct calculation of the left- and right-hand of  $\tilde{\nabla}(C(A)) = C(\tilde{\nabla}(A))$  for  $A = X \otimes \omega$  where  $X$  is **any local vector field** and  $\omega$  is **any local 1-form** □

**Remark**

**Differentiation** of tensor fields with respect to a **connection** induced by a connection in the tangent bundle is sometimes called **covariant differentiation**.  $\nabla_X A$  is then called **covariant derivative of  $A$  in direction  $X$** .

# END OF LECTURE 15

## Next lecture:

- covariant differentiation along curves
- parallel transport
- torsion tensor of a connection
- metric connections
- Levi-Civita connection