



Convolution Transforms in Manifold Learning and Dimensionality Reduction

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NoKo 2009

Motivation and Objectives

- Main Topic: **Manifold Learning and Convolution Transforms**
- Motivation Examples

Background Theory

- Manifold Learning and Dimensionality Reduction
- Differential Geometry: Curves and Curvature Tensor

Manifold Learning and Convolution Transforms

- Curvature Distortion and Convolution
- Examples: Curvature, Wave Equation, Topological Distortion

Manifold Learning and Dimensionality Reduction

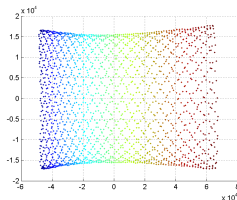
Observed data $X = \{x_1, \dots, x_m\} \subset \mathcal{M} \subset \mathbb{R}^n$

Hypothesis:

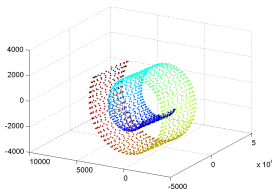
- $Y = \{y_1, \dots, y_m\} \subset \Omega \subset \mathbb{R}^d$, $d < n$ (Ω domain)
- nonlinear map $\mathcal{A} : \Omega \rightarrow \mathbb{R}^n$, $X = \mathcal{A}(Y)$

Task: Recover Y (and Ω)

$$Y \subset \Omega \subset \mathbb{R}^2$$



$$X \subset \mathbb{R}^{1024}$$



$$\begin{array}{ccc} \Omega \subset \mathbb{R}^d & \xrightarrow{\mathcal{A}} & X \subset \mathcal{M} \subset \mathbb{R}^n \\ & & \swarrow \mathcal{P} \\ & & \Omega' \subset \mathbb{R}^d \end{array}$$

Short Term Fourier Transform - Wavelets

- Signal $f \in L^2([0, 1])$ (Audio, Signal Processing)

$$\mathcal{G}_g f(b, \omega) := \langle f, g_{b, \omega} \rangle = \int_0^1 f(t) \overline{g_{b, \omega}(t)} dt, \quad g_{b, \omega}(t) := g(t-b)e^{2\pi i \omega t}.$$

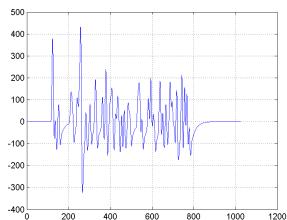
$$X = \{x_i\}_{i=1}^n := \{(f(t_j)g(t_j - k_i))_{j=1}^m\}_{i=1}^n \in \mathbb{R}^m\}_{i=1}^n$$

Image Analysis

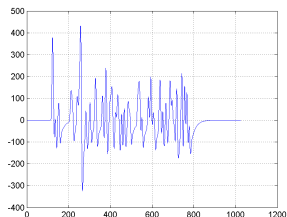
- Grayscale image $F : [0, 1]^2 \rightarrow [0, 1]$
- Finite covering of small squares $O_i \subset [0, 1]^2$

$$X := \{x_i\}_{i=1}^n := \{F(O_i) \in \mathbb{R}^m\}_{i=1}^n$$

Motivation and Objectives



⋮



$$X = \{x_1, \dots, x_m\} \subset \mathcal{M} \subset \mathbb{R}^n$$

$$\Omega \subset \mathbb{R}^d \xrightarrow{\mathcal{A}} \mathcal{M} \subset \mathbb{R}^n$$

T

$$\Omega' \subset \mathbb{R}^d \xleftarrow{\mathcal{P}} \mathcal{M}_T \subset \mathbb{R}^n$$

T Signal Transformation
(Wavelets, Fourier,...)

\mathcal{P} Dimensionality Reduction

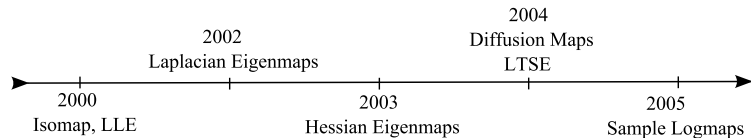
Proposition (Niyogi, Smale, Weinberger, 2008)

- Let \mathcal{M} be a compact Riemannian submanifold of \mathbb{R}^m . Let $X = \{x_i\}_{i=1}^n \subset \mathbb{R}^m$ a finite collection $\epsilon/2$ -dense in \mathcal{M} , i.e. for each $p \in \mathcal{M}$, there is an $x \in X$ such that $\|p - x\|_{\mathbb{R}^m} < \epsilon/2$. Then for any $\epsilon < \sqrt{\frac{3}{5}}\tau$, we have that $U := \bigcup_{x \in X} B_\epsilon(x)$ deformation retracts to \mathcal{M} , and therefore the homology of U equals the homology of \mathcal{M} .
- *Condition number* $1/\tau$ of the manifold.
- *Medial axis* of \mathcal{M} , and is defined as the closure of the set

$$G := \{x \in \mathbb{R}^m, \exists p, q \in \mathcal{M}, p \neq q : d(x, \mathcal{M}) = \|x - p\| = \|x - q\|\}$$

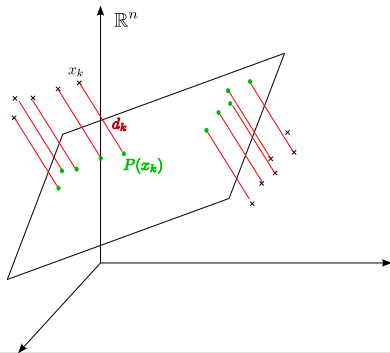
$$\tau := \inf_{p \in \mathcal{M}} d(p, \overline{G})$$

- Principal Component Analysis (PCA)
- Multidimensional Scaling (MDS)
- Isomap - Supervised Isomap
- Whitney Embedding Based Method
- Laplacian Eigenmaps
- Local Tangent Space Alignment
- Riemannian Normal Coordinates



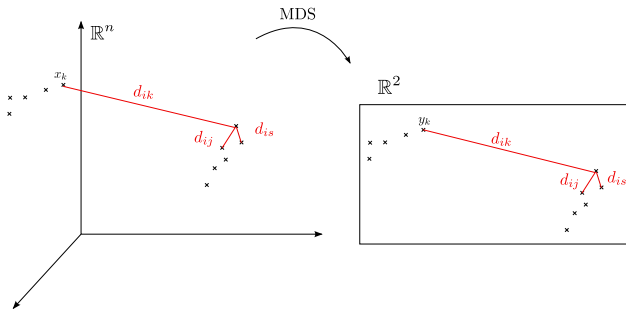
Dimensionality Reduction: PCA

- Matrix data: $X = (x_1 \dots x_m) \in \mathbb{R}^{n \times m}$
- Problem: find projection $P : \mathbb{R}^n \rightarrow \mathbb{R}^3$ with:
- $\text{err}(P, X) = \sum_k \|x_k - P(x_k)\|^2$ minimum
- $\text{var}(P(X)) = \sum_k \|P(x_k)\|^2$ maximum
- “maximum” eigenvectors of the covariance matrix XX^t
- SVD of X



Dimensionality Reduction: MDS

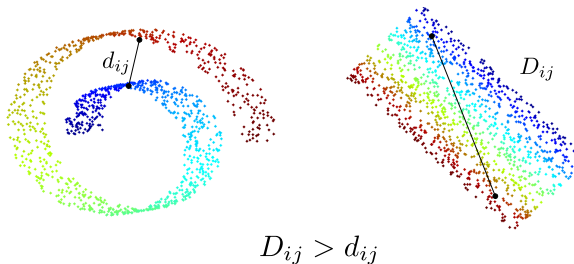
- Matrix data: $X = (x_1 \dots x_m) \in \mathbb{R}^{n \times m}$
- Problem: find a $Y = (y_1 \dots y_m) \in \mathbb{R}^{2 \times m}$ with:
- $\text{err}(Y, X) = \sum_k (d_{ij} - \|y_i - y_j\|)^2$ is minimum
- $d_{ij} = \|x_i - x_j\|$.



Dimensionality Reduction: Isomap

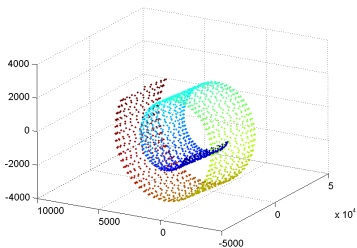
Isomap main ideas:

- Construct neighborhood graph
- Construct geodesic distances
- Use the MDS framework

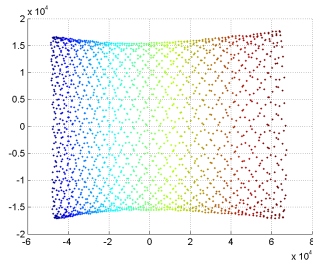
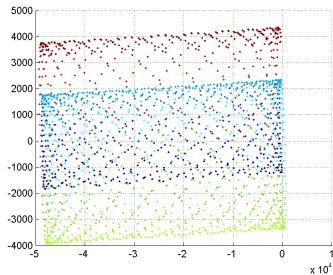


Dimensionality Reduction: Isomap

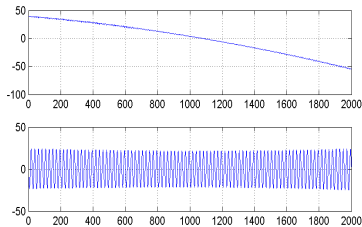
Swiss Roll Dataset \mathbb{R}^3



PCA projection \mathbb{R}^2



Isomap projection \mathbb{R}^2



Isomap projection: Eigenvectors

- For a curve $r : I \rightarrow \mathbb{R}^n$ with arc-length parametrization:

$$s(a, t) = \int_a^t \|r'(x)\| dx$$

the curvature is defined as

$$k(s) = \|r''(s)\|$$

- For a curve r with an arbitrary parametrization we have

$$K^2 = \frac{\|r''\|^2 \|r'\|^2 - \langle r'', r' \rangle^2}{(\|r'\|^2)^3}$$

- Gaussian Curvature:
$$K_{\mathcal{M}} := \frac{\langle R(X, Y)Y, X \rangle}{\|X\|^2\|Y\|^2 - \langle X, Y \rangle^2}$$
- Curvature Tensor: $R(X, Y)Z := \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z$
- Connection: $\nabla_{\partial_i} \partial_j = \sum_{k=1}^n \Gamma_{ij}^k \partial_k$
- Christoffel symbols (expressed with metric tensor)

$$\Gamma_{ij}^k = \frac{1}{2} \sum_{l=1}^m \left(\frac{\partial g_{jl}}{\partial x_i} + \frac{\partial g_{il}}{\partial x_j} + \frac{\partial g_{ij}}{\partial x_l} \right) g^{lk}$$

- Gaussian Curvature (expressed with Christoffel symbols)

$$K = -\frac{1}{E} \left(\frac{\partial}{\partial u} \Gamma_{12}^2 - \frac{\partial}{\partial v} \Gamma_{11}^2 + \Gamma_{12}^1 \Gamma_{11}^2 - \Gamma_{11}^1 \Gamma_{12}^2 + \Gamma_{12}^2 \Gamma_{12}^2 - \Gamma_{11}^2 \Gamma_{22}^2 \right)$$

- Effect of the convolution map T on the \mathcal{M} (and the dataset X).
- $\mathcal{M}_T = \{T(x), x \in \mathcal{M}\}$ $T(x) = x * h, \quad h = (h_1, \dots, h_m)$

$$T = \begin{pmatrix} h_1 & 0 & \dots & 0 \\ h_2 & h_1 & \dots & 0 \\ h_3 & h_2 & \dots & 0 \\ \vdots & \vdots & \dots & \vdots \\ h_m & h_{m-1} & \dots & h_1 \\ 0 & h_m & \dots & h_2 \\ \vdots & \vdots & \dots & \vdots \\ 0 & 0 & \dots & h_m \end{pmatrix}$$

- Curves:

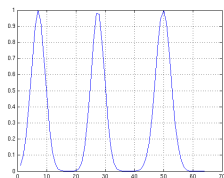
$$K_T^2 = \frac{\|Tr''\|^2 \|Tr'\|^2 - \langle Tr'', Tr' \rangle^2}{(\|Tr'\|^2)^3}$$

Example 1: Curvature Distortion

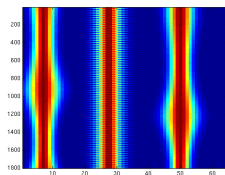
Low dimensional parametrization of scale modulated signals

$$X = \left\{ f_{\alpha^t} = \sum_{i=1}^3 e^{-\alpha_i(t)(\cdot - b_i)^2}, \alpha \in \Omega \right\}$$

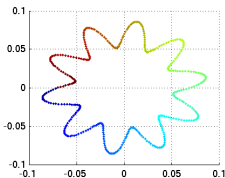
$$\Omega = \left\{ \alpha^t = (\alpha_1(t), \alpha_2(t), \alpha_3(t)), t \in [t_0, t_1] \right\}$$



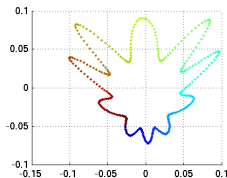
f_{α}



$X = \{f_{\alpha}, \alpha \in \Omega\}$



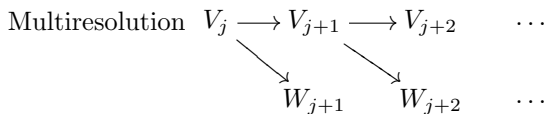
$\Omega \subset \mathbb{R}^3$



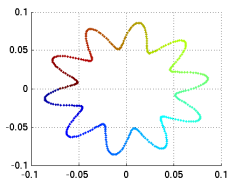
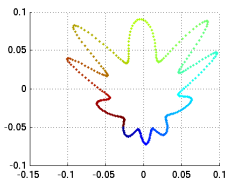
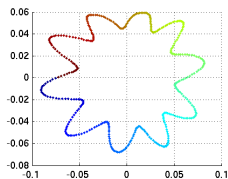
$X \subset \mathbb{R}^{64}$

Example 1: Curvature Distortion - part 2

Low dimensional parametrization of scale modulated signals



$$V_8 \oplus W_8 \oplus W_{16} \oplus W_{32} = V_{64}$$

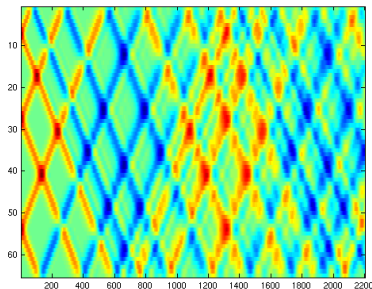
 $\Omega \subset \mathbb{R}^3$  $X \subset \mathbb{R}^{64}$  $T(X) \subset \mathbb{R}^{64}$

Example 1b: Curvature Distortion Evolution

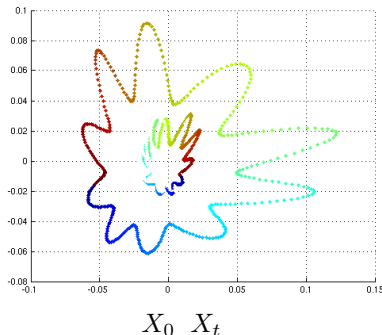
Manifold Evolution under a PDE

Wave Equation
$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2} \quad (\text{WE})$$

$$U_t = \left\{ u_\alpha(t, x), u_\alpha \text{ solution of (WE) with initial condition } f_\alpha, \alpha \in \Omega_0 \right\}$$

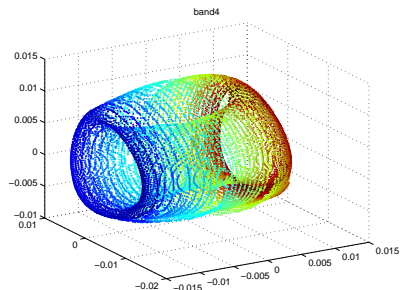
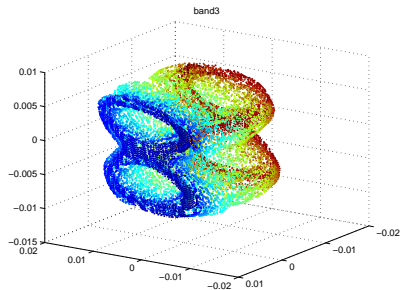
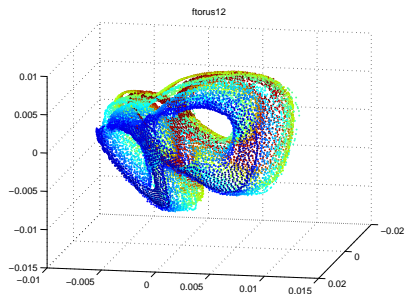


$$\left\{ u_{\alpha_0}(t, x), (t, x) \in [t_0, t_1] \times [x_0, x_1] \right\}$$



Example 2: Topological Distortion

Torus Example: (genus 1 and genus 2)



CW-Complex

$$\emptyset \subset \mathcal{M}_0 \subset \dots \subset \mathcal{M}_n := \mathcal{M}$$

- d -Cell σ : homeomorphic copy of B^d a closed unit ball in \mathbb{R}^d .
 $B^d := \{x \in \mathbb{R}^d : |x| \leq 1\}$, $S^{d-1} := \{x \in \mathbb{R}^d : |x| = 1\}$.
Attaching Map $f : \dot{\sigma} \rightarrow M_{i-1}$ with $\dot{\sigma}$ homeomorphic to S^{d-1} .
- $\mathcal{M}_i := \mathcal{M}_{i-1} \cup_f \sigma$

Simplicial Complex

- Finite set of vertices V and set of subsets K of V with
 - 1- $V \subset K$
 - 2- $\alpha \in K$ and $\beta \subset \alpha$, then $\beta \in K$.

Main Theorem of Morse Theory

- Let $f : \mathcal{M} \rightarrow \mathbb{R}$ is a smooth function, and $p \in \mathcal{M}$ is a non-degenerate critical point of f with index τ , and $f(p) = q$. If $f^{-1}([q - \epsilon, q + \epsilon])$ is compact and contains no critical points besides p , then $M^{p-\epsilon}$ is homotopy equivalent to $M^{p+\epsilon}$ with a τ -cell attached.

Main Theorem of Discrete Morse Theory

- Suppose K is a simplicial complex with a discrete Morse function. Then K is homotopy equivalent to a CW complex with exactly one cell of dimension p for each critical simplex of dimension p .