Differential geometry Lecture 13: Traces, raising and lowering indices, and vector bundles along pseudo-Riemannian submanifolds

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2 Raising/Lowering indices

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Recap of lecture 12:

- recalled definition of pseudo-Euclidean vector spaces
- defined pseudo-Riemannian metrics & pseudo-Riemannian manifolds
- defined arc-length of curves
- described pseudo-Riemannian metrics in local coordinates
- studied examples of pseudo-Riemannian manifolds, in particular Riemannian submanifolds of Riemannian manifolds

Recall the definition of the trace from linear algebra:

Definition

Let V be a real finite-dimensional vector space and $A \in \text{End}(V) \cong V \otimes V^*$, so that for a basis $\{v_1, \ldots, v_n\}$ of V

$$A = \sum_{i,j=1}^n a^i{}_j v_i \otimes v_j^*.$$

The trace of A is defined as

$$\operatorname{tr}(A) := \sum_{i=1}^{n} a^{i}{}_{i}.$$

Note: The trace of an endomorphism is **independent** of the chosen basis.

Examples

- $\operatorname{tr}(\operatorname{id}_V) = \dim(V)$,
- $\operatorname{tr}(A+B) = \operatorname{tr}(A) + \operatorname{tr}(B)$ for all $A, B \in \operatorname{End}(V)$,
- tr(AB) = tr(BA) for all $A, B \in End(V)$,
- $\operatorname{tr}(v \otimes \omega) = \omega(v)$ for all $v \in V$, $\omega \in V^*$.
- if $A: I \to \operatorname{GL}(n)$ is a **smooth curve**, we have $\frac{\partial}{\partial t} \det(A) = \operatorname{tr} \left(A^{-1} \frac{\partial A}{\partial t} \right) \det(A)$

If $(V, \langle \cdot, \cdot \rangle)$ is a pseudo-Euclidean vector space, we can calculate the trace as follows:

Lemma

Let $A \in End(V)$ and $\{e_1, \ldots, e_n\}$ be an **orthonormal basis** of V w.r.t. $\langle \cdot, \cdot \rangle$. Then

$$\operatorname{tr}(A) = \sum_{i=1}^{n} \varepsilon_i \langle e_i, A e_i \rangle,$$

where $\varepsilon_i := \langle e_i, e_i \rangle \in \{-1, 1\}$ for all $1 \le i \le n$.

Trace and induced scalar product in tensor bundles

If we have a pseudo-Euclidean vector space ($V, \langle \cdot, \cdot \rangle$), we can define a scalar product on tensor powers of V and V^* .

Definition

Let
$$\{e_1, \ldots, e_n\}$$
 be a basis of $(V, \langle \cdot, \cdot \rangle)$, $A \in V^{\otimes r} \otimes (V^*)^{\otimes s}$,
and write $\langle \cdot, \cdot \rangle = \sum_{i,j=1}^n g_{ij} e_i^* \otimes e_j^*$,
$$A = \sum_{\substack{1 \leq i_1, \ldots, i_r \leq n \\ 1 \leq j_1, \ldots, j_r \leq n}} A^{i_1 \ldots i_r}{}_{j_1 \ldots j_s} e_{i_1} \otimes \ldots \otimes e_{i_r} \otimes e_{j_1}^* \otimes \ldots \otimes e_{j_s}^*.$$
Then
$$\langle A, A \rangle := \sum_{\substack{1 \leq i_1, \ldots, i_r \leq n \\ 1 \leq j_1, \ldots, j_r \leq n}} A^{i_1 \ldots i_r}{}_{j_1 \ldots j_s} A^{l_1 \ldots l_r}{}_{j_1 \ldots J_s} g_{i_1 l_1} \cdots g_{i_r l_r} \cdot g^{j_1 J_1} \cdots g^{j_s J_s}$$

defines a **possibly indefinite symmetric bilinear form** on $V^{\otimes r} \otimes (V^*)^{\otimes s}$. In the above formula the *g*-terms fulfil, when viewed as a symmetric matrix, $(g^{ij}) := (g_{ij})^{-1}$.

By switching from **pseudo-Euclidean vector spaces** to **pseudo-Riemannian manifolds**, we get the following fibrewise analogous definition:

Definition

Let (M, g) be a pseudo-Riemannian manifold, $A \in \mathbb{T}^{1,1}(M)$ an endomorphism field, $h \in \mathbb{T}^{0,2}(M)$ a symmetric (0, 2)-tensor field, and $B \in \mathbb{T}^{r,s}(M)$ for r + s > 0 an arbitrary tensor field. Then the **trace of** A is in local coordinates (x^1, \ldots, x^n) , so that $A = \sum A^i_j \frac{\partial}{\partial x^i} \otimes dx^j$, given by

$$\operatorname{tr}(A) := \sum_{i} A^{i}_{i}.$$

The above term is **invariant under coordinate change**, which follows from fibrewise invariance of the choice of basis in T_pM and the fact that the coordinate cotangent vector at each point are precisely the **dual** to the coordinate tangent vectors at that point. This means that $\operatorname{tr}_g(A) \in C^{\infty}(M)$. (continued on next page)

Definition (continuation)

The trace of h with respect to g is defined in local coordinates as

$$\operatorname{tr}_g(h) := \sum_{i,j} h_{ij} g^{ij}.$$

As for the endomorphism field, $tr_g(h)$ is **invariant under coordinate change**, but **not** invariant of the pseudo-Riemannian metric g. Furthermore, we define the induced pairing of B with itself with respect to g in the given local coordinates as

$$g(B,B) := \sum B^{i_1 \dots i_r}{}_{j_1 \dots j_s} \cdot B^{l_1 \dots l_r}{}_{J_1 \dots J_s} \cdot g_{i_1 l_1} \cdots g_{i_r l_r} \cdot g^{j_1 J_1} \cdots g^{j_s J_s},$$

where

$$B = \sum B^{i_1 \dots i_r}{}_{j_1 \dots j_s} rac{\partial}{\partial x^{i_1}} \otimes \dots \otimes rac{\partial}{\partial x^{i_r}} \otimes dx^{j_1} \otimes \dots \otimes dx^{j_s}$$

and $(g^{ij}) = (g_{ij})^{-1}$ at each point when viewed as a symmetric matrix valued map. As for the trace, value of g(B, B) does not depend on the choice of local coordinates which implies $g(B, B) \in C^{\infty}(M)$.

Note: One can similarly define a symmetric pairing g in the bundle $T^{r,s}M \to M$, and not just for its local sections, which is an example of a possibly indefinite **bundle metric**.

Example

For any pseudo-Riemannian manifold (M, g) of dimension n we have

 $\operatorname{tr}_g(g) = g(g,g) \equiv n.$

Next, we come to a process called raising, respectively lowering, indices of tensor fields. This is a most commonly used utility in theoretical physics, in particular general relativity.

Proposition A

Let (M, g) be a pseudo-Riemannian manifold. Then $T^{r,s}M \to M$ and $T^{r',s'}M \to M$ are isomorphic as vector bundles if r + s = r' + s'.

Proof:

• first show that
$$T^*M \to M$$
 and $TM \to M$ are **isomorphic**

- define $F: TM \to T^*M, \quad v \mapsto g(v, \cdot)$
- obtain $g(v, \cdot) \in T_p^*M$ for all $v \in T_pM$
- *F* is smooth, fibre-preserving, and at each point a linear isomorphism

(continued on next page)

(continuation of proof)

• F^{-1} is given by

 $F^{-1}: T^*M o TM, \quad \omega \mapsto g^{-1}(\omega, \cdot),$

where we use the **pointwise identification** $(T_p^*M)^* = T_pM$ and g^{-1} is given in local coordinates by

$$g^{-1} = \sum g^{ij} \frac{\partial}{\partial x^i} \otimes \frac{\partial}{\partial x^j}$$

- to show that T^{r,s} M → M and T^{r',s'} M → M are isomorphic for arbitrary r, s, r', s' with r + s = r' + s' one inductively uses entrywise isomorphisms
- note: there are usually choices involved which vector or covector parts to change into covector and vector parts, respectively

Remark

Proposition A is, in local coordinates, known as the process of **lowering and raising indices**. The isomorphisms of vector bundles $T^{r,s}M \rightarrow T^{r+1,s-1}M$ are denoted by \sharp (read: **sharp**), and the isomorphisms $T^{r,s}M \rightarrow T^{r-1,s+1}M$ are denoted by \flat (read: **flat**). Hence the name **musical isomorphisms**.

Our first application of the above is the generalization of the **gradient of a function** to pseudo-Riemannian manifolds:

Definition

Let (M, g) be a pseudo-Riemannian mfd. & $f \in C^{\infty}(M)$. The **gradient vector field of** f **w.r.t.** g, $\operatorname{grad}_{g}(f) \in \mathfrak{X}(M)$, is defined as

$$\operatorname{grad}_g(f) := g^{-1}(df) \in \mathfrak{X}(M)$$

In local coordinates (x^1, \ldots, x^n) , $\operatorname{grad}_g(f) = \sum_{i,j=1}^n \frac{\partial f}{\partial x^i} g^{ij} \frac{\partial}{\partial x^j}$.

Gradient vector fields are important tools in the study of pseudo-Riemannian submanifolds:

Lemma A

Let (\overline{M}, g) be a pseudo-Riemannian manifold, $M \subset \overline{M}$ a pseudo-Riemannian submanifold of codimension k, and identify $T_q M = \iota_*(T_q M) \subset T_q \overline{M}$ for all $q \in M$, where ι is the inclusion. For $p \in M$ fixed let $f = (f^1, \ldots, f^k) : U \to \mathbb{R}^k$, $U \subset \overline{M}$ open, $p \in U$, be any smooth map of maximal rank such that

$$M \cap U = \{f = 0\} \subset \overline{M}.$$

Then

$$T_q M = \ker(df_q^1) \cap \ldots \cap \ker(df_q^k) \subset T_q \overline{M}$$

and

$$(T_q M)^{\perp} = \operatorname{span}_{\mathbb{R}} \{ \operatorname{grad}_g(f^1)_q, \dots, \operatorname{grad}_g(f^k)_q \} \subset T_q \overline{M}$$

for all $q \in M \cap U$. In particular, $T_q M \oplus (T_q M)^{\perp} = T_q \overline{M}$ for all $q \in M \cap U$.

Proof: (next page)

(continuation of proof)

- fix $q \in M \cap U$ and $v \in T_q M$
- for any smooth curve γ : I → M ⊂ M, γ'(t) is tangential to M ∀t ∈ I, follows by using adapted coordinates
- choose a smooth curve $\gamma : (-\varepsilon, \varepsilon) \to M \subset \overline{M}$ fulfilling $\gamma'(0) = v$
- $\rightsquigarrow \forall 1 \leq i \leq k$:

$$df^{i}(v) = \left. \frac{\partial}{\partial t} \right|_{t=0} (f \circ \gamma) = \left. \frac{\partial}{\partial t} \right|_{t=0} (0) = 0$$

- hence: $T_q M \subset \ker(df_q^1) \cap \ldots \cap \ker(df_q^k)$
- for other direction: f being of maximal rank implies df_a^1, \ldots, df_a^k are linearly independent
- this implies

$$\dim(\ker(df_q^1)\cap\ldots\cap\ker(df_q^k))=\dim(T_q\overline{M})-k=\dim(T_qM).$$

■ by comparing dimensions, obtain $T_q M \supset \ker(df_q^1) \cap \ldots \cap \ker(df_q^k)$ (continued on next page) (continuation of proof)

- for $(T_q M)^{\perp} = \operatorname{span}_{\mathbb{R}} \{ \operatorname{grad}_g(f^1)_q, \dots, \operatorname{grad}_g(f^k)_q \}$ use that g is pointwise nondegenerate
- obtain that each nonzero vector in $\operatorname{span}_{\mathbb{R}}\{\operatorname{grad}_g(f^1)_q, \ldots, \operatorname{grad}_g(f^k)_q\}$ is not contained in $T_q M = \operatorname{ker}(df_q^1) \cap \ldots \cap \operatorname{ker}(df_q^k)$
- by $T_q M \oplus (T_q M)^{\perp} = T_q \overline{M}$ and comparing dimensions, the above claim follows

Question: How can we make sense of $T_q M \oplus (T_q M)^{\perp} = T_q \overline{M}$ in a coordinate free, global statement?

Answer: Introduce vector bundles along submanifolds and subbundles!

Lemma B

Let $\pi_E : E \to \overline{M}$ be a vector bundle of rank k and M be a submanifold of \overline{M} . Then

$$\pi_{E|_M} : E|_M \to M, \quad (E|_M)_p := \pi_{E|_M}^{-1}(p) := \pi_E^{-1}(p) \quad \forall p \in M,$$
$$E|_M := \bigsqcup_{p \in M} (E|_M)_p,$$

is a vector bundle of rank k over M. It is called **vector bundle** along M.

Proof:

- suffices to work in local coordinates
- w.l.o.g. assume that locally, M is given by an **open set in** \mathbb{R}^{ℓ} , $\ell \leq \dim(\overline{M})$, and the inclusion $M \subset \overline{M}$ is of the form $\iota : (x^1, \ldots, x^{\ell}) \mapsto (x^1, \ldots, x^{\ell}, 0, \ldots, 0) \in \mathbb{R}^{\dim(\overline{M})}$
- next, apply vector bundle chart lemma to the restriction of, after possibly shrinking U, the transition functions of $E \to \overline{M}$ in local coordinates to $U \subset \mathbb{R}^{\dim(\overline{M})}$
- obtain that the vector parts are, still, smooth

Heuristically, Lemma B means that we make the base manifold smaller but keep all possible vectors at each point in the vector bundle. **Combining** Lemma A & B, we get the following:

Definition

Let (\overline{M}, g) be a pseudo-Riemannian manifold and $M \subset \overline{M}$ a pseudo-Riemannian submanifold of codimension k. Then the **normal bundle of** M, $TM^{\perp} \to M$, is defined as

$$TM^{\perp} := \bigsqcup_{p \in M} (T_p M)^{\perp},$$

with projection induced by the tangent bundle of \overline{M} along M, $T\overline{M}|_M \to M$. In particular we have

 $T\overline{M}|_{M}=TM\oplus TM^{\perp},$

and the above direct sum is orthogonal with respect to g.

The above definition can be put into a more general context, namely that of **subbundles**. (next page)

Definition

Let $\pi_E : E \to M$ be a vector bundle. Another vector bundle $\pi_F : F \to M$ is called **subbundle of** $E \to M$ if for all $p \in M$, F_p is a **linear subspace** of E_p , the **canonical injection**

 $F \hookrightarrow E$,

given fibrewise by the inclusion $F_{\rho} \subset E_{\rho}$, is an **embedding**, $\pi_F = \pi_E|_F$, and for all local trivializations ϕ of E the **restrictions** $\phi|_F$ are local trivializations of F. This means that the **bundle structure** of $F \to M$ and the **smooth manifold structure** of the total space F are induced by the bundle structure of $E \to M$ and the smooth manifold structure of the total space E, respectively.

Note: In the above sense, $TM \to M$ and $TM^{\perp} \to M$ of a pseudo-Riemannian submanifold $M \subset \overline{M}$ are both **subbundles** of $T\overline{M}|_M \to M$.

Examples

• Let
$$f: \mathbb{R}^{n+1} \to \mathbb{R}$$
, $f(u^1, \ldots, u^n) = \sum_i (u^i)^2$ and consider

the ambient space \mathbb{R}^{n+1} equipped with its standard Riemannian metric, denoted simply by $\langle \cdot, \cdot \rangle$. Then

$$S^n = \{f=1\} \subset \mathbb{R}^{n+1}$$

is a Riemannian submanifold of $(\mathbb{R}^{n+1}, \langle \cdot, \cdot \rangle)$ with induced Riemannian metric

 $g := \langle \cdot, \cdot \rangle |_{TS^n \times TS^n}.$

The normal bundle of $S^n \subset \mathbb{R}^{n+1}$, $TS^{n\perp}$, is spanned by the position vector field $\xi \in \mathfrak{X}(\mathbb{R}^{n+1})$ along S^n ,

 $\xi: p \mapsto p \quad \forall p \in \mathbb{R}^{n+1}.$

The **tangent bundle** of TS^n , viewed as a subbundle of $T\mathbb{R}^{n+1}|_{S^n}$, is thus fibrewise given by

$$T_{
ho}S^n = \ker(\langle \xi_{
ho}, \cdot
angle) \subset T_{
ho}\mathbb{R}^{n+1}.$$

(continued on next page)

Examples (continuation)

- This means that a vector field X along S^n is **tangential** to S^n if and only if $\langle \xi, X \rangle \equiv 0$. Note that the function f used to define S^n fulfils $f = \langle \xi, \xi \rangle$.
- Next consider Rⁿ⁺¹ but now equipped with a pseudo-Riemannian metric given in canonical coordinates by

$$\langle \cdot, \cdot
angle_{
u} := \sum_{i=1}^{n-
u} du^i \otimes du^i - \sum_{i=n-
u+1}^n du^i \otimes du^i.$$

Let $\xi \in \mathfrak{X}(\mathbb{R}^{n+1})$ denote the position vector field and define $f : \mathbb{R}^{n+1} \to \mathbb{R}$, $f := \langle \xi, \xi \rangle$. Then the level sets $\{f = -1\}$ are called **hyperboloids**,

$$H^n_
u := \left\{ \langle \xi, \xi
angle = \sum_{i=1}^{n-
u+1} \left(u^i
ight)^2 - \sum_{i=n-
u+2}^{n+1} \left(u^i
ight)^2 = -1
ight\} \subset \mathbb{R}^{n+1}.$$

Hyperboloids in $(\mathbb{R}^{n+1}, \langle \cdot, \cdot \rangle_{\nu})$ are *n*-dimensional ps.-R. manifolds with induced metric of index $\nu - 1$. (continued on next page)

Examples (continuation)

• As for S^n ,

$$T_{
ho}H^n_
u= \ker(\langle \xi_
ho,\cdot
angle_
u) \subset T_{
ho}\mathbb{R}^{n+1}$$

and

$$T_{\rho}H_{\nu}^{n\perp}=\mathbb{R}\xi_{\rho},$$

where $\mathbb{R}\xi_{\rho}$ is another commonly used notation for the linear span of **one** vector, that is $\operatorname{span}_{\mathbb{R}}\{\xi_{\rho}\}$. In the case $n = 3, \nu = 1, H_1^3$ is known as **two-sheeted hyperboloid**, and for $n = 3, \nu = 2, H_2^3$ is the **one-sheeted hyperboloid**.

END OF LECTURE 13

Next lecture:

- frames of vector bundles
- more subbundles
- Killing vector fields