Cauchy problems for Lorentzian manifolds with special holonomy

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Outline

Project with H. Baum & A. Lischewski, Humboldt-Universität Berlin:

- Baum, Lischewski & L., Differential Geom. Appl. 45 (2016), arXiv:1411.3059
- Lischewski, arXiv:1503.04946
- Lischewski & L., in progress
- 1 Cauchy problems for Lorentzian manifolds and special holonomy
- 2 Evolution equations in the analytic setting

Einstein equations Parallel null vector and spinor

The smooth case and quasilinear symmetric hyperbolic systems
 Einstein equations
 Parallel null vector and spinor

4 Riemannian manifolds satisfying the constraints

The Cauchy problem for a parallel null vector field

Given a Riemannian manifold (\mathcal{M}, g) , can we embed (\mathcal{M}, g) as a Cauchy hypersurface into a Lorentzian manifold $(\overline{\mathcal{M}}, \overline{g})$ of the form $\overline{\mathcal{M}} \subset \mathbb{R} \times \mathcal{M}$ and

$$\overline{\mathbf{g}} = -\lambda^2 \, dt^2 + \mathbf{g}_t, \qquad (*)$$

such that $(\overline{\mathcal{M}}, \overline{g})$ admits a parallel null vector field V, i.e., with

$$\nabla V = 0$$
 and $\overline{g}(V, V) = 0$?

Here g_t = family of Riemannian metrics on \mathcal{M} with $g_0 = g$, $\lambda = \lambda(t, x)$ "lapse fct".

- Without requiring V being null finding \overline{g} with V parallel is trivial: The metric $\overline{g} = -dt^2 + g$ on $\mathbb{R} \times \mathcal{M}$ has a parallel time-like vector field ∂_t .
- If V is null and parallel, g has to satisfy the constraint equation

$$\nabla U = uW$$
,

with u = g(U, U) and W the Weingarten operator [Helga's talk].

 For a Riemannian manifold (*M*, g) satisfying the constraints, find a (globally hyperbolic) Lorentzian manifold of the form (*) with parallel null vector field.

Motivation 1: Special Lorentzian holonomy (more details in Helga's talk)

Let (\mathcal{M}, g) be a semi-Riemannian manifold, and

$$\operatorname{Hol}(\mathcal{M}, g) = \left\{ \mathsf{P}_{\gamma}^{\nabla} \in \mathbf{O}(\mathsf{T}_{\rho}\mathcal{M}, g_{\rho}) \mid \gamma(0) = \gamma(1) = \rho \right\}$$

its holonomy group with Lie algebra $\mathfrak{hol}(\mathcal{M},g)$.

- (M,g) has "special holonomy" ⇐⇒ bol ⊊ so(p,q) but the manifold is indecomposable, i.e., does not (locally) decompose as a product.
- Riemannian special holonomy: U(p) SU(p), Sp(q), Sp(q)·Sp(1), G₂,
 Spin(7) [Berger, Bryant, ...] + isotropy groups of symmetric spaces.
- ▶ Lorentzian special holonomy: \nexists irreducible subalgebras of $\mathfrak{so}(1, n+1)! \implies$

$$\mathfrak{hol} \subset \mathfrak{stab}(\mathfrak{null\ line}) = (\mathbb{R} \oplus \mathfrak{so}(\mathfrak{n})) \ltimes \mathbb{R}^n = \left\{ \left(\begin{array}{cc} a & v^\top & 0 \\ 0 & A & -v \\ 0 & 0^\top & -a \end{array} \right) \middle| \begin{array}{c} a \in \mathbb{R} \\ v \in \mathbb{R}^n, \\ A \in \mathfrak{so}(\mathfrak{n}) \end{array} \right\}.$$

There is a classification of Lorentzian special holonomy algebras:

- ▶ indecomposable subalgebras of sv(1, n + 1) [Berard-Bergery & Ikemakhen '93]
- pr_{so(n)}(bol) is a Riemannian holonomy algebra [L '03] → Berger's list
- Construction of local metrics for all possible holonomy algebras [... Galaev '05]

Construction of Lorentzian manifolds with special holonomy

• Let (\mathcal{M}, g, μ) be a Riemannian manifold with closed 1-form μ . Then

$$\overline{\mathbf{g}} = \mu \, d\mathbf{v} + \mathbf{g},$$

is a Lorentzian metric on $\mathcal{M} \times \mathbb{R}$ with parallel null vector field ∂_{v} .

 Most constructions for prescribed holonomy are based on the local form of a Lorentzian manifold with parallel null vector field

$$\overline{g} = 2du(dv + f \, du + f_i \, dx^i) + h_{ij} \, dx^i dx^j,$$

with *f*, f^i and h_{ij} functions of $x^1, \ldots x^{n-2}$, *u*. Then ∂_v is null and parallel.

- Need 'global' constructions for globally hyperbolic manifolds with complete Cauchy hypersurfaces and with special holonomy [Baum-Müller '08]
- A Lorentzian manifold $(\overline{\mathcal{M}}, \overline{g})$ is globally hyperbolic if it admits a Cauchy hypersurface \mathcal{M} , i.e., a spacelike hypersurface that is met by every maximal timelike curve exactly once. They are of the form $\overline{\mathcal{M}} = \mathbb{R} \times \mathcal{M}$ with

$$\overline{\mathbf{g}} = -\lambda^2 dt^2 + \mathbf{g}_t.$$

[Geroch '70, ..., Bernal-Sánchez '03]

Motivation 2: Parallel spinors on Lorentzian manifolds

Let $(\overline{\mathcal{M}}, \overline{g})$ be a Lorentzian spin manifold with spinor bundle $\overline{\mathbb{S}} \to \overline{\mathcal{M}}$. and $\psi \in \Gamma(\overline{\mathbb{S}})$ a parallel spinor, with induced causal and parallel Dirac current V_{ψ} .

• $\overline{g}(V_{\psi}, V_{\psi}) = -1$: $(\overline{\mathcal{M}}, \overline{g})$ locally is a product $-dt^2 + h$ with h Riemannian, Ric^h = 0 and with a parallel spinor

 \rightarrow special holonomy Riemannian manifolds: SU(p), Sp(q), G₂, Spin(7).

- ► $\overline{g}(V_{\psi}, V_{\psi}) = 0$: $T\overline{\mathcal{M}}$ is filtered $\mathbb{R}V_{\psi} \subset V_{\psi}^{\perp} \subset T\overline{\mathcal{M}}$ No induced product structure and *not Ricci-flat* but $\operatorname{Ric}^{\overline{g}} = f(V_{\psi}^{\flat})^2$.
- Constraints: Each spacelike hypersurface (\mathcal{M}, g) admits a spinor field φ with

$$\nabla_{X}\varphi = \frac{i}{2} \operatorname{W}(X) \cdot \varphi, \quad \forall X \in T\mathcal{M}, \qquad U_{\varphi} \cdot \varphi = i \, u_{\varphi} \, \varphi, \tag{1}$$

in which U_{φ} is defined by $g(U_{\varphi}, X) = -i(X \cdot \varphi, \varphi), u_{\varphi} = \sqrt{g(U_{\varphi}, U_{\varphi})} = ||\varphi||^2$.

- A spinor with (1) is called *generalised imaginary Killing spinor (GIKS)*.
- $U_{\varphi} = pr_{TM}V_{\psi}$ satisfies the constraint $\nabla_X U_{\varphi} = u_{\varphi}W(X)$.

Solve the Cauchy problem for Lorentzian manifolds with parallel null vector field V and extend GIKS on (\mathcal{M}, g) to parallel spinor on $(\overline{\mathcal{M}}, \overline{g})$ by parallel transport.

Motivation 3: (Generalised) Killing spinors on Riemannian manifolds

 (\mathcal{M}, g) Riemannian mfd., φ a Killing spinor with Killing number λ , i.e.

 $\nabla_X \varphi = \lambda \, X \cdot \varphi, \qquad \lambda \in \mathbb{R} \cup i \, \mathbb{R}.$

- Killing spinor $\Rightarrow (\mathcal{M}, g)$ Einstein with scal $= 4n(n-1)\lambda^2$.
- ► {Killing spinors} \simeq {parallel spinors on the cone $(\mathbb{R}^+ \times \mathcal{M}, \hat{g} = 2\lambda^2 dr^2 + r^2 g)$ }
- Parallel spinors are fixed under spin rep of Hol → use holonomy classification in order to classify mfd's with Killing spinors.
- λ ∈ ℝ [Bär '93] : Riemannian cones are flat or irreducible [Gallot '79], Berger's list ⇒ (M, g) = Sⁿ, (3-)Sasaski, 6-dim nearly Kähler, nearly parallel G₂
- λ ∈ iℝ: (M, g) = Hⁿ or (M = R × F, g = ds² + e^{4iλs}h) and (F, h) admits a parallel spinor [Baum '89]. This can be obtained using the time-like cone and a generalisation of Gallot's result [Alekseevski, Cortés, Galaev, L '08].

Use same approach — with the cone replaced by the solution to a more general Cauchy problem — and the classification of Lorentzian holonomy, to locally classify Riemannian manifolds with generalised imaginary Killing spinor.

Example: Cauchy problem for $Ric(\overline{g}) = 0$

Let $\overline{g} = -\lambda^2 dt^2 + g_t$ on $I \times M$ and $T = \frac{1}{\lambda} \partial_t$ be the timelike unit normal.

- $W := -\overline{\nabla}T|_{TM}$ the Weingarten operator, $W = -\frac{1}{2\lambda}\dot{g}$, where $dot = \partial_t$.
- Fundamental curvature equations, $\overline{R} = curvature$ tensor of \overline{g} :

$$\begin{array}{rcl} \overline{R}|_{\mathcal{TM}} &=& R + W \wedge W & \mbox{Gauß} \\ \overline{R}(\cdot,\cdot,\cdot,T)|_{\mathcal{TM}} &=& d^{\nabla}W & \mbox{Codazzi} \\ \overline{R}(T,\cdot,\cdot,T)|_{\mathcal{TM}} &=& \frac{1}{\lambda} \left(\dot{W} + \nabla^2(\lambda) \right) + W^2 & \mbox{Mainardi} \end{array}$$

• Ricci-tensor of \overline{g} , $\overline{Ric} = Ric(\overline{g})$:

$$\overline{\operatorname{Ric}}(T,T) = \frac{1}{\lambda} \left(\operatorname{tr}(\dot{W}) + \Delta(\lambda) \right) + \operatorname{tr}(W^2)
\overline{\operatorname{Ric}}(T,.)|_{TM} = d(\operatorname{tr}W) + \operatorname{div}W
\overline{\operatorname{Ric}}|_{TM \times TM} = -\frac{1}{\lambda} \left(\dot{W} + \nabla^2(\lambda) \right) + \operatorname{Ric} + \operatorname{tr}(W)W - 2W^2$$
(2)

Scalar curvature:

$$\overline{\text{scal}} = \text{scal} + (\text{tr}(W_t))^2 - 3\|W\|^2 - \frac{2}{\lambda} \left(\text{tr}(\dot{W}) + \Delta(\lambda) \right)$$
(3)

Set (2) and (3) to zero and replace $tr(\dot{W})$ in (2) by (3).

Constraint and evolution equations for $Ric(\overline{g}) = 0$

$$\overline{\operatorname{Ric}} = 0 \iff \left\{ \begin{array}{l} \operatorname{scal} = \operatorname{tr}(W^2) - \operatorname{tr}(W)^2 \\ d\operatorname{tr}(W) = -\operatorname{div}(W) \end{array} \right\} \text{ (constraints) and} \\ \\ \dot{W} = \lambda \left(\operatorname{Ric} + \operatorname{tr}(W)W - 2W^2 \right) - \nabla^2(\lambda) \quad \text{(evolution equations)} \end{array}$$

- Constraints are preserved under evolution equations.
- The evolution equations are of the form:

 $\ddot{g} = F(g, \dot{g}, \partial_i g, \partial_i \dot{g}, \partial_i \partial_j g),$

with initial data $g|_{t=0} = g$, $\dot{g}|_{t=0} = -2\lambda W$.

- If \u03c4 and initial data are real analytic: apply Cauchy-Kowalevski to get unique solution:
 - for Lorentzian metrics [Darmois '27, Lichnerowicz '39], this can be generalised to the smooth setting: Choquet-Bruhat (50's, second part of the talk).
 - Riemannian: solution for analytic data [Koiso '81], but in general no solution for smooth, non-analytic [counterexamples by Bryant '10, also Ammann, Moroianu & Moroianu '13].

Constraint and evolution equations for a parallel vector field

On $\overline{\mathcal{M}} = \mathbb{R} \times \mathcal{M}$ we can write a vector field $V \in \Gamma(T\overline{\mathcal{M}})$ as

$$V = uT + U$$
 with $U \in \Gamma(T^{\perp})$ and $u \in C^{\infty}(\mathbb{R} \times \mathcal{M})$.

V is null for $\overline{g} = -\lambda^2 dt^2 + g_t \implies u = -g(T, V) = \sqrt{g(U, U)}.$

$$\overline{\nabla}_X V = du(X)T - uW(X) + \underbrace{\overline{\nabla}_X U}_{= \overline{\nabla}_X U - W(X, U)T} \text{ for } X \in TM$$

$$\overline{\nabla}_X V = 0 \quad \Longleftrightarrow \quad \overline{\nabla U - u W} = 0 \quad \& \quad du - W = 0$$

constraint equations (t = 0)

$$\overline{\nabla}_{\partial_t} V = \dot{u}T + u \overline{\nabla}_{\partial_t} T + \overline{\nabla}_{\partial_t} U = [\partial_t, U] - \lambda W(U) + d\lambda(U)T$$

 $\overline{\nabla}_{\partial_t} V = 0 \quad \Longleftrightarrow \quad \underbrace{\dot{U} + u \nabla \lambda + \frac{1}{2} \dot{g}_t(U) = 0}_{\text{evolution equations}} \& \quad \dot{u} + d\lambda(U) = 0$

Second order evolution equations for a parallel null vector field

• If $\overline{\nabla} V = 0$, then for $X, Y \in T\mathcal{M}$ it is

$$\overline{R}(\partial_t, X, Y, V) = \overline{R}(\partial_t, X, V, \partial_t) = 0 \qquad \rightarrow \text{ evolution for g via Codazzi-Mainardi}$$

$$\overline{\nabla}_{\partial_t} \overline{\nabla}_{\partial_t} V = 0 \qquad \rightarrow \text{ evolution for for } U = pr_{\mathcal{T}\mathcal{M}}(V)$$

$$\overline{\nabla}_X V|_{|0| \times \mathcal{M}} = 0 \qquad \rightarrow \text{ constraint for } U \text{ (initial condition for } \dot{g})$$

$$\overline{\nabla}_{\partial_t} V|_{|0| \times \mathcal{M}} = 0 \qquad \rightarrow \text{ initial condition for } \dot{U}$$

• We can show that this is in fact equivalent to $\overline{\nabla}V = 0$ and leads to equivalent 2nd order evolution equations in Cauchy-Kowalevski form:

$$(\ddot{g}, \ddot{U}, \ddot{u}) = \mathcal{F}(g, \dot{g}, \partial_i g, \partial_i \dot{g}, \partial_i \partial_j g, U, \dot{U}, \dots, \partial_i \partial_j u),$$

however the first component of \mathcal{F} is not necessarily symmetric!

Observation:

In the analytic case, (*) can be replaced by $\overline{R}(X, V, V, Y) = 0$ for all $X, Y \in TM$.

Let (\mathcal{M}, g) be a Riemannian mfd, W a symmetric endomorphisms field, U a vector field, u function on \mathcal{M} , all real analytic, with constraints

$$\nabla_i U^j = -u W_i^{\ j}, \ g(U, U) = u^2 > 0.$$

Then for any analytic fct. $\lambda = \lambda(t, x)$ the Lorentzian metric $\overline{g} = -\lambda^2 dt^2 + g_t$ has parallel null vector field $V = \frac{u_t}{\lambda} \partial_t - U_t \iff$

$$\begin{split} \ddot{\mathbf{g}}_{ij} &= \frac{1}{u} U^{k} \left(\lambda \nabla_{[k} \dot{\mathbf{g}}_{(j]i)} - \dot{\mathbf{g}}_{(i[j)} \nabla_{k]} \lambda \right) + \frac{1}{2} \dot{\mathbf{g}}_{ik} \dot{\mathbf{g}}_{j}^{k} + \frac{\lambda}{\lambda} \dot{\mathbf{g}}_{ij} + 2\lambda \nabla_{i} \nabla_{j} \lambda + \frac{2\lambda^{2}}{u^{2}} U^{k} U^{\ell} \mathbf{R}_{ik\ell j} \\ \ddot{U}_{i} &= \frac{1}{2u} U^{k} U^{l} \left(\dot{\mathbf{g}}_{l[k} \nabla_{i]} \lambda - \lambda \nabla_{[i} \dot{\mathbf{g}}_{k]l} \right) - U^{k} \left(\dot{\mathbf{g}}_{ki} - \frac{\lambda}{\lambda^{2}} \dot{\mathbf{g}}_{ki} - \lambda \nabla_{k} \nabla_{i} \lambda - \nabla_{k} \lambda \nabla_{i} \lambda \right) \\ &+ u g_{ki} \nabla^{k} \dot{\lambda} + \frac{u}{2} \dot{\mathbf{g}}_{ki} \nabla^{k} \lambda + 2 \dot{u} \nabla_{i} \lambda \\ \ddot{u} &= U^{k} \left(g_{kl} \nabla^{l} \dot{\lambda} + \frac{3}{2} \dot{\mathbf{g}}_{kl} \nabla^{l} \lambda \right) + 2 \dot{U}^{k} \nabla_{k} \lambda - u \nabla_{k} \lambda \nabla^{k} \lambda \\ \end{split}$$
with initial conditions
$$\begin{cases} g_{ij}(0) &= g_{ij}, & \dot{\mathbf{g}}_{ij}(0) &= -2\lambda W_{ij}, \\ U(0) &= U, & \dot{U}_{i}(0) &= u \nabla_{i} \lambda + \lambda U^{k} W_{ki} \\ u(0) &= u & \dot{u}(0) &= U^{k} \nabla_{k} \lambda \end{split}$$

Theorem 1 (Baum, Lischewski, L '14)

If (\mathcal{M}, g, U) are real analytic satisfying the constraint equations, λ real analytic, then (\mathcal{M}, g) can be embedded as Cauchy hypersurface into a Lorentzian manifold $(\overline{\mathcal{M}} \subset \mathbb{R} \times \mathcal{M}, \overline{g} = -\lambda^2 dt^2 + g_t)$ with parallel null vector field. For given initial conditions as above, \overline{g} is unique and $(\overline{\mathcal{M}}, \overline{g})$ is globally hyperbolic.

- Apply Cauchy-Kowalevski to the evolution equations in coordinate neighbourhoods in *M*. By uniqueness these patch together to a unique global solution on *M* defining the Lorentzian metric ḡ on *M* ⊂ ℝ × *M*.
- ► Every $p \in M$ then admits a neighbourhood \mathcal{U}_p in $\widetilde{\mathcal{M}}$ such that $\mathcal{M} \cap \mathcal{U}$ is a Cauchy hypersurface in \mathcal{U}
- Then $\overline{\mathcal{M}} = \bigcup_{p \in \mathcal{M}} \mathcal{U}_p$ contains *M* as a Cauchy hypersurface.

Example [Baum & Müller '08]

 $\lambda \equiv 1$, W Codazzi tensor, i.e. $\nabla_{[i}W_{i}^{k} = 0$. Solution to the above system:

$$g_{ij}(t) = g_{ij} - 2tW_{ij} + t^2W_{ik}W_j^k$$

$$U^i(t) = A^i_k(t)U^k, \text{ mit } A^i_k \text{ inverse of } (\delta^j_i - tW_i^j)$$

$$u(t) = u$$

Corollary 1

Let $(\mathcal{M}, g, \varphi)$ be an analytic Riemannian spin manifold with an analytic GIKS φ . \implies On the Lorentzian manifold in Theorem 1 there exists a parallel null spinor.

Proof: Take the Lorentzian manifold obtained as solution with parallel null vector field. Translate the initial GIKS φ parallel along *t*-lines \rightsquigarrow spinor ψ with $\overline{\nabla}_{\partial_t}\psi = 0$.

• A = B = 0 along initial hypersurface and hence for all t.

Smooth case: the Cauchy problem for $Ric(\overline{g}) = 0$

In the smooth setting we relax the condition on the explicit form of ḡ: Given a Riemannian manifold (M, g) and symmetric endomorphism W satisfying the constraints

$$R = tr(W^2) - tr(W)^2, \qquad d tr(W) = -div(W),$$

find a Lorentzian manifold $(\overline{\mathcal{M}}, \overline{g})$ with $\operatorname{Ric}(\overline{g}) = 0$ and such that (\mathcal{M}, g) injects into $(\overline{\mathcal{M}}, \overline{g})$ with Weingarten operator W.

A system of PDEs for vector valued functions $u : \mathbb{R}^{n+1} \to \mathbb{R}^N$ of $x^0 = t$ and $x = (x^i)_{i=1,\dots,n}$

$$A^{0}(x^{\mu}, u) \partial_{0} u = \sum_{i=1}^{n} A^{i}(x^{\mu}, u) \partial_{i} u + B(x^{\mu}, u), \qquad (4)$$

- is a 1st order quasilinear symmetric hyperbolic system of PDEs if
 - the $A^{\mu}(x^{\mu}, u)$ are symmetric $N \times N$ matrices, and
 - $A^0(x^{\mu}, u)$ is *positive definite* with a uniform positive lower bound.

Such systems have a unique smooth solution for given initial conditions.

Hyperbolic reduction [Friedrich-Rendall]:

In coordinates the Ricci tensor looks like

$$\operatorname{Ric}(\overline{g})_{\mu\nu} = -\frac{1}{2}\overline{g}^{\alpha\beta}\partial_{\alpha}\partial_{\beta}\overline{g}_{\mu\nu} + \underbrace{\partial_{(\mu}\overline{\Gamma}_{\nu)}}_{=\overline{g}^{\alpha\beta}} + LOTs$$
$$= \overline{g}^{\alpha\beta}\partial_{\mu}\partial_{\nu}\overline{g}_{\alpha\beta} + LOTs$$

where $\Gamma_{\mu} = \Gamma^{\alpha}_{\mu\alpha}$.

► Not fixing time coordinate and the form of the metric ~> full diffeomorphism invariance

$$\phi \in \operatorname{Diff}(\overline{\mathcal{M}}) \implies \operatorname{Ric}(\phi^*\overline{g}) = \phi^*\operatorname{Ric}(\overline{g}) = 0.$$

 Hyperbolic reduction to break the diffeomorphism invariance: Fix background metric

$$\hat{\mathbf{g}} = -\lambda^2 dt^2 + \mathbf{g}$$

on $\mathbb{R} \times \mathcal{M}$ with $\lambda \in C^{\infty}(\mathbb{R} \times \overline{\mathcal{M}})$, define $C = \overline{\nabla} - \hat{\nabla}$ and

$$E_{\mu}=\overline{g}_{\mu\nu}\overline{g}^{\alpha\beta}C^{\nu}_{\ \alpha\beta},$$

and replace $Ric(\overline{g}) = 0$ by the equation

$$\widehat{\operatorname{Ric}}(\overline{g})_{\mu\nu} := \operatorname{Ric}(\overline{g})_{\mu\nu} + \overline{\nabla}_{(\mu} E_{\nu)} = 0.$$

Einstein equation as quasilinear symmetric hyperbolic system

• Locally, $\widehat{\operatorname{Ric}}(\overline{g})_{\mu\nu}$ is of the form

$$\widehat{\rm Ric}(\overline{g})_{\mu\nu} = \operatorname{Ric}(\overline{g})_{\mu\nu} + \overline{\nabla}_{(\mu} E_{\nu)} = -\frac{1}{2} \overline{g}^{\alpha\beta} \partial_{\alpha} \partial_{\beta} \overline{g}_{\mu\nu} + LOTs.$$

• $\widehat{\text{Ric}}(\overline{g}) = 0$ is a 1st order quasilinear symmetric hyperbolic system of PDEs,

$$A^{0}(\mathbf{x}^{\mu},G)\partial_{0}G = \sum_{i=1}^{n} A^{i}(\mathbf{x}^{\mu},G)\partial_{i}G + B(t,x,G),$$
(5)

for functions $G = \begin{pmatrix} \overline{g} \\ \partial_{\mu} \overline{g} \end{pmatrix}$ of $x^0 = t$ and $x = (x^i)_{i=1,...,n}$, i.e., and hence has a

unique smooth solution for given smooth initial conditions.

• Then $\widehat{\text{Ric}}(\overline{g}) = 0$ implies that *E* satisfies a wave equation

$$\overline{\Delta}E_{\mu} = \overline{\nabla}^{\alpha}\overline{\nabla}_{\alpha}E_{\mu} = -\underbrace{2\overline{\nabla}^{\alpha}\overline{R}_{\alpha\mu} - \overline{\nabla}^{\alpha}\overline{\nabla}_{\mu}E_{\alpha}}_{= \overline{R}_{\mu} \alpha} = \overline{R}_{\mu}^{\alpha} E_{\beta} = \overline{R}_{\mu}^{\alpha}E_{\alpha}.$$
(6)

Hence $E \equiv 0$ if $E|_{\mathcal{M}} = 0$ and $\overline{\nabla} E|_{\mathcal{M}} = 0$.

Initial conditions

- $\blacktriangleright \mbox{ original initial data: } \overline{g}_{ij}|_{\mathcal{M}} = g_{ij}, \, \partial_0 \overline{g}_{ij}|_{\mathcal{M}} = -2\lambda W_{ij},$
- choice: $\overline{g}_{00}|_{\mathcal{M}} = -\lambda^2|_{\mathcal{M}}, \overline{g}_{0i}|_{\mathcal{M}} = 0$, i.e., $\overline{g}_{\mu\nu}|_{\mathcal{M}} = \widehat{g}_{\mu\nu}$.
- determine initial data for $\partial_t \overline{g}_{00}$ and $\partial_t \overline{g}_{0i}$ such that $E|_{\mathcal{M}} = 0$:

 $\partial_t \overline{g}_{00}|_{\mathcal{M}} = -2F_0|_{\mathcal{M}} - \mathrm{tr}(\mathbf{W}), \qquad \partial_t \overline{g}_{0i}|_{\mathcal{M}} = -F_i|_{\mathcal{M}} + \frac{1}{2}g^{kl}(2\partial_k g_{il} - \partial_i g_{kl}),$

where $F_{\mu} = \overline{g}_{\mu\nu} \overline{g}^{\alpha\beta} \widehat{\Gamma}^{\nu}_{\alpha\beta}$.

• With $E|_{\mathcal{M}} = 0$ we have $\overline{\nabla}_i E_{\mu}|_{\mathcal{M}} = 0$. The constraints give

$$0 = \operatorname{Ric}(\overline{g})_{0i}|_{\mathcal{M}} = \frac{1}{2}\overline{\nabla}_{0}E_{i}|_{\mathcal{M}}, \qquad 0 = \operatorname{Ric}(\overline{g})_{00} = \overline{\nabla}_{0}E_{0}|_{\mathcal{M}},$$

and hence $\overline{\nabla} E|_{\mathcal{M}} = 0$.

• With $E|_{\mathcal{M}} = 0$, $\overline{\nabla} E|_{\mathcal{M}} = 0$ and wave equation (6), we get E = 0.

We obtain a local solutions to $\widehat{\text{Ric}}(\overline{g}) = \text{Ric}(\overline{g}) = 0$ that patch together to a globally hyperbolic solution.

The smooth case: parallel vector field [Lischewski & L, in prep.]

Given a smooth Riemannian manifold (\mathcal{M}, g) with U and W satisfying the constraints

$$\nabla U = uW, \qquad u = \sqrt{g(U, U)},$$

can we find a Lorentzian manifold $(\overline{\mathcal{M}}, \overline{g})$ with parallel, null vector field V such that $\operatorname{pr}_{\mathcal{TM}}(V) = U$ and W is the Weingarten operator of $\mathcal{M} \subset \overline{\mathcal{M}}$?

- ► Let V be a parallel vector field on $(\overline{\mathcal{M}}, \overline{g})$ and $\mu = V^{\flat} = \overline{g}(V, .) \in \Omega^{1}(\overline{\mathcal{M}})$. Then
 - ▶ $V \sqcup (\overline{\nabla}^{(k)} \operatorname{Ric}(\overline{g})) = 0$ for k = 0, 1, ... hence there is a bilinear form Q with

$$\operatorname{Ric}(\overline{g}) = Q, \quad V \sqcup Q = 0, \quad \overline{\nabla}_V Q = 0.$$
 (7)

► $\overline{\nabla}\mu = 0$ and in particular $(d + \delta^{\overline{z}})\mu = 0$. Recall that $d + \delta^{\overline{z}} = c \circ \overline{\nabla}$, where *c* is the Clifford multiplication on forms

$$c: T\overline{\mathcal{M}} \otimes \Omega^* \ni X \otimes \omega \mapsto X^{\flat} \wedge \omega - X _ \omega \in \Omega^*$$

Given a initial manifold (M, g) and a function λ ∈ C[∞](ℝ × M), fix a background metric ĝ = −λ²dt² + g on ℝ × M that defines Ric(g) as for the Einstein equations.

Consider the PDE system

$$\begin{split} \widehat{\operatorname{Ric}}(\overline{g}) &= Q : \mu^{\sharp} \sqcup Q = 0 \\ \overline{\nabla}_{\mu^{\sharp}} Q &= 0 \\ (d + \delta^{\overline{g}}) \mu &= 0 \end{split}$$

for a metric \overline{g} , a one-form μ , and a symmetric BLF Q. Note that

▶ $\widehat{\text{Ric}}(\overline{g})$ does not contain derivatives of Q, i.e., 1st eq. in (8) is like Einstein equation with energy-momentum tensor Q.

•
$$d + \delta = c \circ \overline{\nabla} : \Lambda^* \to \Lambda^*$$
 is of Dirac type.

 (8) reduces to a 1st order quasilinear symmetric hyperbolic system of the form

$$\begin{pmatrix} A_1^0 & 0 & 0 \\ 0 & A_2^0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \partial_0 G \\ \partial_0 \mu \\ \partial_0 Q \end{pmatrix} = \begin{pmatrix} A_1^i & 0 & 0 \\ 0 & A_2^i & 0 \\ 0 & 0 & a_3^i \mathbf{1} \end{pmatrix} \begin{pmatrix} \partial_i G \\ \partial_i \mu \\ \partial_i Q \end{pmatrix} + \begin{pmatrix} B_1 \\ B_2 \\ B_3 \end{pmatrix},$$

for $G = (\overline{g}, \partial_t \overline{g}, \partial_i \overline{g}), \mu$ and Q, with $A_{1/2}^0$ symmetric positive definite, $A_{1/2}^i$ symmetric, that has a unique solution for given initial data along \mathcal{M} .

- $\Psi := (\overline{\nabla} V, E)$ is a solution to a wave eq. $\mathcal{P} \Psi = 0$, for normally hyperbolic \mathcal{P} .
- Again, the initial data are determined by

$$\overline{g}|_{\mathcal{M}} = \widehat{g}, \quad \mu|_{\mathcal{M}} = \widehat{g}(\frac{u}{\lambda}\partial_t - U, .), \quad \partial_t \overline{g}|_{\mathcal{TM} \times \mathcal{TM}} = -2\lambda W,$$

and the requirement that $\overline{\nabla} V|_{\mathcal{M}} = 0$ and $E|_{\mathcal{M}} = 0$.

Cauchy problems for Lorentzian manifolds and special holonomy

Part 2

Recall from part 1:

Given a Riemannian manifold (\mathcal{M}, g) , with a vector field U and a symmetric endomorphism field W satisfying the constraint equation

$$\nabla U = u W$$
, with $u = \sqrt{g(U, U)}$,

and a function $\lambda \in C^{\infty}(\mathbb{R} \times \mathcal{M})$, we wanted to construct a Lorentzian manifold $(\overline{\mathcal{M}}, \overline{g})$ which

- contains $(\mathcal{M}, g = \overline{g}|_{\mathcal{M}})$ as Cauchy hypersurface, with Weingarten operator W,
- admits a parallel null vector field V such that $\operatorname{pr}_{TM}(V) = U$,
- possibly of the form

$$\overline{\mathbf{g}} = -\lambda^2 dt^2 + \mathbf{g}_t,$$

for a family of Riemannian metrics.

Theorem 2 (Lischewski-L, in progr.)

Let (\mathcal{M}, g) be a smooth Riemannian manifold with a vector field U and a symmetric endomorphism field W satisfying the constraint equation $\nabla U = uW$ and a function $\lambda \in C^{\infty}(\mathbb{R} \times \mathcal{M})$.

Then there is $\overline{\mathcal{M}} \subset \mathbb{R} \times \mathcal{M}$ with a Lorentzian metric

$$\overline{g} = -\widetilde{\lambda}^2 dt^2 + g_t$$
 with $\widetilde{\lambda}|_{\mathcal{M}} = \lambda$, $g_0 = g$,

such that $(\mathcal{M}, \overline{g})$ admits a parallel null vector field V with $\operatorname{pr}_{\mathcal{TM}}(V) = U$, and such that $(\overline{\mathcal{M}}, \overline{g})$ is globally hyperbolic with \mathcal{M} as Cauchy hypersurface with Weingarten operator W.

Moreover, let $\hat{g} = -\lambda^2 dt^2 + g$ be the background metric on $\mathbb{R} \times \mathcal{M}$ defined by the initial data λ and g. Then \overline{g} is the unique metric satisfying the additional conditions

- ► $\overline{g}|_{\mathcal{M}} = -\hat{g}|_{\mathcal{M}}$,
- ► tr_{\overline{g}}(*C*) = 0, where *C*(*X*, *Y*) = $\overline{\nabla}_X Y \hat{\nabla}_X Y$ is the difference tensor between the Levi-Civita connections of \overline{g} and \hat{g} .

Proof, step 1: the quasilinear symmetric hyperbolic system

Fix the background metric $\hat{g} = \lambda^2 dt^2 + g$ on $\mathbb{R} \times \mathcal{M}$. For a Lorentzian metric \overline{g} define the difference difference tensor *C* between the Levi-Civita connections of \overline{g} and \hat{g} , the 1-form *E* and the modified Ricci tensor by

$$E = \overline{g}(\mathrm{tr}_{\overline{g}}(C), .), \qquad \widehat{\mathrm{Ric}}(\overline{g})_{\alpha\beta} = \mathrm{Ric}(\overline{g})_{\alpha\beta} + \overline{\nabla}_{(\alpha} E_{\beta)}.$$

Consider the PDE system

$$\widehat{\operatorname{Ric}}(\overline{g}) = Q \circ \operatorname{pr}_{\mathcal{TM}}^{\mu^{\sharp}} \qquad \overline{\nabla}_{\mu^{\sharp}} Q = 0, \qquad (d + \delta^{\overline{g}})\mu = 0$$
(9)

for a metric \overline{g} , a one-form μ , and a symmetric BLF Q.

In local coordinates $x^0 = t$, $x = (x^i)_{i=1,...,n}$, this is equivalent to a 1st order quasilinear symmetric hyperbolic system of the form

$$\begin{pmatrix} A_1^0 & 0 & 0 \\ 0 & A_2^0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \partial_0 G \\ \partial_0 \mu \\ \partial_0 Q \end{pmatrix} = \begin{pmatrix} A_1^i & 0 & 0 \\ 0 & A_2^i & 0 \\ 0 & 0 & a_3^i \mathbf{1} \end{pmatrix} \begin{pmatrix} \partial_i G \\ \partial_i \mu \\ \partial_i Q \end{pmatrix} + \begin{pmatrix} B_1 \\ B_2 \\ B_3 \end{pmatrix},$$

for $G = (\overline{g}, \partial_{\alpha}\overline{g}), \mu$ and Q, with $A_{1/2}^{\alpha} = A_{1/2}^{\alpha}(x^{\beta}, G, \mu, Q)$ and $A_{1/2}^{0}$ symmetric positive definite, $A_{1/2}^{i}$ symmetric.

Proof, step 2: the wave equation

For \overline{g} , Q and $\mu = V^{\flat}$ be a solution of the system (9) we define the quantities

$$\begin{array}{rcl} \Phi & = & \left(\overline{\nabla}V, E, \overline{\nabla}_V E, \overline{\nabla}E(V)\right). \\ \Psi & = & \operatorname{div}^{\overline{g}}\left(Q - \frac{1}{2}\operatorname{tr}_{\overline{g}}(Q)\overline{g}\right). \end{array}$$

Then show that Φ and Ψ satisfy the following PDEs

$$\Delta \Phi = L_1(\Phi, \overline{\nabla} \Phi, \Psi), \qquad \overline{\nabla}_V \Psi = L_2(\Phi, \overline{\nabla} \Phi), \tag{10}$$

where $\Delta = \overline{\nabla}^2$ is defined by the Bochner Laplacian on the appropriate bundle and L_1 and L_2 are linear.

Again, in local coordinates the system (10) is a equivalent to a 1st order linear symmetric hyperbolic system for Φ , $\partial \Phi$ and Ψ , and hence has a unique solution for given initial values.

If we can show that Φ , $\overline{\nabla}\Phi$ and Ψ vanish along \mathcal{M} , then they vanish for all *t*.

Proof, step 3: Initial conditions

(i) the original initial conditions:

$$\overline{g}|_{\mathcal{M}} = \hat{g}|_{\mathcal{M}}, \qquad \partial_t \overline{g}|_{T\mathcal{M}\times T\mathcal{M}} = 2\lambda W, \qquad \mu|_{\mathcal{M}} = u\hat{g}(\frac{u}{\lambda}\partial_t - U, .)$$

(ii) initial conditions for Q:

$$U \sqcup Q|_{\mathcal{M}} = d \operatorname{tr}(W) = -\operatorname{div}(W)$$

$$Q = \operatorname{Ric} -W^{2} + \operatorname{tr}(W)W - \operatorname{R}(N, ., .N) + W(., N)W(., N) - W(N, N)W$$

where $N = \frac{1}{u}U$ and the second equation holds for $U^{\perp} \times U^{\perp}$ along \mathcal{M} . (iii) initial data for $\partial_t \overline{g}_{00}$ and $\partial_t \overline{g}_{0i}$:

$$\begin{split} \partial_t \overline{g}_{00}|_{\mathcal{M}} &= -2\lambda|_{\mathcal{M}}^2 \left(F_0|_{\mathcal{M}} - \lambda|_{\mathcal{M}} \mathrm{tr}(W)\right), \\ \partial_t \overline{g}_{0i}|_{\mathcal{M}} &= \lambda|_{\mathcal{M}}^2 \left(-F_i|_{\mathcal{M}} + \frac{1}{2}g^{kl}(2\partial_k g_{il} - \partial_i g_{kl}) + \partial_i(\log \lambda|_{\mathcal{M}})\right) \\ \end{split}$$
 where $F_{\mu} = \overline{g}_{\mu\nu} \overline{g}^{\alpha\beta} \widehat{\Gamma}_{\alpha\beta}^{\nu}.$

The initial conditions (ii) and (iii) imply that Φ , $\overline{\nabla}\Phi$ and Ψ from the previous slide vanish along \mathcal{M} .

Proof, step 4: the global metric and its form

From local to global:

- ▶ For each $p \in M$ there is a globally hyperbolic neighbourhood U_p and solutions \overline{g} , V, Q with E = 0 and $\overline{\nabla} V = 0$.
- On overlaps, these solutions coincide and thus give rise to a globally hyperbolic solution on $\overline{\mathcal{M}} = \cup_{p \in \mathcal{M}} \mathcal{U}_p$ containing \mathcal{M} as Cauchy hypersurface.

The form of the metric as $\overline{g} = -\overline{\lambda}^2 dt^2 + g_t$: Consider the vector field $F = \frac{1}{dt(\overline{\nabla}t)}\overline{\nabla}t$, i.e., with dt(F) = 1.

- The leafs of F^{\perp} are given as $\mathcal{M}_t = \{t\} \times \mathcal{M} \subset \overline{\mathcal{M}} \subset \mathbb{R} \times \mathcal{M}$.
- The flow ϕ of F satisfies $\phi_s(\mathcal{M}_t) = \mathcal{M}_{t+s}$ because

$$rac{d}{ds}(t(\phi_s(p)))=dt|_{\phi_s(p)}(F)=1, ext{ and hence } t(\phi_s(p))=s+t(p).$$

► Then the metric $\Phi^*\overline{g}$ for $\Phi(t,p) = \phi_t(p) \in \overline{\mathcal{M}}$ satisfies

$$\Phi^*\overline{g}(\partial_t, X) = \overline{g}(F, d\Phi(X)) = 0 \ \forall X \in T\mathcal{M}_t,$$

with
$$\widetilde{\lambda}^2 = \Phi^* \overline{g}(\partial_t, \partial_t) = \overline{g}(F, F) = \frac{1}{dt(\overline{\nabla}t)}$$
.

Extend generalised imaginary Killing spinor (GIKS) along (\mathcal{M}, g) to parallel spinor on $(\overline{\mathcal{M}}, \overline{g})$ by parallel transport along the flow of $V \implies$

Corollary 2 (Lischewski '15)

Let $(\mathcal{M}, g, \varphi)$ be a smooth Riemannian mfd with smooth GIKS φ and $\lambda \in C^{\infty}(\mathbb{R} \times \mathcal{M})$. Then the above Lorentzian manifold $\overline{\mathcal{M}} \subset \mathbb{R} \times \mathcal{M}$ with Lorentzian metric \overline{g} admits a a parallel spinor ϕ such that $\phi|_{\mathcal{M}} = \varphi$.

The corollary was obtained independently by Lischewski by studying the system

$$\operatorname{Ric}(\overline{g}) = f(V_{\phi}^{\flat})^2, \qquad D^{\overline{g}}\phi = 0, \qquad df(V_{\phi}) = 0$$

for a spinor ϕ , a metric \overline{g} and a function *f*. The wave operator in step 2 of the proof is made of multiple copies of D^2 and $\overline{\nabla}^2$.

Riemannian manifolds satisfying the constraints

Let (\mathcal{M}, g) be a Riemannian manifold with a vector field U such that $\nabla_{[i}U_{j]} = 0$ and $u^2 := g(U, U) \neq 0$.

- $dU^{\flat} = 0$ and U^{\perp} is integrable.
- ▶ Locally, U = grad(f), and the leaves of U^{\perp} are the level sets of *f*.
- ► For $Z = \frac{1}{u^2}U$ we have $\mathcal{L}_Z U^{\flat} = dU^{\flat}(Z, .) = 0$. Hence, the flow ϕ of Z is a diffeomorphism between the leaves of U^{\perp} and there is a diffeomorphism

$$\Phi: I \times \mathcal{U} \ni (s, x) \rightarrow \phi_s(x) \in \mathcal{W} \subset \mathcal{M}, \quad I \text{ an interval},$$

• The diffeomorphism Φ satisfies $d\Phi|_{(s,x)}(\partial_s) = Z|_{\phi_s(x)}$ and

$$\begin{array}{rcl} \Phi^* g(\partial_s, \partial_s) &=& g(Z, Z) \,=\, \frac{1}{g(U, U)}, \\ \Phi^* g(\partial_s, X) &=& g(Z, d\Phi(X)) \,=\, 0, & \quad \text{for } X \in U^\perp \end{array}$$

Riemannian manifolds satisfying the constraints, ctd.

If Z is complete, its flow is defined on \mathbb{R} . On the universal cover $\widetilde{\mathcal{M}}$ of \mathcal{M} , $U = \operatorname{grad}(f)$ globally, and hence there is a diffeomorphism

 $\Phi : \mathbb{R} \times \mathcal{U} \ni (s, x) \to \phi_s(x) \in \widetilde{\mathcal{M}}$ \uparrow level sets of *f* = integral mfds of *U*[⊥].

Theorem 3

 (\mathcal{M}, g, U) satisfies the constraint $\nabla_{[i}U_{j]} = 0 \iff it$ is locally isometric to

 $(I \times \mathcal{F}, g = \frac{1}{u^2} ds^2 + h_s), \quad h_s \text{ family of Riemannian metrics on } \mathcal{F}.$

This isometry maps U to $u^2 \partial_s$. Moreover: If the vector field $\frac{1}{u^2}U$ is complete, then $\widetilde{\mathcal{M}}$ is globally isometric to $\mathbb{R} \times \mathcal{F}$.

Conversely, if \mathcal{F} is compact and $u \in C^{\infty}(\mathcal{F} \times \mathbb{R})$ bounded, then for any family of Riemannian metrics h_s

$$\left(\mathcal{M} = \mathbb{R} \times \mathcal{F}, g = \frac{1}{u^2} ds^2 + h_s\right)$$

is complete.

Lorentzian holonomy reductions and the screen bundle

Let $(\overline{\mathcal{M}}, \overline{g})$ be a Lorentzian mfd. of dim (n+2) with parallel null vector field V.

$$\succ \operatorname{hol}_{p}(\overline{\mathcal{M}},\overline{g}) \subset \operatorname{stab}(V_{p}) = \operatorname{so}(n) \ltimes \mathbb{R}^{n} = \left\{ \left(\begin{array}{ccc} 0 & v^{\top} & 0 \\ 0 & A & -v \\ 0 & 0^{\top} & 0 \end{array} \right) \middle| \begin{array}{c} v \in \mathbb{R}^{n}, \\ A \in \operatorname{so}(n) \end{array} \right\}$$

Screen bundle over M:

$$\mathbb{S} = V^{\perp}/\mathbb{R} \cdot V, \qquad h^{\mathbb{S}}([X], [Y]) = \overline{g}(X, Y), \qquad \nabla^{\mathbb{S}}_{X}[Y] = \left[\overline{\nabla}_{X}Y\right],$$

is a vector bundle with positive def. metric and compatible connection $\nabla^{\mathbb{S}}$.

- bol(∇^S) = pr_{so(n)}bol(M, g) is a Riemannian holonomy algebra, i.e., equal to (a product of) so(k), u(k), sp(1) ⊕ sp(k), su(k), sp(k), g₂ or spin(7), or the isotropy of a Riemannian symmetric space.
- Fixing a time-like unit vf T ∈ Γ(M) gives a canonical identification of S with a tangent subbundle

$$V^{\perp} \cap T^{\perp} = \mathbb{S} \subset T\overline{\mathcal{M}}$$

▶ If $(\overline{\mathcal{M}}, \overline{g}, V)$ arises as solution to the Cauchy problem for *V* from (\mathcal{M}, g, U) we identify $\mathbb{S}|_{\mathcal{M}}$ with $U^{\perp} \subset T\mathcal{M}$ and get

$$\nabla^{\mathbb{S}}_{X}\sigma|_{\mathcal{M}}=\nabla^{\perp}_{X}\sigma,$$

 $\sigma \in \Gamma(\mathbb{S}|_{\mathcal{M}}) = \Gamma(U^{\perp}), X \in T\mathcal{M} \text{ and } \nabla^{\perp} = \operatorname{pr}_{U^{\perp}} \circ \nabla^{g}$ the induced connection.

- ► Locally $(\mathcal{M}, g) = (I \times \mathcal{F}, \frac{1}{u^2} ds^2 + h_s)$ and we can interpret $\sigma \in \Gamma(U^{\perp})$ as family $\{\sigma_s\}_{s \in I}$
- We have the following vector bundles of the same rank

$$\begin{array}{ccc} (\mathcal{TF},\nabla^{\mathrm{h}_{\mathrm{S}}}) & (\mathcal{U}^{\perp},\nabla^{\perp}) & (\mathbb{S},\nabla^{\mathbb{S}}) \\ \downarrow & \downarrow & \downarrow \\ \mathcal{F} & \subset & \mathcal{M} & \subset & \overline{\mathcal{M}} \end{array}$$

Lorentzian holonomy reductions from so(1, n + 1) to g κ ℝⁿ with g ⊂ so(n) are given by a parallel null vector field V and a parallel sections of ⊗^{a,b} S → M such as a complex structure, a stable 3-form, etc.

The relation to Lorentzian holonomy reductions

Theorem 4

Let (\mathcal{M}, g, U) be a Riemannian mfd. satisfying the constraints and $(\mathcal{M}, \overline{g}, V)$ the Lorenzian mfd. arising as solution of the Cauchy problem. Then there is a 1-1 correspondence between

$$\left\{ \begin{array}{l} \hat{\eta} \in \Gamma(\otimes^{a,b} \mathbb{S}) : \\ \nabla^{\mathbb{S}} \hat{\eta} = 0 \end{array} \right\} \stackrel{(*)}{\leftrightarrow} \left\{ \begin{array}{l} \eta \in \Gamma(\otimes^{a,b} U^{\perp}) : \\ \nabla^{\perp} \eta = 0 \end{array} \right\} \leftrightarrow \left\{ \begin{array}{l} \eta_{s} \in \Gamma(\otimes^{a,b} T\mathcal{F}) : \\ \hline \nabla^{h_{s}} \eta_{s} = 0 \qquad (i) \\ \dot{\eta}_{s} = \frac{1}{2} \dot{h}_{s}^{\sharp} \cdot \eta_{s} \qquad (ii) \end{array} \right.$$

Hence, $\mathfrak{hol}(\nabla^{\mathbb{S}}) = \mathrm{pr}_{\mathfrak{so}(n)}\mathfrak{hol}(\overline{\mathcal{M}}, \overline{g})$ lies in the stabiliser of a tensor on \mathbb{S} if and only if on \mathcal{F} there is an induced s-dependent family of h_s -parallel tensors η_s with (ii).

Proof of $(*, \leftarrow)$: Extend $\eta \in \Gamma(\otimes^{a,b} U^{\perp} \to \mathcal{M})$ to $\hat{\eta} \in \Gamma(\otimes^{a,b} \mathbb{S} \to \overline{\mathcal{M}})$ by parallel transport along the flow of *V*. Then $A := \nabla^{\mathbb{S}} \eta \in \Gamma(T^{\perp} \otimes \otimes^{a,b} \mathbb{S})$ satisfies $\nabla^{\mathbb{S}} A = 0$, which is a linear symmetric hyperbolic system for *A* with initial condition $A|_{\mathcal{M}} = 0$. Hence, not only $\nabla^{\mathbb{S}}_{V} \hat{\eta} = 0$ but also $\nabla^{\mathbb{S}}_{X} \hat{\eta} = 0$ for $X \in T\mathcal{M}$.

Flows of special Riemannian structures

Let h_s be a family of Riemannian metrics admitting a family η_s of parallel tensors defining a holonomy reduction. What about condition (ii) $\dot{\eta}_s = \frac{1}{2}\dot{h}_s^{\sharp} \cdot \eta_s$?

• h_s is family of Kähler metrics: there is a complex structure $\eta_s = J_s$ and Kähler form ω_s with

$$\dot{J}_s = \frac{1}{2} \dot{\mathrm{h}}_s^\sharp \cdot J_s, \qquad \dot{\omega}_s = \frac{1}{2} \dot{\mathrm{h}}_s^\sharp \cdot \omega_s,$$

so (ii) is automatically satisfied for J_s .

- h_s is family of Ricci-flat Kähler metrics with $div^{h_s}(\dot{h}_s) = 0$.
- ► $h_s = h_s^1 + h_s^2$ is a family of product metrics $\iff \exists \nabla^{h_s}$ -parallel decomposable *p*-forms $\mu_s^i = \operatorname{vol}^{h_s^i}$. Volume forms evolve as $\dot{\mu}_s = \frac{1}{2}\dot{h}_s^{\sharp} \cdot \mu_s$.
- ▶ h_s is a family of holonomy g_2 metrics defined by a family of stable 3-forms φ_s . Problem: Given a family h_s of holonomy g_2 metrics, does there exist a family of stable 3-forms φ_s defining h_s such that $\dot{\varphi}_s = \frac{1}{2}\dot{h}_s^{\sharp} \cdot \varphi_s$ holds?

$$Sym^{2}(\mathbb{R}^{7}) \oplus \mathbb{R}^{7} \ni (S, X) \longmapsto S \cdot \varphi + X \sqcup (*\varphi) \in \Lambda^{3} \mathbb{R}^{7}$$

If $\dot{\varphi} = S \cdot \varphi + X \square (*\varphi)$, then the associated metric satisfies $\dot{h} = 2S ...$

If $(\overline{\mathcal{M}}, \overline{g})$ is a Lorentzian manifold obtained from the Cauchy problem. Then $\mathfrak{hol}(\nabla^{\mathbb{S}}) \subset \mathfrak{g}$ if and only if the associated family of Riemannian metrics h_s on \mathcal{F} is given as follows:

g		h _s is family of
$\mathfrak{so}(p)\oplus\mathfrak{so}(q)$	\iff	product metrics
u(n/2)	\iff	Kähler metrics
𝒴(n/2)	\iff	Ricci-flat Kähler metrics with $\mathrm{div}^{\mathrm{h}_{\mathfrak{s}}}(\dot{h}_{\mathfrak{s}})=0$
$\mathfrak{sp}(n/4)$	\iff	hyper-Kähler metrics
g ₂ / spin(7)	\iff	of \mathfrak{g}_2 / $\mathfrak{spin}(7)$ -metrics (with (ii)?)

Theorem 5

Let (\mathcal{M}, g) be a Riemannian spin manifold admitting an GIKS φ . Then

1. (\mathcal{M}, g) is locally isometric to

$$(\mathcal{M}, g) = \left(I \times \mathcal{F}_1 \times ... \times \mathcal{F}_k, g = \frac{1}{u^2} ds^2 + h_s^1 + ... + h_s^k \right)$$
(11)

for Riemannian manifolds $(\mathcal{F}_i, \mathbf{h}_s^i)$ of dimension n_i , $u = ||\varphi||^2$. Each h_s^i is one of the following families of special holonomy Riemannian metrics:

- \mathbf{h}_{s}^{i} is Ricci-flat Kähler and $\operatorname{div}_{s}^{\mathbf{h}_{s}^{i}}(\dot{\mathbf{h}}_{s}^{i}) = 0$,
- hyper-Kähler, G_2 (?), Spin(7) (?) or a flat metric.
- If (M, g) is simply connected and the vector field ¹/_{u²_φ} U_φ is complete, the isometry (11) is global with I = ℝ.
- Conversely, every Riemannian manifold (M, g) of the form (11) with *I* ∈ {S¹, ℝ}, where u is any positive function and (*F_i*, hⁱ_s) are families of special holonomy metrics (subject to the above flow equations ...) is spin and admits an GIKS.