

## SYMPLECTIC GEOMETRY

### Problem Set 6

1. Let  $(W, \xi)$  be a coorientable contact manifold, i.e. one which admits global contact forms. Prove that a contact vector field  $Y$  on  $W$  will be the Reeb vector field for some contact form  $\alpha$  defining  $\xi$  if and only if  $Y$  is everywhere transverse to  $\xi$ .
2. Let  $W \subseteq (M, \omega)$  be a regular level set of the function  $H : M \rightarrow \mathbb{R}$ . Assume that  $W$  is also a hypersurface of contact type, so there exists a vector field  $Y$  defined near  $W$  satisfying  $Y \lrcorner W$  and  $L_Y \omega = \omega$ . We have seen that  $\alpha = (\iota_Y \omega)|_W$  is a contact form on  $W$ . Prove the assertion made in class that the Reeb vector field of  $\alpha$  and the restriction of the Hamiltonian vector field  $X_H$  to  $W$  are proportional.
3. (*Legendrian submanifolds*) Let  $(W, \xi)$  be a contact manifold of dimension  $2n + 1$ .
  - a) Suppose  $S \subseteq W$  is a submanifold everywhere tangent to  $\xi$ . Prove that  $\dim S \leq n$ .  
*Note: If  $\dim S = n$ , then  $S$  is called a Legendrian submanifold of  $W$ .*
  - b) Prove that every Legendrian submanifold  $S \subseteq W$  has a neighborhood which is contactomorphic to a neighborhood of the zero section in  $(J^1 S, \ker(dz - \lambda_{\text{can}}))$  (which is obviously an example of a Legendrian submanifold).  
*Hint: Try to immitate the proof for Lagrangian submanifolds of symplectic manifolds. At some point Gray's stability theorem might be helpful.*
4. (*Legendrian knots*) We consider the standard contact structure  $\xi = \ker(dz - ydx)$  on  $\mathbb{R}^3$ .
  - a) Prove that every smooth curve  $\gamma : [0, 1] \rightarrow \mathbb{R}^2$ ,  $\gamma(t) = (x(t), y(t))$  admits a unique lift  $\tilde{\gamma} : [0, 1] \rightarrow \mathbb{R}^3$  which starts at  $\tilde{\gamma}(0) = (x(0), y(0), 0)$  and is tangent to  $\xi$ .
  - b) Which closed curves in the plane lift to closed curves in  $\mathbb{R}^3$ ?
  - c) Compute the lift of  $\gamma(t) = (\sin 2\pi t, \sin 4\pi t)$  explicitly and sketch its image in  $\mathbb{R}^3$ .