Ehlers-Kundt conjecture and the initial value problem for gravitational waves

Miguel Sánchez (U. Granada)

Based on joint work with JL FLORES, arxiv: 1706.03855

Hamburg, March 19-23, 2018





M. Sánchez Ehlers-Kundt conjecture

My talk, in a nutshell

Ehlers-Kundt conjecture: physical assertion on gravitational waves related to its *lack of predictability* from initial data

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- **Ehlers-Kundt conjecture**: physical assertion on gravitational waves related to its *lack of predictability* from initial data
- 2 Mathematically, equivalent to a "Newtonian problem": Given V : ℝ² × ℝ → ℝ,
 (a) V(z, u) harmonic in z, (b) with complete trajectories for

$$\ddot{z}(s) = -\nabla_z V(z(s), s)$$

must $V(\cdot, u)$ be polynomial of degree ≤ 2 in $z = (x, y) \in \mathbb{R}^2$?

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3 Assuming V(z, u) polynomially bounded for finite values of u, → we will give a positive answer

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must $V(\cdot, u)$ be polynomial of degree ≤ 2 in $z = (x, y) \in \mathbb{R}^2$?

- 3 Assuming V(z, u) polynomially bounded for finite values of u,
 → we will give a positive answer
- In general, including autonomous case $V(z, u) \equiv V(z)$, open Basic question in potential theory!!

My talk, in a nutshell

Aims: to explain

1 Background:

- Gravitational waves
- Initial value problem in this framework
- Original Ehlers-Kundt conjecture
- Reformulation with a Newtonian potential

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1 Background:

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- Original Ehlers-Kundt conjecture
- Reformulation with a Newtonian potential
- 2 To sketch the ideas for
 - 1 Technical setup
 - 2 Main steps of the solved polynomial case.

Physical viewpoint and geometric model (Non-) Global Hyperbolicity and EK conjecture Reformulation and known results

GW: (too) short experimental summary

Gravitational waves: prediction by Einstein

- Hulse and Taylor (1974): undirect evidence
- LIGO experiment: direct measurement '15 reported in '16 ...just the first step (eLISA, etc.)

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GW: theoretical viewpoint

Some highlights:

Einstein'18: prediction in the framework of GR (after more speculative introduction by Poincaré), introducing a celebrated quadrupole formula.

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 - Einstein and Rosen argued their inexistence in a paper submitted to Phys. Rev. ('36).
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- Historic meeting at Chapel Hill'57 (Feynmann explained his sticky bead argument)

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- Historic meeting at Chapel Hill'57 (Feynmann explained his sticky bead argument)
- End 50's waves in mainstream: Bondi, Pirani, Robinson '59 = ...

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By the way:

 Bondi, Pirani, Robinson'59 solution, obtained with great effort by physicists along decades...

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By the way:

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- …had been studied by the mathematician Brinkmann'25

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Parallelly propagated plane-fronted waves

pp-wave: \mathbb{R}^4 endowed with:

 $g = dx^2 + dy^2 + 2 du dv + H(z, u) du^2, \quad z := (x, y), \quad (x, y, u, v) \in \mathbb{R}^4$

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gravitational (Ricci-flat): H(z, u) harmonic in z:

$$\Delta_z H(z,u) := (\partial_x^2 H + \partial_y^2 H)(z,u) \equiv 0.$$

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plane wave: at each $u \in \mathbb{R}$, *H* polynomial in *x*, *y* of degree ≤ 2 .

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Penrose's remarkable property

Penrose's observation '65: plane waves are not globally hyperbolic no spacelike hypersurface exists in the spacetime which is adequate for the global specification of Cauchy data

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So:

at what extent plane waves are physically meaningful or just idealizations of the model

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About global hyperbolicity

(M,g) globally hyperbolic if any of the following holds:

- It is (necessarily strongly) causal and has no naked singularities, i.e. $J^+(p) \cap J^-(q)$ is compact for any $p, q \in M$.
- It admits a (topological) Cauchy hypersurface S (S: subset crossed exactly once by any inextensible timelike curve)
- 3 It admits a Cauchy temporal function τ (τ smooth with spacelike and Cauchy levels τ = constant). So, orthogonal Cauchy splitting:

 $M = \mathbb{R} imes S, g = -\Lambda(\tau, x) d\tau^2 + g_{ au}$

[Topological assertions: Geroch '70. Weakening of strong causality: Bernal & S. '07 Smoothening: Bernal & S. '03,'05 (improvements in Müller & S, '11, Müller'16; other approaches: Fathi & Siconolfi '13, Chrusciel et al. '16, Bernard & Suhr '18.)]

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- It admits a Cauchy temporal function τ (τ smooth with spacelike and Cauchy levels τ = constant).
 So, orthogonal Cauchy splitting: M = ℝ × S, g = -Λ(τ, x)dτ² + gτ

Moreover, in this case (Bernal & S. '06):

- Any compact acausal spacelike hyp. with boundary is extensible to a spacelike Cauchy hyp.
- Any spacelike Cauchy hyp. S is the level of some τ

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Relaxing to conformal boundaries

 (\overline{M}, g) globally hyp. with **timelike boundary** Loosen global hyp.: allow naked singularities at (conformal) ∂M

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Theorem (Aké, Flores, S. '18)

 (\overline{M},g) admits a splitting $M = \mathbb{R} \times \overline{S}$ where each slice \overline{S}_{τ} is a Cauchy hyp. with boundary

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This suggests *mixed hyperbolic problems* with:

- Initial conditions on $\{0\} \times \overline{S}$ (slice $\tau \equiv 0$) +
- Boundary conditions on $\mathbb{R} \times \partial S$ (= ∂M) +
- Compatibility on $\{0\} \times \partial S$ (= ($\{0\} \times \overline{S}$) \cap ($\mathbb{R} \times \partial S$))

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Conformal boundary for plane waves

Plane waves are not globally hyperbolic but, how is their conformal boundary?

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Conformal boundary for plane waves

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Berenstein & Natase '02: the conformal boundary of some plane waves is "1-dimensional and lightlike"
 Interesting boundary for holographic principle...
 but not a good timelike one for the initial value

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Conformal boundary for plane waves

Plane waves are not globally hyperbolic but, how is their conformal boundary?

- Marolf & Ross '02 '03: examples with no conformal bd. (bad even for holographic principle)

 extended study including the causal boundary

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Conformal vs causal boundary

Reasonable conformal boundaries are **not** always available:

 Alternative causal boundary ∂_cM (starting at a seminal idea by Geroch, Kronheimer and Penrose '72): intrinsic and general for strongly causal spacetimes

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- Historic problems: redefinition by Marolf-Ross (in order to study pp-waves)
- Boundary points: (P, F)
 - $P = I^{-}(\gamma)$, where γ inextendible, future-directed timelike
 - $F = I^+(\tilde{\gamma})$, where $\tilde{\gamma}$ inextendible, past-directed timelike
 - (P, F) constitute a pair when they are S-related (Szabados'88)
 → pairs (P, Ø) or (Ø, F) are allowed otherwise

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Conformal vs causal boundary

Redefinition and systematic study (Flores, Herrera, S '11):

1 A strongly causal s.t is globally hyp \iff S-relation is trivial (all $(P, F) \in \partial_c M$ has $P = \emptyset$ or $F = \emptyset$)

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- Under general conditions (applicable to globally hyp. s.t. with timelike bd, up to i[±]) the conformal and causal boundaries agree
- 3 When a conf. bound. ∂M is C¹ + chronologically complete (inextensible timelike curves have an endpoint at ∂M):
 M is glob. hyp. ⇔ T(∂M) is nowhere timelike (consistency with globally hyp. s.t. with timelike boundary)

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Plane waves did not have a good timelike conformal boundary, how is their causal bd. ?

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Marolf & Ross '02 '03: interesting particular cases
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Causal boundary for plane waves

Plane waves did not have a good timelike conformal boundary, how is their causal bd. ?

- Marolf & Ross '02 '03: interesting particular cases
- Flores & S. '08: systematic study c-boundary of pp-waves
 - Characterization possible dimensions of $\partial_c M$: $1, \ldots, n-1$.
 - Analysis conformal $\partial M \neq$ causal $\partial_c M$
 - many problematic examples
 - including pp-waves non-strongly causal (nor distinguishing)!
 - ...neither the conformal nor the c-boundary make sense!

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EK conjecture: physical statement

Ehlers and Kundt '62: summary on gravitational waves.

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After proving that plane waves are (geodesically) complete they posed *EK conjecture*:

Prove the plane waves to be the only complete [gravitational] **pp-waves**, no matter which topology one chooses.

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Under their viewpoint:

- Complete and Ricci flat pp-waves would represent a graviton field independent of any matter by which it would be generated
- Such gravitons (allegedly plane waves), would correspond to source-free photons in electrodynamics.

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EK conjecture: the loose end

Recall:

- Source-free photons, represented by monocromatic sine waves, constitute an idealization (very useful: the basis of the Fourier analysis of homogeneous electromagnetic waves).
- EK conjecture assigns a similar role to gravitational plane waves.

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- EK conjecture assigns a similar role to gravitational plane waves.
- In connection with the commented ideas, EK conjecture:
 - 1 assigns the idealized role suggested by Penrose
 - 2 circumvents the initial/mixed value problem for plane waves
 - 3 for pp-waves, problem transferred to incompleteness ~> something is missed in the modelling (so, add a source!)

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Precise mathematical problem

$\begin{array}{c} \text{Ricci-flat} \\ (\Delta_z H = 0) \\ + \\ \text{Complete} \end{array} \end{array} \right\} \text{ pp-wave (any H)} \Longrightarrow \text{ plane wave (quad. polyn. } x, y)$

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Reformulation in Lagrangian (Newtonian) Mechanics

Theorem

Put V = -H. A pp-wave is complete \Leftrightarrow all the trajectories of

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 (1)

are complete.

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Conjecture (Alternative EK Lagrangian conjecture)

Let V(z, u) non-autonomous potential on \mathbb{R}^2 , harmonic in z. The dynamical system (1) is complete \iff V(z, u) is a (at most) quadratic polynomial in z, $\forall u \in \mathbb{R}$.

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Nomenclature for known results

• *H* polynomially bounded at finite *u*-times or just polynomially *u*-bounded:

 $\forall u_0 \in \mathbb{R}, \exists \epsilon_0 > 0 \text{ and polynomial } q_0$:

 $H(z,u) \leq q_0(z)$ $\forall (z,u) \in \mathbb{R}^2 \times (u_0 - \epsilon_0, u_0 + \epsilon_0)$

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• *H* quadratically polynomially *u*-bounded: q_0 degree $\leq 2 \forall u_0 \in \mathbb{R}$.

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Known results

(a) **Ehlers-Kundt'62:** All plane waves (gravitational or not) are complete (ODE system with enough symmetries)

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- (b) Flores-S. '06+ Candela-Romero-S. '13: all pp-waves whenever H = -V is quadratically polynomially u-bounded (use Lagrangian viewpoint). As a consequence, EK conjecture true in this case

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- (c) Leistner-Schliebner'16: focus on the vague assertion
 "No matter which topology one chooses".
 It can be extended rigorously (by taking a locally pp-wave metric on a compact manifold) and:
 the problem becomes equivalent to the standard one on R⁴.
 - (+ further extensions by **Costa-Flores-Herrera'16**)

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Our goal: proof of polynomial EK conjecture

Theorem (Flores-S., arxiv 1706.03855)

EK conjecture is true when H(z, u) is polynomially u-bounded.

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Discussion

1 Necessity of the polynomial bound:

- z-harmonicity ⇒ z-analiticity ⇒ z-polynomial series
 → but the technique crashes for infinite series.
- Physically: EK conj holds at any finite perturbative order

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2 Significative (even in the autonomous case $V(z, u) \equiv V(z)$)

- z-harmonicity: new type of hypothesis for incompleteness
- Links with the theory of polynomial holomorphic vector on C² (result natural but unknown there) and other fields

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- Open case of physical and mathematical interest:
 Relativity + Classical Mechanics + Dynamical systems

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- Links with the theory of polynomial holomorphic vector on C² (result natural but unknown there) and other fields
- Open case of physical and mathematical interest:
 Relativity + Classical Mechanics + Dynamical systems
- Natural smoothness in the non-autonomous case: C¹ (existence of geodesics)
 - ~ Analiticity will not be used in our techniques.

Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

Preliminaries on V = -H

■ Focus on the Lagrangian problem in Classical Mechanics: use V(z, u) ("potential energy") rather than -H(z, u)

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Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

Preliminaries on V = -H

- Focus on the Lagrangian problem in Classical Mechanics: use V(z, u) ("potential energy") rather than -H(z, u)
- Classically u is the "external time" (but u is not a time function in the relativistic sense for the pp-wave)

Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

Which approach should be used?

Autonomous case: complex variable for V = -H?

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Theorem (Rellich'40)

If h = h(z) is an entire function that is not a polynomial of degree at most 1, then every entire solution of the complex analytic differential equation z'' = -h(z) is constant.

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1 Given V, complexify to an entire V_C and solve $z'' = -V'_C$

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Given V, complexify to an entire V_C and solve $z'' = -V'_C$ $\rightsquigarrow h_1(z) = \partial_x V - i \partial_y V$ introduces a wrong sign

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Given V, complexify to an entire V_C and solve z" = −V'_C → h₁(z) = ∂_xV − i∂_yV introduces a wrong sign
 Choose h₂(z) = ∂_xV + i∂_yV → anti-holomorphic

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If h = h(z) is an entire function that is not a polynomial of degree at most 1, then every entire solution of the complex analytic differential equation z'' = -h(z) is constant.

 Given V, complexify to an entire V_C and solve z" = -V'_C → h₁(z) = ∂_xV - i∂_yV introduces a wrong sign

 Choose h₂(z) = ∂_xV + i∂_yV → anti-holomorphic

 Choose h₃(z) = ∂_yV + i∂_xV holomorphic
 → but x, y are switched in the equation

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Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

Which approach should be used?

Autonomous case: complex variable for V = -H?

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 ... choose h₄(z) = ih₃ holomorphic and un-switch the coordinates → but this is again h₁

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Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

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 ... choose h₄(z) = ih₃ holomorphic and un-switch the coordinates → but this is again h₁

Incompatibility, complex variable does not seem to work!

Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

Explicit form of V = -H

Result 1: expression of V in polar coordinates

• Autonomous case: z-harmonic + polynomially u-bounded \implies

$$V(\rho,\theta) = -\lambda \rho^n \cos n(\theta + \alpha) - \sum_{m=0}^{n-1} \lambda_m \rho^m \cos m(\theta + \alpha_m),$$
(2)

 $\lambda > 0$ and $\lambda_m, \alpha, \alpha_m$ constants.

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Tool: harmonic polynomials on $\mathbb{C} = \mathbb{R}^2$

- **1** *V* harmonic \Leftrightarrow real part of an entire function V_C
- **2** V (upper) bounded by a polynomial \Leftrightarrow V polynomial
- 3 *V* harmonic polynomial of degree $n \Leftrightarrow$ terms of degree $m (\in \{1, ..., n\})$ harmonic p_m
- 4 Homogeneous harmonic polynomials degree m > 0: 2-dim $p_m(\rho, \theta) = A_m \rho^m \cos(m\theta) + B_m \rho^m \sin(m\theta)$ $= \lambda_m \rho^m \cos m(\theta + \alpha_m)$
- 5 Thus, V harmonic polynomial p of degree n > 0: $p = \sum_{m=0}^{n} p_m$

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u-dependence

Non autonomous case: expected explicit form

$$V(\rho, \theta, u) = -\lambda(u)\rho^{n} \cos n(\theta + \alpha(u)) -\sum_{m=0}^{n-1} \lambda_{m}(u)\rho^{m} \cos m(\theta + \alpha_{m}(u)),$$
(3)

 $\lambda(u) > 0$, C^1 -smooth $\lambda(u), \lambda_m(u), \alpha(u), \alpha_m(u)$.

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Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

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(3)

 $\lambda(u) > 0$, C^1 -smooth $\lambda(u), \lambda_m(u), \alpha(u), \alpha_m(u)$.

...but only in some (dense) intervals $I = (u_0 - \epsilon_0, u_0 + \epsilon_0)$

$$V(z,u) = \begin{cases} e^{-1/u^2} \rho^n \cos(n\theta + 1/u) & u \neq 0\\ 0 & u = 0 \end{cases}$$

 \rightsquigarrow non-continuous lpha(u)=1/u

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Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

EK conjecture vs Lagrangian EK conjecture

Theorem

Put V = -H. A pp-wave is complete \Leftrightarrow all the trajectories of

$$\ddot{z}(s) = -\nabla_z V(z(s), s) \tag{4}$$

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are complete.

Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

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Proof. Geodesic eqn (z(s), u(s), v(s)): $u(s) = \dot{u}(0)s + u(0)$
Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

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Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

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 $\ddot{z}(s) = -\lambda^2
abla_z V(z(s), u(s))$ with $\lambda^2 = \dot{u}(0)^2/2 \ge 0$

Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

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Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

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Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

Criterion for completeness: upper quadratic bound of -V

Proposition

(-V) quadratically polynomially u-bounded, that is,

 $-V(z,u) \leq a(u)|z|^2 + b(u)$

\Rightarrow complete trajectories

Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

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Rough idea. Autonomous case: constant energy $E = \frac{1}{2}\dot{z}^2(s) + V(z(s))$

Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

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Rough idea. Autonomous case: constant energy $E = \frac{1}{2}\dot{z}^2(s) + V(z(s)) \Rightarrow |\dot{z}(s)| \leq |z(s)| \Rightarrow \text{length}(z|_{[0,s]}) \leq e^{C|s|}$ \Rightarrow in a finite time, z(s) covers a finite length (Lagrangian viewpoint) \rightsquigarrow completeness (Non-autonomous bound too \rightsquigarrow restrict to compact $[u_0, u_1]$) \Box

Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

Criterion for incompleteness: lower radial quadratic bound

 \rightsquigarrow For EK, focus on $n \ge 3$ and incompleteness

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Criterion for incompleteness: lower radial quadratic bound

→ For EK, focus on $n \ge 3$ and incompleteness Trajectory in polar coordinates, $(\rho(s), \theta(s))$

Lemma (Criterion incompleteness of ρ)

For n > 2, assume:

 $\ddot{
ho}(s)\geq n\lambda_0
ho^{n-1}(s), \qquad \qquad
ho(0)>0, \qquad \dot{
ho}(0)\geq 0.$

 $\lambda_0 > 0 \Rightarrow$ all the solutions are incomplete (to the right)

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Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

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Idea of the proof. After some manipulations

$$\int_{
ho(0)}^{
ho}rac{dar
ho}{\sqrt{2\lambda_0(ar
ho^n-
ho(0)^n)+\dot
ho(0)^2}}\geq s(
ho)$$

and the integral is finite for $\rho = \infty$. \Box

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Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

Precise result

For $n \ge 3$, autonomous case, assuming with no loss of generality:

$$V(\rho, \theta) = -\frac{\lambda \rho^n \cos n\theta}{-\sum_{m=0}^{n-1} \lambda_m \rho^m \cos m(\theta + \alpha_m)},$$

Proposition

For any $0 < \theta_0 < \theta_+ < \pi/(2n) \exists \rho_0 > 0$: any trajectory γ with

 $\gamma(\mathbf{0}) = (\rho(\mathbf{0}), \theta(\mathbf{0})) \in D[\rho_0, \theta_0] := \{(\rho, \theta) : \rho > \rho_0, |\theta| < \theta_0\}$

and $\dot{\rho}(0) \ge 0, \dot{\theta}(0) = 0$, satisfies: (a) γ remains in $D[\rho_0, \theta_+]$ (b) whenever in this region, $\ddot{\rho}(s) \ge \lambda_0 n \rho^{n-1}(s)$,

Thus, γ is incomplete

Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

The role of harmonicity

• If $V(\rho, \theta) = -\lambda \rho^n \cos n\theta$ (only leading term):

incomplete trajectory γ_0 reparametrizing positive x-axis.

In general: γ₀ is not a trajectory but a direction of maximum asymptotic decreasing

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Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

The role of harmonicity

- If V(ρ, θ) = −λρⁿ cos nθ (only leading term): incomplete trajectory γ₀ reparametrizing positive x-axis.
- In general: γ₀ is not a trajectory but a direction of maximum asymptotic decreasing
- Region D[ρ₀, θ₀]: by harmonicity each point of γ₀ is a strict minimum of V under θ-variations → oscillations
 → confinement in D[ρ₀, θ₊] (where V decreases enough fast)



Controlling harmonic potentials Completeness of dynamical systems Heuristic idea of the proof

Summing up: claims

In general:

- No hope to find an (incomplete) radial trajectory
- ... but a radial direction γ_0 so that V decreases fast on γ_0 and:
 - **1** Trajectories $(\rho(s), \theta(s))$ starting at some $D[\rho_0, \theta_0]$ will have bounded angular oscillations around γ_0
 - 2 ...so that they remain in some bigger $D[\rho_0, \theta_+]$, $\theta_0 < \theta_+ < \pi/(2n)$
 - 3 and $\rho(s)$ satisfies the differential inequality ensuring incompleteness on $D[\rho_0, \theta_+]$

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Steps and aim Bounds on V and balance of energies Bounds on V and balance of energies

Preliminary step: steepest V-decreasing direction

 Identify a radial direction \(\gamma_0\) with steepest decreasing \(V\) (provided by the leading mononomial of \(V\))

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Potential and its gradient

Identification of θ_k for radial γ_k :

$$V(\rho,\theta) = -\rho^n \cos(n\theta) - \sum_{m=1}^{n-1} \lambda_m \rho^m \cos m(\theta + \alpha_m),$$

(up to a rotation and homothety), thus

$$-\nabla V = \left(n\rho^{n-1}\cos(n\theta) + \sum_{m=1}^{n-1}m\lambda_m\rho^{m-1}\cos m(\theta + \alpha_m)\right)\partial_\rho \\ - \left(n\rho^{n-2}\sin(n\theta) + \sum_{m=1}^{n-1}m\lambda_m\rho^{m-2}\sin m(\theta + \alpha_m)\right)\partial_\theta$$

 $\partial_{\theta} V$ vanish for big ρ at *n* angles $\vartheta_k(\rho) \in [0, 2\pi)$:

$$\lim_{\rho\to\infty}\vartheta_k(\rho)=\hat{\theta}_k:=2\pi k/n, \qquad k=0,\ldots,n-1.$$

 $(\hat{ heta}_k := (2\pi k - lpha(u))/n$ in the non-autonomous case).

Steps and aim

Bounds on *V* and balance of energies Bounds on *V* and balance of energies

Aim

Focus on the angle $\hat{\theta}_0 = 0$, choose $0 < \theta_0 < \theta_+ < \pi/(2n)$:

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Steps and aim Bounds on V and balance of energy Bounds on V and balance of energy

Focus on the angle $\hat{\theta}_0 = 0$, choose $0 < \theta_0 < \theta_+ < \pi/(2n)$:

Proposition

V harmonic polynomial of degree $n \ge 3$ $\exists \rho_0 > 0$: any V-trajectory γ with

 $\gamma(0) = (\rho(0), \theta(0)) \in D[\rho_0, \theta_0] \qquad \dot{\rho}(0) \ge 0, \ \dot{\theta}(0) = 0,$ (5)

remains in $D[\rho_0, \theta_+]$ and is incomplete.

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Step 0: for big ρ₀ > 0 study the region D[ρ₀, θ₊] to find suitable technical bounds for V, ∂V/∂ρ (necessary for confinement and incompleteness)

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Steps and aim Bounds on V and balance of energi Bounds on V and balance of energi

Steps

For suitably prescribed ρ_0 , and any trajectory γ ($\gamma(0) \in D[\rho_0, \theta_0] \subset D[\rho_0, \theta_+]$) as in Prop.:

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Steps and aim Bounds on V and balance of energies Bounds on V and balance of energies

Steps

For suitably prescribed ρ_0 , and any trajectory γ ($\gamma(0) \in D[\rho_0, \theta_0] \subset D[\rho_0, \theta_+]$) as in Prop.:

 Bound the growth of |θ(s)|-peaks in terms of ρ(s). (the biggest starting point ρ(s₀), the smallest growth)
 Tool: careful balance of the energies of the trajectories in comparison with their projections in radial directions.

Steps and aim Bounds on V and balance of energies Bounds on V and balance of energies

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 Tool: careful balance of the energies of the trajectories in comparison with their projections in radial directions.
- Check that, from peak to peak, ρ increases very fast, so that the increasing of the amplitudes of the oscillations will not allow γ to escape from D[ρ₀, θ₊].
 Tool: introduce a notion of angular length θ and derive a formula showing that along each possible oscillation, ρ grows

exponentially with $\bar{\theta}$

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Steps and aim Bounds on V and balance of energies Bounds on V and balance of energies

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 Tool: careful balance of the energies of the trajectories in comparison with their projections in radial directions.
- 2 Check that, from peak to peak, ρ increases very fast, so that the increasing of the amplitudes of the oscillations will not allow γ to escape from $D[\rho_0, \theta_+]$.

Tool: introduce a notion of angular length $\bar{\theta}$ and derive a formula showing that along each possible oscillation, ρ grows **exponentially** with $\bar{\theta}$

 $\rightsquigarrow \rho$ will arrive ∞ (in finite time) before an oscillation moving γ outside $D[\rho_0, \theta_+]$ can occur.

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Step 0: technical bounds for V from its harmonicity

Proposition

(Incompleteness) $\forall \theta_+ \in (0, \pi/(2n)) \ \delta_0 \in (0, \cos(n\theta_+)), \exists \rho_0 > 1:$ $-\partial_{\rho}V(\rho,\theta) > \delta_0 n \rho^{n-1} \ (>0), \forall \rho \ge \rho_0, \forall \theta \in (-\theta_+,\theta_+).$ (Confinement) Chosen $0 < \epsilon < \theta_{-} < \theta_{+}, \exists \rho_0 > 1, \delta > 0$ s. t. $\forall \theta_1 \in [\theta_-, \theta_+], \ \forall \rho > \rho_0$ $V(\rho, \theta_1) - V(\rho, \theta) > \delta(\theta_1 - \theta)\rho^n, \forall \theta \in (-\theta_1 + \epsilon, \theta_1),$ $V(\rho, -\theta_1) - V(\rho, \theta) > \delta(\theta_1 + \theta)\rho^n, \forall \theta \in (-\theta_1, \theta_1 - \epsilon),$ $\partial_{\theta} V(\rho, \theta_1) - \partial_{\theta} V(\rho, \theta) > \delta n(\theta_1 - \theta) \rho^{n-1}, \forall \theta \in (-\theta_1 + \epsilon, \theta_1),$ $\partial_{\theta} V(\rho, -\theta_1) - \partial_{\theta} V(\rho, \theta) > \delta n(\theta_1 + \theta) \rho^{n-1}, \forall \theta \in (-\theta_1, \theta_1 - \epsilon).$ Moreover, chosen $0 < \theta_{-} < \theta_{+} < \pi/(2n)$, one can find A > 0, $\rho_0 > 1$ such that all the previous inequalities hold for $\rho \geq \rho_0$, by replacing ϵ and δ by A/ρ and $1/\rho$, resp.,

 $\epsilon > 0 \rightarrow$ lower order asymmetry of $V \epsilon \rho \sim A > 0$; $\theta_1 \rightarrow$ use to bound the amplitude of oscillation $P \in \mathbb{P} \setminus \mathbb{P} \setminus \mathbb{P} \setminus \mathbb{P}$ M. Sánchez Ehlers-Kundt conjecture

Steps and aim Bounds on V and balance of energies Bounds on V and balance of energies

Step 1: Radial projection

- Trajectory $\gamma(s) \equiv (\rho(s), \theta(s)), s \in [0, b)$: and $\theta_1 \in \mathbb{R}$: θ_1 -projection: $\gamma_{\theta_1}(s) \equiv (\rho(s), \theta_1)$
- Energy $\gamma_{\theta_1}(s)$ = radial kinetic $\gamma(s)$ + potential $V(\rho(s), \theta_1)$
- In particular, choosing $s_1 \in [0, b)$, energy $\theta(s_1)$ -projection: Energy[$\theta(s_1)$ -proj]: $F(s) = \frac{1}{2}\dot{\rho}(s)^2 + V(\rho(s), \theta(s_1))$

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Step 1: bounding angular peaks by the radial distance

First estimate of the (angular) peaks.

Key: whenever $\theta(s)$ is monotonous, the energy F cannot decrease.

Proposition

Choose $0 < \theta_- < \theta_+ < \pi/(2n)$ and let $A, \rho_0 > 0$ as above. Let $(\rho(s), \theta(s))$, trajectory with $(\rho(s_0), \theta(s_0)) \in D[\rho_0, \theta_+], \dot{\theta}(s_0) = 0$ and $\dot{\rho}(s_0) \ge 0$ for some $s_0 \in [0, b)$. If $s_1 \in (s_0, b)$ satisfies $|\theta(s_0)| < |\theta(s_1)| < \theta_+$, and $\theta(s)$ is (non-necessarily strictly) monotonous on (s_0, s_1) , then $|\theta(s_1)| - |\theta(s_0)| \le A/\rho(s_0)$.

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Step 2: Angular length

Such an inequality is not enough to confine γ in D[ρ, θ₊]: we must assure that the radial coordinate grows enough fast in each oscillation.

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Step 2: Angular length

Such an inequality is not enough to confine γ in D[ρ, θ₊]: we must assure that the radial coordinate grows enough fast in each oscillation.

Angular length:

$$\overline{\theta}(s) := \int_{s_0}^s |\dot{\theta}(\sigma)| d\sigma, \quad s \in [s_0, b)$$
(6)

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Step 2: Bound of the angular length

Lemma

For some ρ_0 big enough, any solution $\gamma : [s_0, b) \to \mathbb{R}^2$ starting at $D[\rho_0, \theta_+]$ with $\dot{\rho}(s_0) > 0$, $\dot{\theta}(s_0) = 0$ satisfies (for $\Lambda := 8/\cos(n\theta_+) > 1$):

 $ho(s) >
ho(s_0) e^{\overline{ heta}(s)/\Lambda}$

for all $s \in (s_0, b)$ such that $\gamma([s_0, s]) \subset D[\rho_0, \theta_+]$.

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Steps and aim Bounds on V and balance of energies Bounds on V and balance of energies

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 $ho(s) >
ho(s_0) e^{\overline{ heta}(s)/\Lambda}$

for all $s \in (s_0, b)$ such that $\gamma([s_0, s]) \subset D[\rho_0, \theta_+]$.

Discussing the possible cases (none/finite/infinite oscillations), this bound combined with the previous one, implies the confinement in $D[\rho_0, \theta_+] \square$

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Conclusion

Achievements:

- Clarify physical and mathematical grounds of EK conjecture
- Solve the significative polynomial case

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Conclusion

Achievements:

- Clarify physical and mathematical grounds of EK conjecture
- Solve the significative polynomial case

Interest:

- **1 Relativity**: foundational basis of gravitational waves.
- Classical Mechanics: the forces under consideration (coming from a divergence free gradient potential) are the most standard ones in Mechanics!!
- **3 Dynamical Systems**: proof completely original, no standard tool on stability and attractors seem to be appliable
- Complex variable (theory of holomorphic vector fields): also in this framework, only the polynomial case has been fully developed

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Conclusion

Obvious open lines of research:

- Non-polynomial case
- Beyond the original motivation: higher dimensions, impulsive waves, Finslerian modifications of the waves...

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Conclusion

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- Non-polynomial case
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What is more EK conjecture introduces the pattern

Source-free dynamics $\implies \begin{cases} \text{Natural (mathematical) vacuum, or} \\ \text{Incompleteness (eventually missed source),} \end{cases}$

which may serve as a paradigm for other parts of Physics, as well as for its mathematical modelling.

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Thank you for your attention

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