

Let  $H_k$  be the linear space of vec. fields whose coefficients are homogeneous polyn. of degree  $k$ , i.e.

$$H_k = \left\{ \begin{pmatrix} P_1 \\ P_2 \\ \vdots \\ P_N \end{pmatrix} : \begin{array}{l} P_i \text{ is a homog. polyn. of degree } k \text{ in } (x_1, \dots, x_N) \\ \text{i.e. } P_i \text{ is a lin. comb. of monomials of deg. } k. \end{array} \right\}$$

Let  $L = Df(0) \cdot x$ , the linear part of " $x' = f(x), f(0) = 0$ ".

Define a linear operator on  $H_k$  using  $L$ :

$$\text{ad } L : H_k \longrightarrow H_k$$

$$Y \longmapsto [Y, L] = DLY - DY L.$$

↑ Lie Bracket

(part I)

Example 2.3.2 Let  $Df(0) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ . then  $L = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -y \\ x \end{pmatrix}$ .

Consider  $H_2 = \left\{ \begin{pmatrix} P_1 \\ P_2 \end{pmatrix} : P_i = P_i(x, y) = a_i x^2 + b_i xy + c_i y^2, \quad i=1,2, \quad a_i, b_i, c_i \in \mathbb{R} \right\} \cong \mathbb{R}^6$ , a 6-dim

real vector space spanned by  $\begin{pmatrix} x^2 \\ 0 \end{pmatrix}, \begin{pmatrix} xy \\ 0 \end{pmatrix}, \begin{pmatrix} y^2 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ x^2 \end{pmatrix}, \begin{pmatrix} 0 \\ xy \end{pmatrix}, \begin{pmatrix} 0 \\ y^2 \end{pmatrix}$ .

write as

$$\begin{matrix} \parallel & \parallel & \parallel & \parallel & \parallel & \parallel \\ x^2 \frac{\partial}{\partial x} & xy \frac{\partial}{\partial x} & y^2 \frac{\partial}{\partial x} & x^2 \frac{\partial}{\partial y} & xy \frac{\partial}{\partial y} & y^2 \frac{\partial}{\partial y} \end{matrix}$$

$$\text{ad } L \left( x^2 \frac{\partial}{\partial x} \right) = \text{ad } L \begin{pmatrix} x^2 \\ 0 \end{pmatrix} = \underbrace{\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x^2 \\ 0 \end{pmatrix}}_{DL} - \underbrace{\begin{pmatrix} 2x & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}}_{DY} = \begin{pmatrix} 2xy \\ x^2 \end{pmatrix} = 2xy \frac{\partial}{\partial x} + x^2 \frac{\partial}{\partial y}$$

$$\text{ad } L = 6 \times 6 \text{-matrix} = \begin{matrix} & x^2 \frac{\partial}{\partial x} & xy \frac{\partial}{\partial x} & y^2 \frac{\partial}{\partial x} & x^2 \frac{\partial}{\partial y} & xy \frac{\partial}{\partial y} & y^2 \frac{\partial}{\partial y} \\ \begin{matrix} x^2 \frac{\partial}{\partial x} \\ xy \frac{\partial}{\partial x} \\ y^2 \frac{\partial}{\partial x} \\ x^2 \frac{\partial}{\partial y} \\ xy \frac{\partial}{\partial y} \\ y^2 \frac{\partial}{\partial y} \end{matrix} & \begin{pmatrix} 0 & -1 & 0 & -1 & 0 & 0 \\ 2 & 0 & -2 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 2 & 0 & -2 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{pmatrix} \end{matrix}$$

Theorem 2.3.3 Let  $\dot{x} = f(x)$  be a  $C^r$ -system of diff. equations with  $f(0) = 0$  and  $Df(0)x = L$ . Let  $G_k$  be a complement for the range  $\text{ad}L(H_k)$  of  $\text{ad}L$  in  $H_k$ , i.e.  $H_k = \text{ad}L(H_k) + G_k$ . Then,

$\exists$  an analytic change of coord. s.t.  $\dot{x} = f(x)$  is transformed to  
in a nbhd of 0

$$\dot{y} = g(y) = g^{(1)}(y) + g^{(2)}(y) + \dots + g^{(r)}(y) + R_r$$

where  $L = g^{(1)}$ ,  $g^{(k)} \in G_k$  for  $2 \leq k \leq r$  and  $R_r = o(|y|^r)$

*pf: (sketch)*, By induction, assume  $\dot{x} = f(x)$  is transformed s.t.

$$\dot{x} = f^{(1)}(x) + f^{(2)}(x) + \dots + f^{(s)}(x) + R, \quad L = f^{(1)}, \text{ and } f^{(k)} \in G_k \quad \forall 2 \leq k < s$$

Let  $x = y + P(y)$  with  $P$  being a homog. polyn. of degree  $s$ . Then

$$(I + DP(y))\dot{y} = f^{(1)}(y) + f^{(2)}(y) + \dots + f^{(s)}(y) + Df(0)P(y) + o(|y|^s)$$

$$\begin{aligned} \uparrow \\ \dot{x} = (I + DP(y))\dot{y} &= f^{(1)}(x) + \dots + f^{(s)}(x) + R = f^{(1)}(y + P(y)) + \dots + f^{(s)}(y + P(y)) + R \\ &= f^{(1)}(y) + \dots + f^{(s)}(y) + Df(0)P(y) + R' \end{aligned}$$

$$(I + DP)^{-1} \approx I - DP$$

$$\xrightarrow{\quad} \dot{y} = f^{(1)}(y) + \dots + f^{(s)}(y) + \underbrace{Df(0)P(y)}_{=DL} - \underbrace{DP(y)f^{(1)}(y)}_{=L} + o(|y|^s)$$

i.e. the term of degree  $s$  is

$$f^{(s)}(y) + DL P(y) - DP(y)L = f^{(s)}(y) + \text{ad}L(P)(y)$$

choose  $P$  s.t. the above lies in  $G_s$ .

□

Example 2.3.2. (part II) Consider the system

$$\begin{cases} \dot{x} = -y + o(|x|, |y|) \\ \dot{y} = x + o(|x|, |y|) \end{cases} \quad \text{or} \quad \dot{x} = f(x) \quad \text{with} \quad f(0) = 0, \quad Df(0) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

and we derive the normal form for it:

Let  $L = Df(0) \begin{pmatrix} x \\ y \end{pmatrix}$  and  $\text{ad}L : H_k \rightarrow H_k$  as defined above.

$k=2$ : as calculated in Example 2.3.2 (part I),  $\text{ad}L : H_2 \rightarrow H_2$  is given by a  $6 \times 6$ -matrix, which is nonsingular, thus  $G_2 = \{0\}$ . By Theorem 2.3.3, all degree-2 terms can be removed from  $f$  by change of coord.

$k=3$ : Similar calculation shows:

$$\text{ad}L = \begin{array}{c} \begin{array}{cccc|cccc} x^3 \frac{\partial}{\partial x} & x^2 y \frac{\partial}{\partial x} & xy^2 \frac{\partial}{\partial x} & y^3 \frac{\partial}{\partial x} & x^3 \frac{\partial}{\partial y} & x^2 y \frac{\partial}{\partial y} & xy^2 \frac{\partial}{\partial y} & y^3 \frac{\partial}{\partial y} \\ \hline x^3 \frac{\partial}{\partial x} & 0 & -1 & 0 & 0 & -1 & 0 & 0 & 0 \\ x^2 y \frac{\partial}{\partial x} & 3 & 0 & -2 & 0 & 0 & -1 & 0 & 0 \\ xy^2 \frac{\partial}{\partial x} & 0 & 2 & 0 & -3 & 0 & 0 & -1 & 0 \\ y^3 \frac{\partial}{\partial x} & 0 & 0 & 1 & 0 & 0 & 0 & 0 & -1 \\ \hline x^3 \frac{\partial}{\partial y} & 1 & 0 & 0 & 0 & 0 & -1 & 0 & 0 \\ x^2 y \frac{\partial}{\partial y} & 0 & 1 & 0 & 0 & 3 & 0 & -2 & 0 \\ xy^2 \frac{\partial}{\partial y} & 0 & 0 & 1 & 0 & 0 & 2 & 0 & -3 \\ y^3 \frac{\partial}{\partial y} & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \end{array} \end{array}$$

is singular with 2-dimensional kernel.  $\Rightarrow G_3 \cong \mathbb{R}^2$ , choices of  $G_3$ :

Choice 1:  $G_3 = \ker(\text{ad}L) = \langle v_1, v_2 \rangle = \left\langle \begin{pmatrix} 3 \\ 0 \\ 1 \\ 0 \\ 0 \\ 1 \\ 0 \\ 3 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \\ 3 \\ 0 \\ 0 \\ -1 \\ 0 \end{pmatrix} \right\rangle$ ,  $v_1, v_2$  eigenvectors of 0.

Then,  $G_3 = \left\{ a(3x^2 \frac{\partial}{\partial x} + xy^2 \frac{\partial}{\partial x} + x^2 y \frac{\partial}{\partial y} + 3y^3 \frac{\partial}{\partial y}) + b(xy^2 \frac{\partial}{\partial x} + 3y^3 \frac{\partial}{\partial x} - 3x^3 \frac{\partial}{\partial y} - xy^2 \frac{\partial}{\partial y}) : a, b \in \mathbb{R} \right\}$

$$= \left\{ \begin{pmatrix} a(3x^3 + xy^2) + b(x^2y + 3y^3) \\ a(x^2y + 3y^3) + b(-3x^3 - xy^2) \end{pmatrix} : a, b \in \mathbb{R} \right\}$$

Choice 2:  $G_3 = \left\langle \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 0 \\ 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ -1 \\ 0 \\ -1 \\ 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \right\rangle$  is also a complement of  $\text{adL}(H_3)$ , then

$$G_3 = \left\{ a(x^3 \frac{\partial}{\partial x} + xy^2 \frac{\partial}{\partial x} + x^2 y \frac{\partial}{\partial y} + y^3 \frac{\partial}{\partial y}) + b(-xy^2 \frac{\partial}{\partial x} - y^3 \frac{\partial}{\partial x} + x^3 \frac{\partial}{\partial y} + xy^2 \frac{\partial}{\partial y}) : a, b \in \mathbb{R} \right\}$$

$$= \left\{ \begin{pmatrix} (ax - by)(x^2 + y^2) \\ (ay + bx)(x^2 + y^2) \end{pmatrix} : a, b \in \mathbb{R} \right\}$$

Then 2.3.3  $\implies$  the system can be transformed to

$$\begin{cases} \dot{x} = -y + (ax - by)(x^2 + y^2) + o(|(x, y)|^3) \\ \dot{y} = x + (ay + bx)(x^2 + y^2) + o(|(x, y)|^3) \end{cases}$$

where the values of  $a, b$  are determined by higher derivatives of  $f$ .

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Normal forms for parametrised system:  $\sim f(x, \mu) = \begin{pmatrix} f(x, \mu) \\ 0 \end{pmatrix}$

$$\dot{x} = f(x, \mu), \quad x \in \mathbb{R}^n, \mu \in \mathbb{R} \quad \xrightarrow{\text{extend}} \quad \begin{cases} \dot{x} = f(x, \mu) \\ \dot{\mu} = 0 \end{cases} \quad x \in \mathbb{R}^n, \mu \in \mathbb{R}$$

$f(0, \mu) = 0 \quad \forall \mu$  in a nbhd of  $\mu_0 \in \mathbb{R}$

Consider  $\begin{pmatrix} \dot{x} \\ \dot{\mu} \end{pmatrix} = H(y, \mu) = \begin{pmatrix} h(y, \mu) \\ \mu + 0 \end{pmatrix} = \begin{pmatrix} y + P(y, \mu) \\ \mu + 0 \end{pmatrix}$  for some homog. polyn. of deg.  $k$ ,  $P = P(y, \mu)$

in order to reduce the parametrised system to its "normal form".

Let  $L = D_{(x, \mu)} \tilde{f}(0, \mu_0) \begin{pmatrix} x \\ \mu \end{pmatrix}$  "the linear part of  $\begin{cases} \dot{x} = f(x, \mu) \\ \dot{\mu} = 0 \end{cases}$ "

Let  $H_k$  be the br. space of vec. fields whose coefficients are homogeneous polyn. in  $(x, \mu)$  of degree  $k$ ; i.e.

$$H_k(x, \mu) = \left\{ \begin{pmatrix} P_1 \\ \vdots \\ P_N \\ 0 \end{pmatrix} : P_i \text{ is a homog. polyn. of deg. } k \text{ in } (x_1, \dots, x_n, \mu) \right\}$$

Define  $adL : H_k(x, \mu) \rightarrow H_k(x, \mu)$

$$Y = Y(x, \mu) \mapsto DLY - DY L$$

Theorem 2.3.3 Let  $\dot{x} = f(x, \mu)$  be a  $C^r$ -system with  $f(0, \mu) = 0 \quad \forall \mu$  near  $\mu_0$

and  $D_{(x, \mu)} \tilde{f}(0, \mu_0) \begin{pmatrix} x \\ \mu \end{pmatrix} = L$ . If  $G_k$  is a complement for  $adL(H_k)$

in  $H_k$ , then  $\exists$  analytic change of coord. (near 0) s.t.  $\dot{x} = f(x, \mu)$  becomes

$$\dot{y} = g(y, \mu) = g_{(1)}^{(1)}(y, \mu) + \dots + g_{(r)}^{(r)}(y, \mu) + o(|y|^r) \quad \text{wh. } L = g_{(1)}^{(1)}, g_{(k)} \in G_k \quad \forall 2 \leq k \leq r.$$

Example 2.3.2 (part II) Consider the param. system

$$\begin{cases} \dot{x} = \mu x - \omega y + o(|x|, |y|) \\ \dot{y} = \omega x + \mu y + o(|x|, |y|) \end{cases} \quad \begin{array}{l} (x, y) \in \mathbb{R}^2, \omega \in \mathbb{R} \text{ fixed constant,} \\ \mu \in \mathbb{R} \text{ parameter} \end{array}$$

The linearization  $\begin{pmatrix} \mu & -\omega \\ \omega & \mu \end{pmatrix}$  has eigenvalues  $\mu \pm i\omega$ , so has

purely imaginary eigenvalues  $\pm i\omega$ , for  $\mu = \mu_0 = 0$ .

Let  $L = \left( \begin{array}{cc|c} \mu & -\omega & 0 \\ \omega & \mu & 0 \\ \hline 0 & 0 & 0 \end{array} \right) \begin{pmatrix} x \\ y \\ \mu \end{pmatrix}$  and  $adL : H_k \rightarrow H_k$ . One can show that

the system can be brought to the form :

$$(*_p) \begin{cases} \dot{x} = \mu x - \omega y + (ax - by)(x^2 + y^2) + O(|(x, y)|^5) \\ \dot{y} = \omega x + \mu y + (ay + bx)(x^2 + y^2) + O(|(x, y)|^5) \end{cases}$$

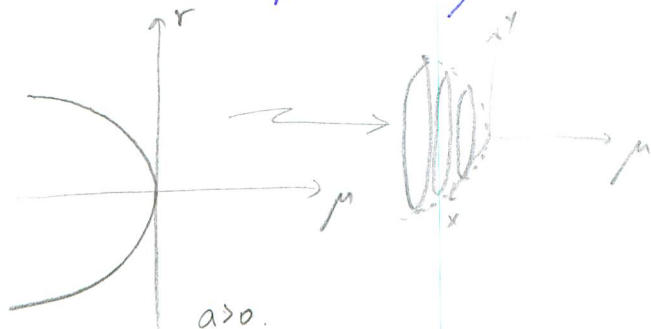
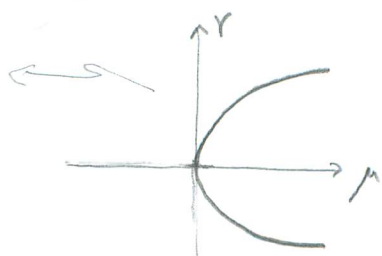
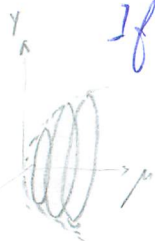
where  $a, b \in \mathbb{R}$  are determined by the nonlinearity  $o(|(x, y)|^3)$ .

Using polar coordinates, we have

$$\begin{cases} \dot{r} = (\mu + ar^2)r \\ \dot{\theta} = \omega + br^2 \end{cases}$$

So periodic solutions can be obtained from  $\dot{r} = 0$ .

If  $a \neq 0$ , then these solutions lie on the parabola  $\mu = -ar^2$



It is worthwhile noting that (\*) is neatly expressed in complex variables as

$$\dot{w} = \lambda w + c w^2 \bar{w} + O(|w|^5),$$

where  $\lambda = \mu + i\omega$ ,  $c = a + ib$ ,  $w = x + iy$ .

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## 2.4. Codimension-One bifurcations of equilibria

Recall "codimension one bifurcations" are related to

either (i) a simple zero eigenvalue

$$D_x f_\mu = \begin{pmatrix} 0 & 0 \\ 0 & A \end{pmatrix}$$

or (ii) a simple pure ima. pair

$$D_x f_\mu = \left( \begin{array}{cc|c} 0 & -\omega & 0 \\ \omega & 0 & 0 \\ \hline 0 & & A \end{array} \right),$$

where  $A$  is a square matrix s.t.  $\sigma(A) \cap i\mathbb{R} = \emptyset$ .

We give some simplest examples of codim-1 bifurcations of equilibria:

(i1) saddle-node bifurcation

(i2) transcritical bifurcation

(i3) pitchfork bifurcation

(ii) Hopf bifurcation

## 2.4.1 Codim-One bifurcations related to a simple zero eigenvalue

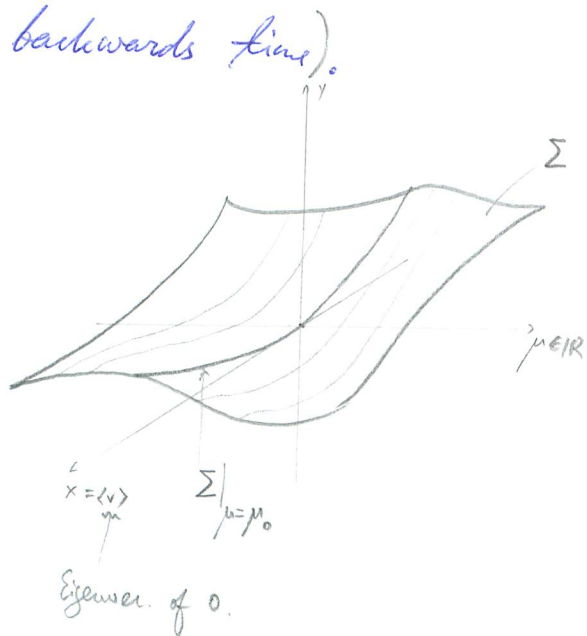
Consider  $\dot{x} = f(x, \mu)$ ,  $x \in \mathbb{R}^n$ ,  $\mu \in \mathbb{R}$ ,  $f_\mu$  smooth.

Assume  $f(x_0, \mu_0) = 0$  and  $D_x f(x_0, \mu_0)$  has a simple eigenvalue 0 (other than that no other eigenvalues on  $i\mathbb{R}$ ).

Center Manifold

Theorem  $\rightarrow \exists$  2-dimensional center manifold  $\Sigma \subset \mathbb{R}^n \times \mathbb{R}$  passing through  $(x_0, \mu_0)$  (which is spanned by an eigenvector of 0 and the  $\mu$ -axis)

s.t.  $\Sigma$  and the flow on  $\Sigma$  describe the qualitative structure of trajectories which remain close to  $(x_0, \mu_0)$  (in forwards time or backwards time).



Restriction to  $\Sigma \rightarrow$  a one-parameter family of equations on the one-dimensional curves  $\Sigma_\mu$  in  $\Sigma$  obtained by fixing  $\mu$ .  
"restriction of our bf. problem".

Therefore, it suffices to consider: