

# Linear perturbations of special spacetimes

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## Linear perturbations of the Kerr spacetime

- Black hole stability problem.
- Uniqueness problem.
- Self force problem.

## Methods and motivation

- Covariant geometric methods based on a conformal Killing-Yano tensor or Killing spinor.
- Don't have to care much about coordinates.
- Much works for a larger class than just Kerr. Vacuum Petrov type D or Kerr-NUT. (Focus on Kerr)
- The Killing spinor can be approximated on general backgrounds.

- Spinor notation, linearized curvature notation.
- Symmetries and structure of the Kerr black hole (Petrov type D)
- Gauge invariant quantities
- Hyperbolic evolution equations for some gauge invariants
- Symmetry operators. (briefly)
- Summary and concluding remarks

Will use abstract tensor notation and 2-spinor notation.

<b>Tensors</b>	<b>Spinors</b>
4D real bundles	2D complex bundles
$T_a$	$T_{AA'}$
$\nabla_a$	$\nabla_{AA'}$
Symmetric metric $g_{ab}$	Antisymmetric metric $\epsilon_{AB}$
Symmetric trace-free tensors	Symmetric spinors
Ricci scalar $R$	$24\Lambda$
Trace-free Ricci $S_{ab}$	$-2\Phi_{ABA'B'}$
Weyl tensor $C_{abcd}$	$\Psi_{ABCD}\bar{\epsilon}_{A'B'}\bar{\epsilon}_{C'D'} + \bar{\Psi}_{A'B'C'D'}\epsilon_{AB}\epsilon_{CD}$
Conformal Killing-Yano $Y_{ab} = Y_{[ab]}$ $\nabla_{(a}Y_{b)c} = \frac{1}{3}g_{c(a}\nabla^d Y_{b)d} - \frac{1}{3}g_{ab}\nabla_d Y_c{}^d.$	Killing spinor $\kappa_{AB} = \kappa_{(AB)}$ $\nabla_{A'(A}\kappa_{BC)} = 0$

Irreducible decompositions  $\Rightarrow$  Symmetric spinors times  $\epsilon \Rightarrow$  Use symmetric spinors.

Covariant metric perturbations around a background  $g_{ab}$  metric (vacuum)

$$\tilde{g}_{ab} = g_{ab} + \epsilon h_{ab} + \mathcal{O}(\epsilon^2)$$

- Linearized metric  $h_{ab}$ .
- Linearized Riemann in tensor form

$$\dot{R}_{abcd} = 2g_{f[d}\nabla_{c]}\nabla_{[a}h_{b]}{}^f + \frac{2}{3}R_{[ab]}{}^f{}_{[c}h_{d]f} - \frac{2}{3}R^f{}_{[ab][c}h_{d]f},$$

- Linearized Weyl, tracefree Ricci and Ricci scalar in spinor form

$$\begin{aligned}\vartheta\Psi_{ABCD} &= \frac{1}{2}\nabla_{(A}{}^{A'}\nabla_{B}{}^{B'}h_{CD)A'B'} - \frac{1}{4}\Psi_{ABCD}h^F{}_{F}{}^{A'}{}_{A'}, \\ \vartheta\Phi_{AB}{}^{A'B'} &= \frac{1}{2}\nabla^C{}^{(A'}\nabla_{(A}{}^{C'}|h_{B)CC'}{}^{B'}) + \frac{1}{2}\Psi_{AB}{}^{CD}h_{CD}{}^{A'B'}, \\ \vartheta\Lambda &= \frac{1}{12}\nabla_{CB'}\nabla^{(B}{}_{A'}h^C)_{B}{}^{A'B'}.\end{aligned}$$

## Vacuum Petrov type D

- A Petrov type D spacetime has two repeated principal spinors  $o_A, \iota_A$ , and we can write

$$\Psi_{ABCD} = \frac{1}{6} \Psi_2 o_{(A} o_B \iota_C \iota_{D)}.$$

- (Walker & Penrose 1970) Vacuum type D  $\Rightarrow$  existence of a Killing spinor  $\kappa_{AB}$ ,  $\nabla_{A'(A} \kappa_{BC)} = 0$   
or a conformal Killing-Yano tensor  $Y_{ab}$ ,  $\nabla_{(a} Y_{b)c} = \frac{1}{3} g_{c(a} \nabla^d Y_{b)d} - \frac{1}{3} g_{ab} \nabla_d Y_c^d$ .
- Will study such spacetimes (or more special) and build all structures from  $\kappa_{AB}$  or  $Y_{ab}$ .

## Vacuum Petrov type D

Let  $\mathcal{Y}_{ab} = \frac{1}{2}(Y_{ab} + i*Y_{ab})$  be anti-self dual conformal Killing-Yano tensor related to the Killing spinor  $\kappa_{AB}$  via

$$\mathcal{Y}_{ab} = \frac{3}{2}i\bar{\epsilon}_{A'B'}\kappa_{AB}, \quad \text{and let} \quad \rho = \sqrt{\mathcal{Y}_{bd}\mathcal{Y}^{bd}}.$$

From the 2-form  $\mathcal{Y}_{ab}$ , we can construct a Killing vector

$$\xi^c = \frac{2}{3}i\nabla_a\mathcal{Y}^{ca} = \nabla^{BC'}\kappa^C_B.$$

If  $\xi^c$  is real, we can also construct

- a Killing tensor  $K_{ab} = -Y_a{}^c Y_{bc}$ ,  $\nabla_{(a}K_{bc)} = 0$ .
- a second Killing vector

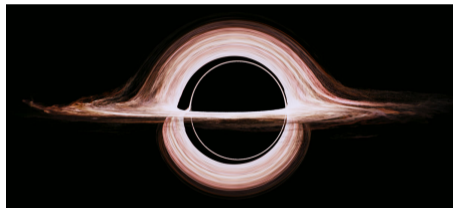
$$\zeta^a = K^{ab}\xi_b = 2\mathcal{Y}^{ab}\bar{\mathcal{Y}}_{bc}\xi^c - \frac{1}{4}(\rho^2 + \bar{\rho}^2)\xi^a.$$

## The Kerr metric

$$g_{ab} = -\frac{(a^2 \sin^2 \theta - \Delta) dt_a dt_b}{\Sigma} - \frac{\Sigma dr_a dr_b}{\Delta} - \Sigma d\theta_a d\theta_b$$
$$+ \frac{\sin^2 \theta (a^2 \sin^2 \theta \Delta - (a^2 + r^2)^2) d\phi_a d\phi_b}{\Sigma}$$
$$+ \frac{2a \sin^2 \theta (a^2 + r^2 - \Delta) dt_{(a} d\phi_{b)}}{\Sigma},$$

where  $\Delta = a^2 - 2Mr + r^2$  and  $\Sigma = a^2 \cos^2 \theta + r^2$ .

- Vacuum Petrov type D spacetime describing a rotating black hole.
- $M$  is mass and  $a$  angular momentum parameter with  $|a| \leq M$ .
- Will not use coordinate formulation.





## Kerr

- We can normalize the Killing spinor so that  $\xi^a$  is the real Killing vector  $(\partial_t)^a$ .
- $p = r - ia \cos \theta$  in B-L coordinates.
- $\Psi_2 p^3 = \bar{\Psi}_2 \bar{p}^3 = -M$ .
- $\zeta^a = a^2 (\partial_t)^a + a (\partial_\phi)^a$ . (Vanish for Schwarzschild)
- Rotating case: **Killing spinor**  $\Rightarrow$  All symmetries  $(\partial_t, \partial_\phi$  and  $K_{ab})$ .
- Geodesic equation integrable. (Carter constant.  $Q = \dot{\gamma}^a \dot{\gamma}^b K_{ab}$ )
- The **Killing spinor** can also be used for characterization of Kerr.
- Use covariant **Killing spinor** instead of coordinates for calculations.

Focus on Kerr but many results are valid for larger classes of spacetimes (Kerr-NUT).

- $\mathcal{K}$  operators:

$$(\mathcal{K}_{k,l}^0 \varphi)_{A_1 \dots A_{k+2}} = -6p^{-1} \kappa_{(A_1 A_2} \varphi_{A_3 \dots A_{k+2})} \quad \text{"spin raising"}$$

$$(\mathcal{K}_{k,l}^1 \varphi)_{A_1 \dots A_k} = -3p^{-1} \kappa_{(A_1}{}^B \varphi_{A_2 \dots A_k)B} \quad \text{"sign flip"}$$

$$(\mathcal{K}_{k,l}^2 \varphi)_{A_1 \dots A_{k-2}} = \frac{3}{2} p^{-1} \kappa^{CD} \varphi_{A_1 \dots A_{k-2} CD} \quad \text{"spin lowering"}$$

The spin-0, spin-1 and spin-2 parts of the linearized curvature can be expressed by

$$\begin{aligned} \vartheta \Psi_2 &= \mathcal{K}_{2,0}^2 \mathcal{K}_{4,0}^2 \vartheta \Psi \\ &= (\dot{R}_b{}^d{}_{cd} \mathcal{Y}_a{}^c - \dot{R}_{abcd} \mathcal{Y}^{cd} - \dot{R}_{acbd} \mathcal{Y}^{cd}) \mathcal{Y}^{ab} p^{-2} / 6, \end{aligned}$$

$$\begin{aligned} \mathcal{Z}_{ab} &= (\mathcal{K}_{2,0}^1 \mathcal{K}_{4,0}^2 \vartheta \Psi)_{AB} \bar{\epsilon}_{A'B'} \\ &= (-2 \mathcal{Y}^{cd} \dot{R}_{[a|cd|}{}^f \mathcal{Y}_{b]f} + 3 \mathcal{Y}^{cd} \dot{R}_{[a}{}^f{}_{|cd|} \mathcal{Y}_{b]f}) p^{-2} / 4, \end{aligned}$$

$$\mathcal{W}_{abcd} = ((\mathcal{K}_{4,0}^1 \mathcal{K}_{4,0}^1 \mathcal{K}_{4,0}^1 \mathcal{K}_{4,0}^1 - \frac{1}{16} \mathcal{K}_{2,0}^0 \mathcal{K}_{2,0}^1 \mathcal{K}_{2,0}^1 \mathcal{K}_{4,0}^2) \vartheta \Psi)_{ABCD} \bar{\epsilon}_{A'B'} \bar{\epsilon}_{C'D'}.$$

In any principal tetrad  $(l^a, n^a, m^a, \bar{m}^a)$  (aligned with principal directions of Weyl):

$$\vartheta\Psi_0 = \dot{R}_{lmlm},$$

$$\vartheta\Psi_1 = \frac{1}{2}\dot{R}_{lmln} - \frac{1}{2}\dot{R}_{lmm\bar{m}},$$

$$\vartheta\Psi_2 = \frac{1}{6}\dot{R}_{lnln} - \frac{1}{3}\dot{R}_{lnm\bar{m}} + \frac{1}{3}\dot{R}_{lm\bar{m}n} + \frac{1}{6}\dot{R}_{m\bar{m}mm\bar{m}},$$

$$\vartheta\Psi_3 = \frac{1}{2}\dot{R}_{ln\bar{m}n} - \frac{1}{2}\dot{R}_{m\bar{m}\bar{m}n},$$

$$\vartheta\Psi_4 = \dot{R}_{\bar{m}n\bar{m}n},$$

$$\mathcal{Y}_{ab} = ip(l_{[a}n_{b]} - m_{[a}\bar{m}_{b]}),$$

$$\mathcal{Z}_{ab} = 2\vartheta\Psi_1\bar{m}_{[a}n_{b]} - 2\vartheta\Psi_3l_{[a}m_{b]},$$

$$\mathcal{W}_{abcd} = 4\vartheta\Psi_0\bar{m}_{[a}n_{b]}\bar{m}_{[c}n_{d]} + 4\vartheta\Psi_4l_{[a}m_{b]}l_{[c}m_{d]}.$$

Observe that we don't formally need a frame.

Observe that  $\mathcal{W}_{abcd}$  only contains  $\vartheta\Psi_0, \vartheta\Psi_4$  called the Teukolsky variables.

# Applications of symmetries to linearized gravity

With the help of the Killing spinor we can describe

- **All local gauge invariant quantities** from the Killing spinor and lin. curvature.
- **Field equations for gauge invariants.** Several possibilities:
  - Teukolsky master equations (TME)
  - Teukolsky Starobinsky identities (TSI)

Both can be seen as hyperbolic.

- **Symmetry operators.**
- **Conservation laws.** (Not today.)

## Benefits

- Coordinate free description.
- Characterization of Kerr in terms of Killing spinor.
- Killing spinor can be approximated on general backgrounds  
⇒ approximation for all structures.

- Only **gauge invariant** quantities carries physically relevant information.

## Gauge invariance

- Quantities invariant under linearized diffeomorphisms  $h_{ab} = \mathcal{L}_\nu g_{ab}$  for some  $\nu^a$  are called (local) gauge invariant. (Linear differential operators)
- The Teukolsky scalars  $\vartheta\Psi_0$  and  $\vartheta\Psi_4$  (components of lin. Weyl) are gauge invariant.

## Generators

- Any linear differential operator applied to a gauge invariant is also gauge invariant.
- A set of gauge invariants is **generating** if all gauge invariants can be expressed as a linear combinations of differential operators on elements of this set.
- New result: A minimal generating set of gauge invariant quantities for linearized gravity on Kerr.

$$\rho = \sqrt{\mathcal{Y}_{bd}\mathcal{Y}^{bd}} = r - ia\cos\theta,$$

$$U_a = -\nabla_a \log(\rho).$$

## Proposition

Let  $V^a$  be a real Killing vector field and

$$\mathbb{I}_V = \rho^2 W^a \nabla_a (\rho^4 \vartheta \Psi_2) - \frac{1}{2} \text{Re}(\rho^6 \vartheta \Psi_2 \nabla_a W^a) - 2i \text{Im}(\rho^6 U^a W^b \mathcal{Z}_{ab}) - \frac{3}{2} \rho^6 \Psi_2 U^a W^b h_{ab}$$

where the vector field  $W_a \equiv 2ip^{-3} V^b \mathcal{Y}_{ab}$  is assumed to satisfy the condition

$$\bar{\rho}^3 \bar{U}_{[a} \bar{W}_{b]} = -\rho^3 U_{[a} W_{b]}. \quad (1)$$

Then  $\mathbb{I}_V$  is a local gauge invariant.

On Kerr:  $\xi^a$  and  $\zeta^a$  satisfies (1)  $\Rightarrow \mathbb{I}_\xi, \mathbb{I}_\zeta$  are gauge invariants.

# All gauge invariant for perturbations of Kerr

## Corollary

*A set of local gauge invariant quantities for perturbations of the Kerr spacetime is given by the 18 components*

$$\text{Teukolsky scalars} \quad \vartheta\Psi_0, \vartheta\Psi_4, \quad (\text{Second order}) \quad (2a)$$

$$\text{Linearized Ricci} \quad \dot{R}_{ab} = \dot{R}_{acb}{}^c, \quad (\text{Second order}) \quad (2b)$$

$$\text{Killing invariants} \quad \mathbb{I}_\xi, \mathbb{I}_\zeta. \quad (\text{Third order}) \quad (2c)$$

## Complete description

The set of gauge invariants above is minimal and generates all local gauge invariants for perturbations of the Kerr spacetime with  $a \neq 0$ .

Minkowski: All 20 components of the linearized curvature tensor.

## Information carried by $\mathbb{I}_\xi, \mathbb{I}_\zeta$

$\vartheta\Psi_0 = 0, \vartheta\Psi_4 = 0, \dot{R}_{ab} = 0, \Rightarrow$  Linearized vacuum type D with parameters  $M, N, a, c$   
(mass, NUT charge, angular momentum and c-metric)

- $\dot{M}, \dot{a}$  perturbations

$$\mathbb{I}_\xi = \dot{M},$$

$$\mathbb{I}_\zeta = 2a^2\dot{M} - 3Ma\dot{a},$$

- $\dot{N}$  perturbations with  $x = \cos\theta$

$$\mathbb{I}_\xi = -i\dot{N} + \frac{2iM}{\bar{p}}\dot{N},$$

$$\mathbb{I}_\zeta = -ia^2\dot{N} + ax(r - 2M - \frac{Mp}{\bar{p}})\dot{N},$$

- $\dot{c}$  perturbations

$$\mathbb{I}_\xi = \frac{6M^2rx}{\bar{p}}\dot{c} + 3M(ia + (M - r)x)\dot{c}, \quad \mathbb{I}_\zeta = \frac{6M^2a^2rx^3}{\bar{p}}\dot{c} - 3iMa(p^2 - r^2x^2)\dot{c}.$$

- Important to control  $\dot{M}$  and  $\dot{a}$  modes for self-force problems and stability problems.



## Differential relations

- The gauge invariants satisfy differential equations.
- Minkowski: Linearized Bianchi.
- Kerr: Linearized Bianchi gives compatibility conditions between the gauge invariants.
- Important for the proof that the set generates all gauge invariants. (Not in this talk)

## Hyperbolic evolution equations for lin. vacuum $\dot{R}_{ab} = 0$ .

- Linearized Bianchi not always practical for estimates.
- Standard method: Apply another derivative to get wave equations for curvature components.
- This gives Teukolsky equations (TME) for  $\vartheta\Psi_0, \vartheta\Psi_4$  (wave eqs) on Kerr.
- Can also get other equations: Teukolsky-Starobinsky identities (TSI) relating  $\vartheta\Psi_0$  and  $\vartheta\Psi_4$ . (Also hyperbolic)
- Evolution equations involving  $\mathbb{I}_\xi, \mathbb{I}_\zeta$  under investigation.

# Teukolsky (TME) and Teukolsky-Starobinsky (TSI)

Classical view

Field equations  $\Rightarrow$  decoupled, separable *integrability conditions*

- Teukolsky Master Equations (TME):

$$\left[ \frac{(r^2 + a^2)^2}{\Delta} - a^2 \sin^2 \theta \right] \frac{\partial^2 \psi}{\partial t^2} + \frac{4Mar}{\Delta} \frac{\partial^2 \psi}{\partial t \partial \varphi} + \left[ \frac{a^2}{\Delta} - \frac{1}{\sin^2 \theta} \right] \frac{\partial^2 \psi}{\partial \varphi^2} - \Delta^{-s} \frac{\partial}{\partial r} \left( \Delta^{s+1} \frac{\partial \psi}{\partial r} \right) - \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial \psi}{\partial \theta} \right) - 2s \left[ \frac{a(r-M)}{\Delta} + \frac{i \cos \theta}{\sin^2 \theta} \right] \frac{\partial \psi}{\partial \varphi} - 2s \left[ \frac{M(r^2 - a^2)}{\Delta} - r - ia \cos \theta \right] \frac{\partial \psi}{\partial t} + (s^2 \cot^2 \theta - s) \psi = 4\pi \Sigma T.$$

- Teukolsky-Starobinsky Identities (TSI):  $\psi = e^{-i\omega t} e^{im\phi} S(\theta) R(r)$

$$\mathcal{L}_{-1} \mathcal{L}_0 \mathcal{L}_1 \mathcal{L}_2 S_2 + 12Mi\omega S_2^\dagger = S_{-2},$$

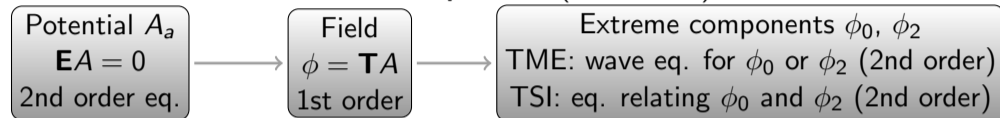
$$\mathcal{D} \mathcal{D} \mathcal{D} \mathcal{D} R_{-2} = \frac{1}{4} R_2.$$

(Properties of confluent Heun functions.)

# Teukolsky (TME) and Teukolsky-Starobinsky (TSI)

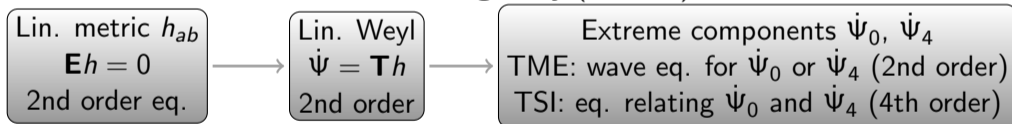
Modern view 1

## Maxwell equations (source free)



TME=Teukolsky Master Equations, TSI=Teukolsky–Starobinsky Identities

## Linearized gravity (vacuum)



- Extreme components: **gauge invariant** and carry dynamical degrees of freedom.
- TME often used (gravitational waves), but TSI also carries important information.
- Not all solutions to TME correspond to solutions of linearized gravity.

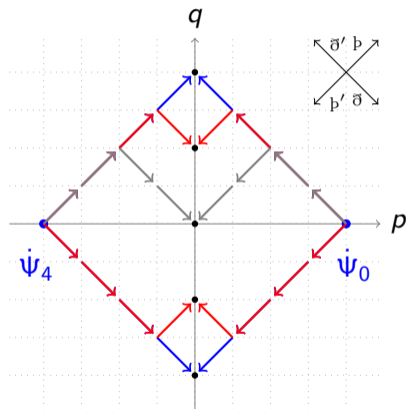
# Teukolsky (TME) and Teukolsky-Starobinsky (TSI)

Modern view 2

- The TME is decoupled set of two hyperbolic (weighted) scalar wave equations (TME).

## Completing TSI to a hyperbolic system

- One can formulate TSI as a set of two coupled differential equations.  
(Derivatives of linearized Bianchi.)
- TSI can be completed to "full TSI" with 5 equations (3 for Maxwell).
- **Remarkable:** Full TSI gives a first order symmetric hyperbolic system.
- Alternative to TME evolution.



# Symmetric hyperbolic systems

## First order symmetric hyperbolic systems

Any equation of the form

$$\nabla^A{}_{A'}\phi_{\dots A\dots} = \varphi_{\dots A'\dots} \quad \text{or} \quad \nabla_A{}^{A'}\phi_{\dots A'\dots} = \varphi_{\dots A\dots}$$

gives a *first order symmetric hyperbolic system*.

## Maxwell

Let  $\phi_{AB}$  be a Maxwell field, and  $\kappa_{AB}$  the Killing spinor ( $p^2 = -\frac{9}{2}\kappa_{AB}\kappa^{AB}$ ). Define

$$\varphi_{AB} = -\frac{1}{3}p\kappa_{(A}{}^C\phi_{B)C}, \quad \psi_{AA'} = -p^2\nabla_{BA'}(p^{-2}\varphi)_{A}{}^B.$$

The TME and full TSI for Maxwell can be written as

$$\nabla_{(A}{}^{A'}\psi_{B)A'} = 0, \quad \nabla^A{}_{(A'}\psi_{|A|B')} = 0.$$

2 TME equations, 3 TSI equations (cf Coll et. al.)

# Symmetric hyperbolic systems

Maxwell TME and TSI

Use the commutator  $\nabla^{AA'}\psi_{AA'} = -2U^{AA'}\psi_{AA'}$ , with  $U_{AA'} = -\nabla_{AA'}\log(\rho)$  to write

First order symmetric hyperbolic system for the Maxwell TME

$$\begin{aligned}\nabla^B{}_{A'}\varphi_{AB} &= -2U^B{}_{A'}\varphi_{AB} + \psi_{AA'}, \\ \nabla_A{}^{A'}\psi_{BA'} &= \epsilon_{AB}U^{CA'}\psi_{CA'},\end{aligned}$$

First order symmetric hyperbolic system for the Maxwell TSI

$$\begin{aligned}\nabla^B{}_{A'}\varphi_{AB} &= -2U^B{}_{A'}\varphi_{AB} + \psi_{AA'}, \\ \nabla^A{}_{A'}\psi_{AB'} &= U^{AC'}\bar{\epsilon}_{A'B'}\psi_{AC'}.\end{aligned}$$

### New view

- Also TSI is a hyperbolic evolution system.
- Same variables for TME and TSI.
- Given an initial data surface with normal  $n^{AA'}$  the difference

$$0 = -n^D{}_{A'} \nabla_{DB'} \psi_A{}^{B'} + n_A{}^{B'} \nabla_{DB'} \psi^D{}_{A'}.$$

is a constraint for the initial data. (Spatial derivative.)

- TSI as constraint under TME evolution. (Propagates)
- TME as constraint under TSI evolution. (Propagates)

# Symmetric hyperbolic systems

## Linearized gravity

### First order symmetric hyperbolic system for linearized gravity TSI

- Have a system.

$$\nabla^A{}_{A'} \begin{bmatrix} \varphi_{ABCD} \\ \psi_{ABCB'} \\ \chi_{ABB'C'} \\ \eta_{AB'C'D'} \\ \alpha_{AB'} \\ \beta_{AB} \end{bmatrix} = \dots$$

- Involves Teukolsky scalars and another gauge invariant ( $\alpha_{AA'}$ ).

### First order symmetric hyperbolic system for linearized gravity TME

- TME implies another hyperbolic system in *the same variables*.
- TME as constraint for TSI and vice versa under investigation.



# Symmetry operators

## Definition

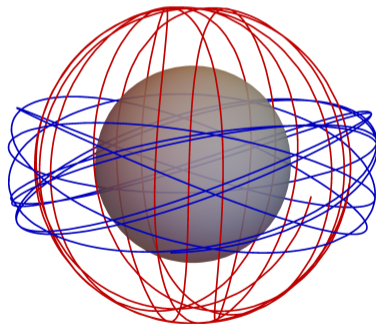
A *symmetry operator* is a linear differential operator that maps a solution of a differential equation to a solution.

## Examples

- Lie derivatives along (conformal) Killing vectors for wave eq in Minkowski.

## Motivation for symmetry operators

- Explains separability and integrability.
- Useful for energy estimates:
  - Sobolev norms with symmetry operators instead of partial derivatives.
  - Higher order conservation laws.
  - Morawetz estimates near orbiting null geodesics for rotating black holes. (Andersson, Blue)



## Symmetries on the Kerr spacetime

- Classical symmetry operators: Lie derivatives along Killing vectors ( $\partial_t$  and  $\partial_\varphi$ ).
- Hidden symmetry operator for scalar wave equation:  
 $\nabla_a K^{ab} \nabla_b$  (Carter) where is the Killing tensor  $K^{ab}$ ,  $\nabla_{(a} K_{bc)} = 0$ .
- Use **Killing spinor** to derive symmetry operators for Maxwell and lin. gravity.

# Symmetry operators from operator identities

## Operator identities

- So far: TME and TSI in the source-free case (lin. vacuum).
- Include source terms (lin. Einstein)  $\Rightarrow$  operator identities relating lin. Weyl components with lin. Einstein components. (cf Bianchi).
- Identity: **SE = OT**
- **E** linearized Einstein.
- **T** :  $h_{ab} \mapsto \vartheta \Psi_{ABCD}$ .
- **O** TME or TSI.

## Symmetry operators from TME and TSI (Maxwell and lin. gravity)

- Wald 1978: TME operator identity  $\Rightarrow$  symmetry operator.
- We: Also TSI operator identity  $\Rightarrow$  symmetry operator.

# Adjoint operator method

## Idea (Wald 1978)

Use adjoint operator method to produce solutions of Maxwell or linearized gravity from solutions of TME. (Leads to symmetry operator.)

For any linear partial differential operator  $\mathbf{A}$ , define

- $\mathbf{A}^\dagger$  adjoint w.r.t.  $(\phi, \psi) = \int \phi \psi d\mu$ , i.e.  $(\mathbf{A}^\dagger \phi, \varphi) = (\phi, \mathbf{A}\varphi)$ .
- $\mathbf{A}^*$  adjoint w.r.t.  $\langle \phi, \psi \rangle = \int \phi \bar{\psi} d\mu$ , i.e.  $\langle \mathbf{A}^* \phi, \varphi \rangle = \langle \phi, \mathbf{A}\varphi \rangle$ .

## Theorem

*Suppose the identity*

$$\mathbf{S}\mathbf{E} = \mathbf{O}\mathbf{T}$$

*holds for linear partial differential operators  $\mathbf{S}$ ,  $\mathbf{E}$ ,  $\mathbf{O}$  and  $\mathbf{T}$ .*

*Suppose  $\psi$  satisfies  $\mathbf{O}^\dagger \psi = 0$ . Then  $\mathbf{S}^\dagger \psi$  satisfies  $\mathbf{E}^\dagger (\mathbf{S}^\dagger \psi) = 0$ .*

*In particular, if  $\mathbf{E}$  is self-adjoint then  $\mathbf{E}\mathbf{S}^\dagger \psi = 0$ . (Also works with  $\star$ -adjoint.)*

**Proof:**  $\mathbf{E}^\dagger \mathbf{S}^\dagger = \mathbf{T}^\dagger \mathbf{O}^\dagger$ .

# Linearized gravity

## TME and a 4th order symmetry operator

### General

- Linearized Einstein operator  $\mathbf{E}$  (2nd order).  $\mathbf{E}^\dagger = \mathbf{E}^* = \mathbf{E}$ .
- Linearized Weyl operator  $\mathbf{T} : h \mapsto \vartheta\Psi$  (2nd order).

### TME and a 4th order symmetry operator

- TME equation  $\mathbf{O}\vartheta\Psi = 0$  (2nd order) involves only  $\vartheta\Psi_0$  and  $\vartheta\Psi_4$ . ( $\mathbf{O}^\dagger = \mathbf{O}$ )
- The identity  $\mathbf{S}\mathbf{E} = \mathbf{O}\mathbf{T}$  holds for a 2nd order  $\mathbf{S}$ .
- $\mathbf{S}^\dagger\vartheta\Psi$  is a **new complex solution to the linearized gravity**.
- Symmetry operator  $\mathbf{S}^\dagger\mathbf{T}$  from metric to metric is **4th order**.
- We have explicit expressions in a new powerful covariant operator formalism involving **only** covariant derivatives and the Killing spinor.

# Linearized gravity

## TSI and a 6th order symmetry operator

### Recall

- Linearized Einstein operator  $\mathbf{E}$  (2nd order).  $\mathbf{E}^\dagger = \mathbf{E}^* = \mathbf{E}$ .
- Linearized Weyl operator  $\mathbf{T} : h \mapsto \vartheta\Psi$  (2nd order).

### TSI and a 6th order symmetry operator (Aksteiner & Bäckdahl 2016)

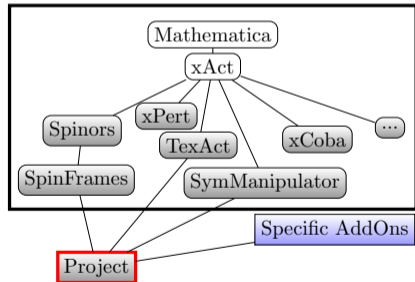
- TSI equation  $\widehat{\mathbf{O}}\vartheta\Psi - \widehat{\mathbf{L}}\overline{\vartheta\Psi} = 0$  involves only  $\vartheta\Psi_0$  and  $\vartheta\Psi_4$ .
- $\widehat{\mathbf{O}}^* = \widehat{\mathbf{O}}$  is 4th order, and  $\widehat{\mathbf{L}}^\dagger = \widehat{\mathbf{L}}$  is 1st order (Lie derivative).
- The identity  $\widehat{\mathbf{S}}\mathbf{E} = \widehat{\mathbf{O}}\mathbf{T} - \widehat{\mathbf{L}}\overline{\mathbf{T}}$  holds for a 4th order  $\widehat{\mathbf{S}}$ .
- $\mathbf{E}(\widehat{\mathbf{S}}^*\vartheta\Psi + \overline{\widehat{\mathbf{S}}^*\vartheta\Psi}) = \mathbf{T}^*(\widehat{\mathbf{O}}\vartheta\Psi - \widehat{\mathbf{L}}\overline{\vartheta\Psi}) + \overline{\mathbf{T}}^*(\overline{\widehat{\mathbf{O}}\vartheta\Psi} - \widehat{\mathbf{L}}\vartheta\Psi)$
- $\hat{k}_{ABA'B'} = (\widehat{\mathbf{S}}^*\vartheta\Psi)_{ABA'B'} + \overline{(\widehat{\mathbf{S}}^*\vartheta\Psi)_{ABA'B'}}$  is a **real solution to linearized gravity**
- The symmetry operator for linearized gravity (from metric to metric) is **6th order**.

# Symbolic calculations with xAct

Efficient tensor/spinor computer algebra for Mathematica

Calculations leading to the results just presented were performed with xAct.  
Based on the Killing spinor  $\rightarrow$  coordinate free calculations.

- Open source, [www.xAct.es](http://www.xAct.es)
- Powerful algorithms to handle and use symmetries of tensors and spinors
- All operators of this talk are implemented
- xAct Packages: *SymManipulator*, *SpinFrames*, *TexAct*
  - Irreducible decompositions
  - Fundamental spinor operators
  - NP and GHP formalisms
  - Structured Tex output



- All gauge invariant quantities for linearized gravity on Kerr.
- New view on the Teukolsky-Starobinsky Identities (TSI).
- TSI  $\Rightarrow$  **hyperbolic evolution system**.
- Both TME and TSI generate symmetry operators.
- For linearized gravity we get a 4th order symmetry operator (known), and a **new** 6th order symmetry operator.
- Covariant techniques and efficient formalisms  $\Rightarrow$  new insights.
- Robust operator formulation could work for "almost Kerr" backgrounds.

**Thank you!**